

LAMPIRAN 1

- **DATA WAKTU PROSES DAN
DATA WAKTU HANDLING**

Waktu Proses Untuk Forging

Brake Shoe

Data Ke-	Waktu (detik)
1	5.88
2	4.88
3	4.42
4	5.47
5	4.5
6	4.64
7	6.5
8	4.9
9	5.04
10	7.55
11	4.35
12	4.64
13	6.74
14	5.02
15	4.58
16	6.57
17	6.3
18	7.67
19	7.24
20	4.05
21	5.52
22	7.08
23	4.91
24	7.11
25	6.46
26	5.17
27	7.1
28	7.13
29	7.3
30	7.06

Waktu Proses Untuk Bending Arm

XC

Data Ke-	Waktu (detik)
1	25.26
2	24.62
3	23.84
4	23.93
5	25.83
6	23.22
7	19.79
8	23.56
9	21.44
10	22.79
11	21.68
12	24.66
13	22.21
14	26.14
15	22.32
16	23.17
17	25.59
18	21.88
19	26.34
20	23.29
21	23.58
22	24.7
23	21.46
24	21.2
25	23.54
26	25.92
27	24.81
28	24.71
29	22.42
30	21.64

Waktu Proses Untuk Piercing Arm**XC**

Data Ke-	Waktu (detik)
1	24.92
2	25.93
3	26.44
4	24.22
5	25.2
6	25.28
7	24.49
8	24.48
9	26.21
10	22.91
11	25.54
12	24.66
13	25.97
14	23.65
15	24.69
16	24.32
17	25.7
18	25.32
19	22.76
20	25.09
21	26.66
22	27.45
23	24.22
24	25.8
25	23.41
26	25.32
27	24.5
28	25.11
29	22.76
30	23.12

Waktu Proses Untuk Cutting Arm**XC**

Data Ke-	Waktu (detik)
1	13.38
2	15.68
3	13.69
4	10.98
5	17.59
6	13.88
7	14.05
8	11.58
9	13.75
10	10.79
11	9.74
12	12.79
13	11.99
14	14.19
15	10.07
16	8.04
17	12.31
18	10.97
19	15.52
20	12.31
21	7.86
22	12.98
23	14.63
24	12.81
25	15.23
26	10.08
27	6.29
28	13.64
29	10.18
30	9.42

Waktu Proses Untuk Assembly 1

XC

Data Ke-	Waktu (detik)
1	66.89
2	67.89
3	65.83
4	66.18
5	73.86
6	73.46
7	65.33
8	72.66
9	65.86
10	66.44
11	64.25
12	64.16
13	70.5
14	72.52
15	71.71
16	66.06
17	79.7
18	76.31
19	81.08
20	72.84
21	66.68
22	67.02
23	73.17
24	76.63
25	73.15
26	74.15
27	73.23
28	67.16
29	76.52
30	79.11

Waktu Proses Untuk Assembly 2

XC

Data Ke-	Waktu (detik)
1	36.23
2	35.11
3	33.28
4	45.19
5	39.29
6	39.88
7	37.52
8	41.71
9	38.21
10	33.65
11	39.47
12	39.89
13	37.81
14	42.97
15	35.19
16	33.99
17	34.31
18	32.87
19	36.34
20	37.02
21	39.96
22	34.52
23	37.52
24	32.24
25	33.48
26	39.06
27	42.6
28	33.02
29	36.33
30	34.02

Waktu Proses Untuk Blank Rod**XC**

Data Ke-	Waktu (detik)
1	3.82
2	4.77
3	2.56
4	4.53
5	3.97
6	2.99
7	4.94
8	3.17
9	3.6
10	4.76
11	3.22
12	5.97
13	2.94
14	2.07
15	4.24
16	2.3
17	3.47
18	4.04
19	2.16
20	5.94
21	2.66
22	3.64
23	4.92
24	2.07
25	3.26
26	5.84
27	2.71
28	3.67
29	4.7
30	3.69

Waktu Proses Untuk Piercing Rod**XC**

Data Ke-	Waktu (detik)
1	18.18
2	13.69
3	15.24
4	12.88
5	14.57
6	15.57
7	13.56
8	17.74
9	16.57
10	15.38
11	20.05
12	17.42
13	14.56
14	16.41
15	13.85
16	14.81
17	15.64
18	17.32
19	16.44
20	15.38
21	14.78
22	19.22
23	15.6
24	16.25
25	12.96
26	15.71
27	14.94
28	15.96
29	12.69
30	17.12

Waktu Proses Untuk Bending 1

Arm H10

Data Ke-	Waktu (detik)
1	17.8
2	21.11
3	19.14
4	17.52
5	20.22
6	19.83
7	20.62
8	19.73
9	18.81
10	20.04
11	19.14
12	18.44
13	21.04
14	17.61
15	19.43
16	18.07
17	16.91
18	18.55
19	19.42
20	17.03
21	18.85
22	17.63
23	17.31
24	19.5
25	20.04
26	18.65
27	17.67
28	18.6
29	18.27
30	16.84

Waktu Proses Untuk Bending 2

Arm H10

Data Ke-	Waktu (detik)
1	11.01
2	10.9
3	10.21
4	16.41
5	8.66
6	11.32
7	16.16
8	12.65
9	15.78
10	14.53
11	16.7
12	15.66
13	6.86
14	7.12
15	13.25
16	14.88
17	10.35
18	11.92
19	13.51
20	14.04
21	15.21
22	10.76
23	15.7
24	10.67
25	12.31
26	8.16
27	15.85
28	9.6
29	12.93
30	14.9

Waktu Proses Untuk Piercing Arm**H10**

Data Ke-	Waktu (detik)
1	24.69
2	23.31
3	25.86
4	23.64
5	26.6
6	27.14
7	22.61
8	24.36
9	23.34
10	23.42
11	24.08
12	24.19
13	24.86
14	25.38
15	23.25
16	23.42
17	23.53
18	27.51
19	23.5
20	25.41
21	24.72
22	23.31
23	24.17
24	23.06
25	23.7
26	25.21
27	22.54
28	24.96
29	24.39
30	24.9

Waktu Proses Untuk Cutting Arm**H10**

Data Ke-	Waktu (detik)
1	9.51
2	14.94
3	11.84
4	12.44
5	10.34
6	11.63
7	10.74
8	12.62
9	13.81
10	10.31
11	14.05
12	8.14
13	15.33
14	11.18
15	14.95
16	12.35
17	9.12
18	11.92
19	13.3
20	11.41
21	9.72
22	10.4
23	15.54
24	8.08
25	11.31
26	16.13
27	10.44
28	13.66
29	14.93
30	8.74

Waktu Proses Untuk Assembly 1

H10

Data Ke-	Waktu (detik)
1	105.02
2	101.34
3	97.25
4	101.72
5	104.95
6	98.35
7	102.8
8	106.13
9	105.93
10	102.51
11	99.59
12	101.68
13	97.37
14	100.25
15	104.12
16	101.46
17	97.67
18	99.13
19	102.38
20	98.44
21	102.18
22	99.24
23	98.18
24	100.49
25	102.42
26	98.91
27	100.68
28	99.64
29	104.47
30	102.94

Waktu Proses Untuk Assembly 2

H10

Data Ke-	Waktu (detik)
1	34.81
2	31.08
3	32.09
4	29.54
5	34.74
6	31.19
7	32.56
8	34.19
9	31.99
10	32.46
11	31.95
12	33.9
13	32.64
14	30.96
15	31.87
16	34.14
17	32.06
18	29.42
19	37.11
20	34.37
21	34.61
22	33.79
23	31.9
24	31.46
25	33.22
26	27.81
27	31.66
28	31.21
29	33.91
30	29.41

Waktu Proses Untuk Blank Rod

H10

Data Ke-	Waktu (detik)
1	4.66
2	5.42
3	4.97
4	4.85
5	5.24
6	5.98
7	6.75
8	5.14
9	4.84
10	5.65
11	5.95
12	5.46
13	4.95
14	4.25
15	4.38
16	3.15
17	5.75
18	4.94
19	5.15
20	5.64
21	5.83
22	6.54
23	4.23
24	5.17
25	4.9
26	4.11
27	3.21
28	5.49
29	5.22
30	6.91

Waktu Proses Untuk Piercing Rod

H10

Data Ke-	Waktu (detik)
1	16.74
2	16.16
3	15.94
4	16.74
5	10.19
6	11.76
7	16.35
8	15.91
9	13.24
10	12.64
11	11.62
12	9.27
13	14.35
14	11.2
15	16.94
16	12.41
17	14.84
18	9.08
19	13.12
20	16.82
21	13.63
22	15.45
23	11.16
24	14.99
25	13.18
26	9.75
27	14.42
28	12.64
29	14.5
30	13.84

Waktu Proses Untuk Bending Rod

H10

Data Ke-	Waktu (detik)
1	16.66
2	14.48
3	16.7
4	14.55
5	14.35
6	16.12
7	13.37
8	16.79
9	16.88
10	13.14
11	13.81
12	15.37
13	15.78
14	14.53
15	12.9
16	14.89
17	14.2
18	11.41
19	11.55
20	12.14
21	13.28
22	15.72
23	14.44
24	11.91
25	12.47
26	13.46
27	11.08
28	16.08
29	13.06
30	15.24

Waktu Proses Untuk Bending 1

Arm H00

Data Ke-	Waktu (detik)
1	17.8
2	21.11
3	19.14
4	17.52
5	20.22
6	19.83
7	20.62
8	19.73
9	18.81
10	20.04
11	19.14
12	18.44
13	21.04
14	17.61
15	19.43
16	18.07
17	16.91
18	18.55
19	19.42
20	17.03
21	18.85
22	17.63
23	17.31
24	19.5
25	20.04
26	18.65
27	17.67
28	18.6
29	18.27
30	16.84

Waktu Proses Untuk Bending 2**Arm H00**

Data Ke-	Waktu (detik)
1	12.82
2	14.14
3	16.76
4	15.14
5	14.48
6	16.14
7	12.43
8	11.95
9	16.03
10	15.77
11	13.53
12	15.65
13	16.12
14	11.12
15	10.33
16	15.81
17	15.99
18	14.44
19	16.29
20	17.26
21	16.12
22	16.77
23	15.33
24	11.5
25	16.94
26	15.42
27	16.03
28	16.2
29	13.32
30	15.42

Waktu Proses Untuk Piercing Arm**H00**

Data Ke-	Waktu (detik)
1	28.33
2	27.69
3	25.31
4	30.36
5	27.26
6	25.66
7	28.88
8	29.56
9	26.32
10	28.08
11	26.19
12	25.35
13	22.1
14	24.96
15	26.5
16	25.62
17	27.56
18	25.72
19	27.16
20	24.92
21	22.02
22	26.42
23	28.12
24	27.18
25	22.92
26	27.52
27	25.26
28	24.32
29	23.63
30	27.38

Waktu Proses Untuk Cutting Arm

H00

Data Ke-	Waktu (detik)
1	15.01
2	15.09
3	15.2
4	14.14
5	14.23
6	14.96
7	16.61
8	14.26
9	13.78
10	13.42
11	13.08
12	14.19
13	14.86
14	15.38
15	13.25
16	14.23
17	13.53
18	14.92
19	13.5
20	15.14
21	14.72
22	13.13
23	14.7
24	13.67
25	13.7
26	13.16
27	15.11
28	14.96
29	14.39
30	14.9

Waktu Proses Untuk Assembly 1

H00

Data Ke-	Waktu (detik)
1	104.48
2	105.06
3	99.04
4	106.47
5	116.64
6	109.91
7	113.92
8	105.31
9	111.58
10	115.28
11	116.13
12	108.73
13	109.58
14	110.41
15	114.21
16	107.85
17	113.88
18	116.92
19	105.46
20	113.9
21	109.25
22	112.44
23	102.23
24	104.55
25	110.04
26	107.33
27	104.59
28	100.92
29	112.15
30	103.07

Waktu Proses Untuk Assembly 2

H00

Data Ke-	Waktu (detik)
1	39.89
2	33.44
3	42.04
4	38.66
5	29.27
6	38.92
7	40.71
8	35.46
9	38.74
10	35.11
11	34.19
12	32.94
13	39.62
14	36.86
15	40.71
16	32.44
17	40.62
18	29.91
19	31.14
20	33.47
21	35.64
22	39.73
23	30.19
24	34.5
25	33.61
26	34.48
27	38.66
28	42.23
29	35.37
30	34.41

Waktu Proses Untuk Blank Rod

H00

Data Ke-	Waktu (detik)
1	5.12
2	4.26
3	4.1
4	3.98
5	6.01
6	5.64
7	4.17
8	5.25
9	4.79
10	6.64
11	3.46
12	4.68
13	4.61
14	3.91
15	4.04
16	5.61
17	7.11
18	4.24
19	4.18
20	5.24
21	4.74
22	6.23
23	5.45
24	4.24
25	3.71
26	4.26
27	5.42
28	4.61
29	5.21
30	5.45

Waktu Proses Untuk Piercing Rod

H00

Data Ke-	Waktu (detik)
1	13.02
2	12.03
3	15.82
4	11.14
5	14.19
6	9.56
7	13.93
8	15.2
9	14.26
10	13.94
11	14.55
12	16.27
13	13.35
14	14.28
15	16.44
16	13.94
17	17.51
18	13.68
19	12.25
20	14.63
21	13.26
22	14.64
23	16.17
24	14.79
25	15.36
26	13.35
27	12.27
28	13.76
29	15.78
30	14.14

Waktu Proses Untuk Bending Rod

H00

Data Ke-	Waktu (detik)
1	17.56
2	15.84
3	17.6
4	15.44
5	13.54
6	16.21
7	17.33
8	17.69
9	16.88
10	14.13
11	18.13
12	17.35
13	17.85
14	15.34
15	13.9
16	14.58
17	15.28
18	11.64
19	14.44
20	14.57
21	15.28
22	13.81
23	14.14
24	16.11
25	14.72
26	14.34
27	13.97
28	14.15
29	11.67
30	12.35

Waktu Proses Untuk Mesin**Expand**

Data Ke-	Waktu (detik)
1	11.27
2	13.06
3	14.39
4	12.52
5	10.56
6	10.96
7	9.93
8	11.16
9	10.07
10	9.89
11	11.2
12	13.77
13	15.53
14	12.92
15	10.39
16	12.56
17	11.77
18	9.54
19	13.8
20	12.02
21	10.37
22	12.78
23	12.53
24	14.35
25	11.48
26	12.75
27	10.02
28	15.91
29	11.84
30	12.4

Waktu *Handling* Receiving ke**Forging**

Data Ke-	Waktu (detik)
1	3.13
2	2.73
3	2.57
4	3.18
5	3.22
6	3.28
7	2.19
8	3.12
9	3.5
10	2.35
11	2.94
12	2.13
13	2.91
14	2.74
15	3.67
16	2.94
17	2.35
18	3.55
19	2.22
20	4.02
21	2.12
22	2.25
23	2.86
24	3.28
25	1.46
26	2.54
27	2.88
28	3.19
29	1.96
30	2.17

Waktu *Handling* Forging ke WIP

Data Ke-	Waktu (detik)
1	15.11
2	13.88
3	14.58
4	15.11
5	15.26
6	14.92
7	17.02
8	14.09
9	15.38
10	16.44
11	18.85
12	17.31
13	16.84
14	17.55
15	14.35
16	11.24
17	15.11
18	17.14
19	15.05
20	14.86
21	16.28
22	14.54
23	16.92
24	15.17
25	16.84
26	16.12
27	17.15
28	16.04
29	16.33
30	13.81

Waktu *Handling* Receiving ke**Bending (Arm XC)**

Data Ke-	Waktu (detik)
1	3.74
2	2.73
3	2.98
4	2.57
5	1.94
6	2.84
7	2.94
8	3.6
9	3.99
10	2.96
11	3.06
12	4.77
13	3.12
14	2.75
15	2.16
16	2.73
17	3
18	2.52
19	3.21
20	4.17
21	3.99
22	3.34
23	4.06
24	2.24
25	2.49
26	3.3
27	1.97
28	3.28
29	2.15
30	2.64

Waktu *Handling* Bending ke**Piercing (Arm XC)**

Data Ke-	Waktu (detik)
1	4.46
2	3.21
3	4.05
4	3.52
5	4.88
6	2.98
7	3.6
8	3.41
9	4.05
10	3.99
11	2.81
12	3.64
13	3.81
14	4.4
15	3.06
16	3.53
17	4.7
18	4.3
19	2.96
20	3.42
21	3.81
22	4.59
23	4.14
24	5.1
25	4.4
26	4.25
27	3.06
28	3.97
29	2.57
30	4.36

Waktu *Handling* Piercing ke**Cutting (Arm XC)**

Data Ke-	Waktu (detik)
1	3.82
2	2.97
3	4.01
4	2.47
5	2.78
6	3.74
7	4.17
8	3.17
9	2.07
10	3.97
11	1.77
12	4.5
13	4.52
14	3.12
15	2.75
16	3.13
17	4.55
18	2.16
19	3.08
20	3.31
21	2.53
22	3.9
23	4.19
24	3.21
25	3.46
26	2.73
27	4.02
28	3.16
29	2.38
30	3.98

**Waktu *Handling* Cutting ke WIP
(Arm XC)**

Data Ke-	Waktu (detik)
1	6.11
2	6.04
3	6.52
4	6.84
5	5.8
6	6.75
7	5.97
8	6.44
9	6.75
10	7.02
11	6.83
12	5.29
13	6.76
14	6.93
15	5.97
16	5.94
17	7.2
18	6.12
19	7.02
20	5.57
21	5.04
22	6.46
23	7.13
24	5.59
25	6.44
26	6.57
27	7.06
28	6.84
29	6.87
30	6.35

**Waktu *Handling* Receiving ke
Blanking (Rod XC)**

Data Ke-	Waktu (detik)
1	3.81
2	3.38
3	2.34
4	4.47
5	4.24
6	4.77
7	5.45
8	3.58
9	4.26
10	3.2
11	3.22
12	1.42
13	2.29
14	1.94
15	3.81
16	3.28
17	4.96
18	2.51
19	3.79
20	4.13
21	4.46
22	3.29
23	2.14
24	2.44
25	3.94
26	2.83
27	2.56
28	3.77
29	1.54
30	3.8

**Waktu *Handling* Blanking ke
Piercing (Rod XC)**

Data Ke-	Waktu (detik)
1	3.84
2	3.74
3	3.13
4	4.55
5	3.46
6	2.73
7	3.6
8	3.81
9	3.42
10	2.25
11	2.98
12	1.92
13	3.54
14	2.57
15	4.05
16	1.94
17	2.96
18	3.12
19	3.74
20	2.84
21	2.81
22	3.18
23	3.42
24	2.94
25	4.04
26	3.54
27	3.22
28	2.87
29	3.28
30	2.11

**Waktu *Handling* Piercing ke WIP
(Rod XC)**

Data Ke-	Waktu (detik)
1	12.4
2	10.31
3	11.47
4	13.77
5	10.25
6	12.59
7	13.56
8	11.92
9	11.94
10	12.81
11	13.28
12	12.41
13	13.22
14	12.11
15	11.94
16	11.85
17	12.77
18	12.91
19	13.64
20	11.89
21	11.71
22	13.78
23	12.96
24	13.89
25	11.51
26	9.79
27	11.05
28	12.74
29	11.85
30	11.76

Waktu *Handling* WIP ke Assembly**1 (XC)**

Data Ke-	Waktu (detik)
1	11.57
2	10.24
3	12.81
4	11.38
5	11.94
6	10.31
7	12.58
8	10.23
9	12.96
10	11.85
11	11.88
12	12.34
13	11.47
14	12.4
15	11.71
16	9.17
17	11.85
18	10.41
19	12.24
20	12.71
21	10.77
22	11.47
23	12.28
24	10.35
25	10.04
26	12.77
27	10.66
28	12.45
29	11.89
30	11.54

Waktu *Handling* WIP ke Assembly**2 (XC)**

Data Ke-	Waktu (detik)
1	18.07
2	17.52
3	16.06
4	17.49
5	19.08
6	15.57
7	18.52
8	17.55
9	16.28
10	17.21
11	16.46
12	16.94
13	18.05
14	16.84
15	16.56
16	16.59
17	19.51
18	17.13
19	16.7
20	17.16
21	18.96
22	16.54
23	16.72
24	17.66
25	17.96
26	18.5
27	17.72
28	18.11
29	16.84
30	16.44

Waktu Handling Assembly 1 ke**Assembly 2 (XC)**

Data Ke-	Waktu (detik)
1	2.19
2	1.92
3	2.22
4	1.92
5	2.57
6	3.12
7	2.2
8	1.59
9	3.2
10	3.5
11	2.35
12	2.15
13	2.04
14	2.35
15	3.55
16	4.02
17	2.94
18	2.13
19	3.15
20	2.55
21	2.82
22	3.56
23	2.91
24	4.11
25	2.74
26	2.92
27	3.35
28	1.85
29	2.7
30	3.06

Waktu Handling Assembly 2 ke**Expand (XC)**

Data Ke-	Waktu (detik)
1	6.55
2	8.11
3	6.44
4	8.42
5	7.31
6	6.84
7	6.28
8	6.13
9	7.15
10	7.02
11	6.41
12	5.74
13	7.4
14	6.54
15	8.08
16	7.31
17	6.72
18	7.44
19	7.66
20	6.93
21	5.88
22	8.56
23	5.32
24	5.19
25	6.35
26	6.1
27	7.96
28	8.5
29	6.62
30	7.72

**Waktu *Handling Expand* ke
Gudang (XC)**

Data Ke-	Waktu (detik)
1	7.05
2	8.85
3	9.54
4	6.16
5	6.59
6	7.44
7	7.36
8	8.66
9	6.97
10	8.64
11	9.1
12	8.71
13	7.57
14	6.18
15	7.28
16	7.27
17	7.13
18	6.66
19	8.42
20	7.08
21	6.56
22	5.14
23	7.72
24	7.13
25	6.7
26	8.67
27	8.7
28	7.16
29	6.11
30	6.96

**Waktu *Handling Receiving* ke
Bending 1 (Arm H10)**

Data Ke-	Waktu (detik)
1	3.12
2	2.07
3	2.77
4	4.62
5	4
6	3.52
7	3.21
8	3.17
9	4.99
10	4.34
11	5.06
12	3.24
13	3.49
14	4.3
15	5.97
16	3.88
17	4.02
18	3.23
19	3.08
20	5.57
21	5.11
22	4.37
23	3.91
24	5.59
25	6.44
26	2.52
27	4.22
28	2.84
29	4.62
30	3.55

Waktu *Handling* Bending 1 ke**Bending 2 (Arm H10)**

Data Ke-	Waktu (detik)
1	7.62
2	8.67
3	7.26
4	6.24
5	8.67
6	7.31
7	7.5
8	8.04
9	7.05
10	8.28
11	8.1
12	6.93
13	8.72
14	7.46
15	6.91
16	5.23
17	6.48
18	5.19
19	6.42
20	8.81
21	7.96
22	6.97
23	8.15
24	6.67
25	7.35
26	6.64
27	8.44
28	7
29	6.08
30	8.94

Waktu *Handling* Bending 2 ke**Piercing (Arm H10)**

Data Ke-	Waktu (detik)
1	1.33
2	2.18
3	4.95
4	3.35
5	2.91
6	3.24
7	2.64
8	8.62
9	4.89
10	4.2
11	2.41
12	1.55
13	2.14
14	3.28
15	5.72
16	4.44
17	1.91
18	5.99
19	2.42
20	2.81
21	3.53
22	4.75
23	2.19
24	1.45
25	2.94
26	2.49
27	3.14
28	2.66
29	3.23
30	2.62

**Waktu *Handling* Piercing ke
Cutting (Arm H10)**

Data Ke-	Waktu (detik)
1	2.18
2	1.86
3	2.49
4	2.31
5	2.34
6	2.09
7	2.41
8	1.62
9	2.06
10	2.08
11	2.22
12	2
13	2.35
14	1.79
15	2.69
16	1.84
17	2.3
18	3.22
19	2.54
20	2.68
21	3.14
22	2.98
23	3.13
24	2.01
25	1.8
26	3.01
27	2.07
28	2.77
29	2.84
30	2.31

**Waktu *Handling* Cutting ke WIP
(Arm H10)**

Data Ke-	Waktu (detik)
1	6.61
2	5.28
3	6.75
4	6.04
5	6.05
6	5.88
7	7.54
8	5.38
9	6.77
10	8.48
11	5.64
12	5.93
13	8.23
14	6.92
15	7.34
16	6.12
17	6.92
18	7.44
19	5.39
20	7.42
21	5.4
22	8.59
23	6.82
24	7.68
25	6.7
26	8.25
27	6.98
28	6.24
29	5.81
30	7.24

Waktu *Handling* Receiving ke**Blanking (Rod H10)**

Data Ke-	Waktu (detik)
1	3.86
2	3.28
3	4.93
4	2.41
5	3.46
6	3.54
7	4.52
8	3.07
9	5.29
10	2.94
11	1.96
12	3.69
13	5
14	4.31
15	5.5
16	3.36
17	2.94
18	3.47
19	2.62
20	3.4
21	2.54
22	4.22
23	3.95
24	3.81
25	5.42
26	2.61
27	4.35
28	5.66
29	3.95
30	3.3

Waktu *Handling* Blanking ke**Piercing (Rod H10)**

Data Ke-	Waktu (detik)
1	2.34
2	1.94
3	3.79
4	2.14
5	2.44
6	1.54
7	3.82
8	2.78
9	3.17
10	3.12
11	3.08
12	3.21
13	3.98
14	2.73
15	1.94
16	3.99
17	3
18	2.24
19	3.28
20	4.01
21	1.91
22	2.23
23	3.42
24	4.19
25	2.66
26	2.17
27	2.9
28	3.28
29	2.54
30	2.35

**Waktu *Handling* Piercing ke
Bending (Rod H10)**

Data Ke-	Waktu (detik)
1	1.11
2	2.04
3	2.65
4	2.75
5	3.17
6	1.49
7	3.37
8	2.65
9	2.35
10	4.69
11	3.64
12	3.42
13	3.42
14	2.72
15	3.7
16	2.9
17	2.25
18	3.81
19	2.31
20	2.61
21	3.42
22	3.06
23	2.82
24	2.98
25	4.72
26	2.39
27	2.98
28	1.97
29	4.38
30	3.16

**Waktu *Handling* Bending ke WIP
(Rod H10)**

Data Ke-	Waktu (detik)
1	6.28
2	6.79
3	6.52
4	7.2
5	5.8
6	6.75
7	6.04
8	7.4
9	7.11
10	7.13
11	6.46
12	5.29
13	7.14
14	7.44
15	6.94
16	8.83
17	7.31
18	6.12
19	8.92
20	7.42
21	8.12
22	6.79
23	7.46
24	8.05
25	6.95
26	6.64
27	7.19
28	6.84
29	7.74
30	6.56

Waktu *Handling* WIP ke Assembly**1 (H10)**

Data Ke-	Waktu (detik)
1	11.1
2	9.96
3	10.77
4	8.25
5	11.98
6	10.45
7	11.85
8	13.02
9	12.46
10	9.2
11	11.85
12	13.2
13	11.5
14	13.25
15	10.11
16	10.41
17	13.55
18	12.79
19	12.24
20	10.85
21	11.88
22	14.64
23	9.04
24	14.91
25	12
26	12.71
27	14.52
28	11.07
29	13.63
30	12.34

Waktu *Handling* WIP ke Assembly**2 (H10)**

Data Ke-	Waktu (detik)
1	15.88
2	14.88
3	15.04
4	14.35
5	14.64
6	14.58
7	14.05
8	15.52
9	14.91
10	16.13
11	14.86
12	14.54
13	14.52
14	15.07
15	15.29
16	13.64
17	13.78
18	15.96
19	14.55
20	14.05
21	14.04
22	15.99
23	14.23
24	13.87
25	14.17
26	14.61
27	15.5
28	16.04
29	15.78
30	16.05

Waktu Handling Assembly 1 ke**Assembly 2 (H10)**

Data Ke-	Waktu (detik)
1	5.43
2	4.86
3	7.42
4	5.19
5	4.66
6	5.67
7	4.87
8	5.39
9	5.74
10	5.88
11	4.64
12	5.93
13	3.92
14	5.39
15	4.82
16	6.7
17	6.24
18	5.81
19	4.24
20	6.55
21	6.57
22	3.24
23	6.46
24	4.07
25	5.46
26	7.11
27	5.29
28	4.94
29	5.79
30	6.64

Waktu Handling WIP Assembly 2**ke Expand (H10)**

Data Ke-	Waktu (detik)
1	8.64
2	8.82
3	7.55
4	6.04
5	8.1
6	9.88
7	12.17
8	7.4
9	10.92
10	8.48
11	7.86
12	7.43
13	8.86
14	9.42
15	10.19
16	6.66
17	8.67
18	11.87
19	6.39
20	7.74
21	10.73
22	11.54
23	12.4
24	12.96
25	10.25
26	7.28
27	8.27
28	9.48
29	11.77
30	12.7

**Waktu *Handling Expand* ke
Gudang (H10)**

Data Ke-	Waktu (detik)
1	6.55
2	8.11
3	6.44
4	8.42
5	7.31
6	6.84
7	6.28
8	6.13
9	7.15
10	7.02
11	6.41
12	5.74
13	7.4
14	6.54
15	8.08
16	7.31
17	6.72
18	7.44
19	7.66
20	6.93
21	5.88
22	8.56
23	5.32
24	5.19
25	6.35
26	6.1
27	7.96
28	8.5
29	6.62
30	7.72

**Waktu *Handling Receiving* ke
Bending 1 (Arm H00)**

Data Ke-	Waktu (detik)
1	3.12
2	2.07
3	2.77
4	4.62
5	4
6	3.52
7	3.21
8	3.17
9	4.99
10	4.34
11	5.06
12	3.24
13	3.49
14	4.3
15	5.97
16	3.88
17	4.02
18	3.23
19	3.08
20	5.57
21	5.11
22	4.37
23	3.91
24	5.59
25	6.44
26	2.52
27	4.22
28	2.84
29	4.62
30	3.55

Waktu *Handling* Bending 1 ke**Bending 2 (Arm H00)**

Data Ke-	Waktu (detik)
1	4.19
2	5.66
3	6.17
4	3.76
5	4.53
6	5.99
7	4.98
8	5.47
9	6.15
10	4.23
11	3.26
12	6.93
13	5.54
14	6.55
15	4.72
16	6.96
17	6.28
18	3.87
19	7.43
20	8.63
21	5.33
22	4.17
23	3.55
24	4.91
25	5.04
26	2.76
27	3.52
28	4.61
29	3.44
30	5.11

Waktu *Handling* Bending 2 ke**Piercing (Arm H00)**

Data Ke-	Waktu (detik)
1	8.5
2	11.6
3	8.74
4	6.02
5	8.08
6	10.44
7	7.46
8	8.63
9	11.3
10	9
11	10.15
12	10.62
13	9.86
14	8.71
15	11.44
16	8.62
17	9.91
18	7.14
19	8.47
20	9.64
21	9.73
22	10.19
23	7.25
24	11.63
25	8.26
26	9.64
27	8.17
28	9.18
29	10.92
30	8.52

**Waktu *Handling* Piercing ke
Cutting (Arm H00)**

Data Ke-	Waktu (detik)
1	2.82
2	4.59
3	3.15
4	2.53
5	3.97
6	1.96
7	2.94
8	3.17
9	3.6
10	2.76
11	2.22
12	4.97
13	2.94
14	2.07
15	3.78
16	2.3
17	3.47
18	4.04
19	2.16
20	3.94
21	1.66
22	2.64
23	4.56
24	2.63
25	4.26
26	3.84
27	3.71
28	2.67
29	2.7
30	3.69

**Waktu *Handling* Cutting ke WIP
(Arm H00)**

Data Ke-	Waktu (detik)
1	5.5
2	6.54
3	7.33
4	6.63
5	6.15
6	7.22
7	6.54
8	8.01
9	6.54
10	6.04
11	8.38
12	6.17
13	6.58
14	7.82
15	6.04
16	8.1
17	5.78
18	5.08
19	7.81
20	5.39
21	6.82
22	7.15
23	8.48
24	7.05
25	7.36
26	6.97
27	7.08
28	6.56
29	6.11
30	8.5

Waktu *Handling* Receiving ke**Blanking (Rod H00)**

Data Ke-	Waktu (detik)
1	3.86
2	3.28
3	4.93
4	2.41
5	3.46
6	3.54
7	4.52
8	3.07
9	5.29
10	2.94
11	1.96
12	3.69
13	5
14	4.31
15	5.5
16	3.36
17	2.94
18	3.47
19	2.62
20	3.4
21	2.54
22	4.22
23	3.95
24	3.81
25	5.42
26	2.61
27	4.35
28	5.66
29	3.95
30	3.3

Waktu *Handling* Blanking ke**Piercing (Rod H00)**

Data Ke-	Waktu (detik)
1	2.34
2	1.94
3	3.79
4	2.14
5	2.44
6	1.54
7	3.82
8	2.78
9	3.17
10	3.12
11	3.08
12	3.21
13	3.98
14	2.73
15	1.94
16	3.99
17	3
18	2.24
19	3.28
20	4.01
21	1.91
22	2.23
23	3.42
24	4.19
25	2.66
26	2.17
27	2.9
28	3.28
29	2.54
30	2.35

**Waktu *Handling* Piercing ke
Bending (Rod H00)**

Data Ke-	Waktu (detik)
1	1.11
2	2.04
3	2.65
4	2.75
5	3.17
6	1.49
7	3.37
8	2.65
9	2.35
10	4.69
11	3.64
12	3.42
13	3.42
14	2.72
15	3.7
16	2.9
17	2.25
18	3.81
19	2.31
20	2.61
21	3.42
22	3.06
23	2.82
24	2.98
25	4.72
26	2.39
27	2.98
28	1.97
29	4.38
30	3.16

**Waktu *Handling* Bending ke WIP
(Rod H00)**

Data Ke-	Waktu (detik)
1	6.28
2	6.79
3	6.52
4	7.2
5	5.8
6	6.75
7	6.04
8	7.4
9	7.11
10	7.13
11	6.46
12	5.29
13	7.14
14	7.44
15	6.94
16	8.83
17	7.31
18	6.12
19	8.92
20	7.42
21	8.12
22	6.79
23	7.46
24	8.05
25	6.95
26	6.64
27	7.19
28	6.84
29	7.74
30	6.56

Waktu *Handling* WIP ke Assembly**1 (H00)**

Data Ke-	Waktu (detik)
1	6.44
2	5.11
3	7.08
4	4.58
5	5.07
6	6.14
7	7.24
8	5.17
9	7.13
10	9.84
11	5.18
12	6.02
13	8.85
14	5.32
15	4.88
16	6.16
17	5.26
18	8.85
19	6.92
20	7.55
21	5.7
22	6.86
23	9.14
24	7.71
25	5.32
26	6.47
27	5.11
28	6.39
29	9.12
30	7.44

Waktu *Handling* WIP ke Assembly**2 (H00)**

Data Ke-	Waktu (detik)
1	10.77
2	14.22
3	10.19
4	8.98
5	11.6
6	10.44
7	11.63
8	14.58
9	15.32
10	11.88
11	12.38
12	13.68
13	13.97
14	12.16
15	13.14
16	12.82
17	13.97
18	11.96
19	12.76
20	12.3
21	14.56
22	13.84
23	11.19
24	10.98
25	8.63
26	11.17
27	13.44
28	11.98
29	11.85
30	13.2

Waktu Handling Assembly 1 ke**Assembly 2 (H10)**

Data Ke-	Waktu (detik)
1	1.88
2	3.31
3	2.98
4	2.14
5	4.21
6	3.37
7	2.38
8	3.44
9	2.92
10	3.11
11	2.22
12	4.52
13	2.61
14	2.54
15	3.68
16	3.17
17	2.45
18	2.74
19	4.11
20	3.55
21	1.91
22	3.97
23	4.22
24	2.3
25	2.16
26	3.37
27	2.65
28	2.47
29	3.14
30	2.84

Waktu Handling WIP Assembly 2**ke Expand (H10)**

Data Ke-	Waktu (detik)
1	12.55
2	12.59
3	10.14
4	11.27
5	13.31
6	12.46
7	11.7
8	10.13
9	12.98
10	11.34
11	11.94
12	9.11
13	10.26
14	14.92
15	12.02
16	14.09
17	11.38
18	13.44
19	13.85
20	11.31
21	10.84
22	9.55
23	10.35
24	11.24
25	15.11
26	12.14
27	10.05
28	11.38
29	10.78
30	10.22

**Waktu *Handling* Expand ke
Gudang (H10)**

Data Ke-	Waktu (detik)
1	6.55
2	8.11
3	6.44
4	8.42
5	7.31
6	6.84
7	6.28
8	6.13
9	7.15
10	7.02
11	6.41
12	5.74
13	7.4
14	6.54
15	8.08
16	7.31
17	6.72
18	7.44
19	7.66
20	6.93
21	5.88
22	8.56
23	5.32
24	5.19
25	6.35
26	6.1
27	7.96
28	8.5
29	6.62
30	7.72

LAMPIRAN 2

- **CONTOH HASIL PENGUJIAN
STAT FIT UNTUK *BENDING*
*ARM BRAKE PEDAL XC***

HASIL PENGUJIAN STAT FIT UNTUK *BENDING* *ARM BRAKE PEDAL XC*

Auto::Fit Distributions

distribution	rank	acceptance
Weibull(0, 16, 24.3)	99.2	accept
Lognormal(0, 3.16, 0.0714)	86.7	accept
Pearson 5(0, 195, 4.57e+03)	85.2	accept
Beta(0, 26.3, 16.8, 2.07)	63.7	accept
Triangular(0, 27, 26.1)	0	reject
Uniform(0, 26.3)	0	reject

Weibull

minimum = 0 [fixed]
 alpha = 15.9711
 beta = 24.2894

Chi Squared

total classes 4
 interval type equal probable
 net bins 4
 chi**2 1.2
 degrees of freedom 3
 alpha 0.05
 chi**2(3,0.05) 7.81
 p-value 0.753
 result DO NOT REJECT

Kolmogorov-Smirnov

data points 30
 ks stat 0.103
 alpha 0.05
 ks stat(30,0.05) 0.242
 p-value 0.875
 result DO NOT REJECT

Anderson-Darling

data points 30
 ad stat 0.396
 alpha 0.05
 ad stat(0.05) 2.49
 p-value 0.853
 result DO NOT REJECT

LAMPIRAN 3

▪ TABEL UJI SEBARAN T

TABEL UJI SEBARAN T

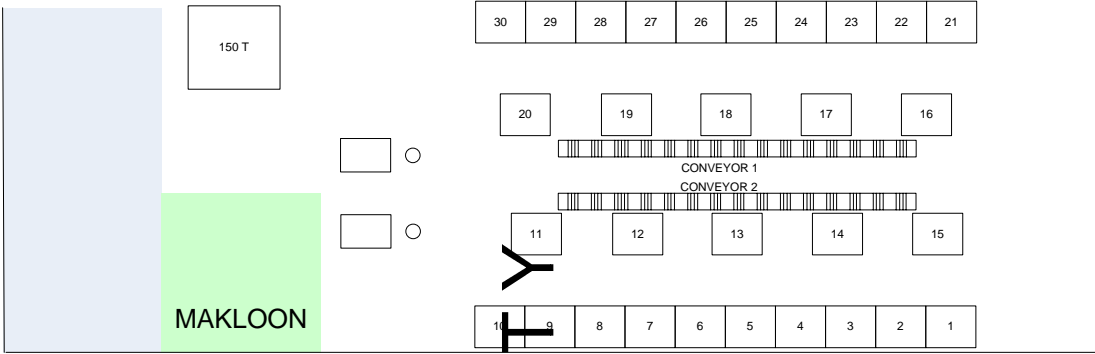
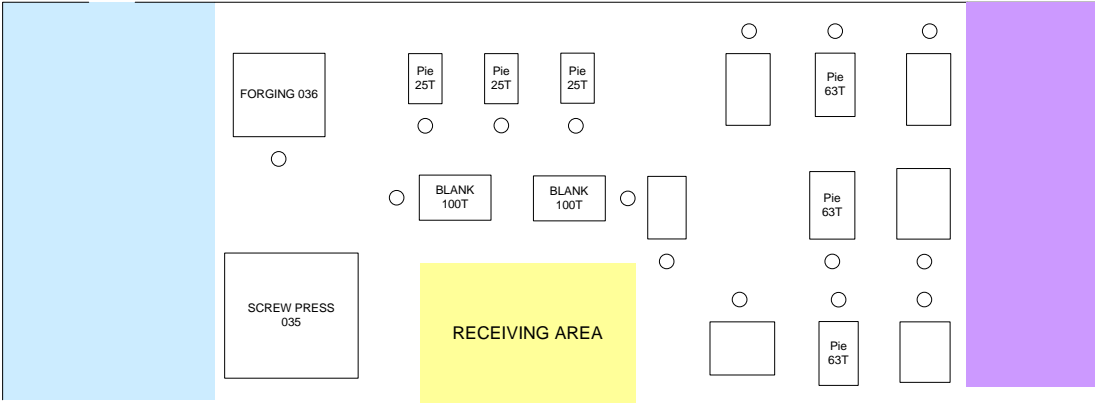
**TABEL II
NILAI-NILAI DALAM DISTRIBUSI t**

α untuk uji dua pihak (two tail test)						
	0,50	0,20	0,10	0,05	0,02	0,01
α untuk uji satu pihak (one tail test)						
dk	0,25	0,10	0,05	0,025	0,01	0,005
1	1,000	3,078	6,314	12,706	31,821	63,657
2	0,816	1,886	2,920	4,303	6,965	9,925
3	0,765	1,638	2,353	3,182	4,541	5,841
4	0,741	1,533	2,132	2,776	3,747	4,604
5	0,727	1,476	2,015	2,571	3,365	4,032
6	0,718	1,440	1,943	2,447	3,143	3,707
7	0,711	1,415	1,895	2,365	2,998	3,499
8	0,706	1,397	1,860	2,306	2,896	3,355
9	0,703	1,383	1,833	2,262	2,821	3,250
10	0,700	1,372	1,812	2,228	2,764	3,169
11	0,697	1,363	1,796	2,201	2,718	3,106
12	0,695	1,356	1,782	2,179	2,681	3,055
13	0,692	1,350	1,771	2,160	2,650	3,012
14	0,691	1,345	1,761	2,145	2,624	2,977
15	0,690	1,341	1,753	2,131	2,602	2,947
16	0,689	1,337	1,746	2,120	2,583	2,921
17	0,688	1,333	1,740	2,110	2,567	2,898
18	0,688	1,330	1,734	2,101	2,552	2,878
19	0,687	1,328	1,729	2,093	2,539	2,861
20	0,687	1,325	1,725	2,086	2,528	2,845
21	0,686	1,323	1,721	2,080	2,518	2,831
22	0,686	1,321	1,717	2,074	2,508	2,819
23	0,685	1,319	1,714	2,069	2,500	2,807
24	0,685	1,318	1,711	2,064	2,492	2,797
25	0,684	1,316	1,708	2,060	2,485	2,787
26	0,684	1,315	1,706	2,056	2,479	2,779
27	0,684	1,314	1,703	2,052	2,473	2,771
28	0,683	1,313	1,701	2,048	2,467	2,763
29	0,683	1,311	1,699	2,045	2,462	2,756
30	0,683	1,310	1,697	2,042	2,457	2,750
40	0,681	1,303	1,684	2,021	2,423	2,704
60	0,679	1,296	1,671	2,000	2,390	2,660
120	0,677	1,289	1,658	1,980	2,358	2,617
∞	0,674	1,282	1,645	1,960	2,326	2,576

LAMPIRAN 4

- **LAYOUT LANTAI PRODUKSI**

LAYOUT LANTAI PRODUKSI



KETING

LAMPIRAN 5

- **INPUT SIMULASI AKTUAL**
- **OUTPUT SIMULASI AKTUAL**

INPUT SIMULASI AKTUAL

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*****
*
*           Formatted Listing of Model :
*           D: \Li na' s Document\TA\Aktual .MOD
*
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Time Uni ts:           Mi nutes
Di stance Uni ts:     Feet
Ini tial izati on Logi c:

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*****
*
*           Locati ons
*
*****

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Name	Cap	Uni ts	Stats	Rules	Cost
Ms_Forgi ng	1	1	Time Series	Ol dest,	
Ms_Bl ank1	1	1	Time Series	Ol dest,	
Ms_Pi e25_1	2	1	Time Series	Ol dest,	
Ms_Hyd	2	1	Time Series	Ol dest,	
Ms_Pi e63_1	2	1	Time Series	Ol dest,	
Ms_Cut90_1	1	1	Time Series	Ol dest,	
Ms_Bl ank2	1	1	Time Series	Ol dest,	
Ms_Pi e25_2	2	1	Time Series	Ol dest,	
Ms_Pi e25_3	2	1	Time Series	Ol dest,	
Ms_Bend35	2	1	Time Series	Ol dest,	
Ms_Bend35_2	2	1	Time Series	Ol dest,	
Ms_Bend100	1	1	Time Series	Ol dest,	
Ms_Pi e63_3	2	1	Time Series	Ol dest,	
Ms_Cut100	1	1	Time Series	Ol dest,	
Ms_Pi e63_2	2	1	Time Series	Ol dest,	
Ms_Cut90_2	1	1	Time Series	Ol dest,	
Assy1_XC	1	3	Time Series	Ol dest,	Fi rst
Assy1_XC. 1	1	1	Time Series	Ol dest,	
Assy1_XC. 2	1	1	Time Series	Ol dest,	
Assy1_XC. 3	1	1	Time Series	Ol dest,	
Assy1_H10	1	3	Time Series	Ol dest,	Fi rst
Assy1_H10. 1	1	1	Time Series	Ol dest,	
Assy1_H10. 2	1	1	Time Series	Ol dest,	
Assy1_H10. 3	1	1	Time Series	Ol dest,	
Assy1_H00	1	3	Time Series	Ol dest,	Fi rst

Assy1_H00.1	1	1	Time Series Oldest,	,
Assy1_H00.2	1	1	Time Series Oldest,	,
Assy1_H00.3	1	1	Time Series Oldest,	,
Assy2_XC	1	1	Time Series Oldest,	,
Assy2_H10	1	1	Time Series Oldest,	,
Assy2_H00	1	1	Time Series Oldest,	,
Ms_Expand	1	1	Time Series Oldest,	,
Receiving_Area	INF	1	Time Series Oldest,	,
WIP	INF	1	Time Series Oldest,	,
in_forging	INF	1	Time Series Oldest,	,
in_blank1	INF	1	Time Series Oldest,	,
in_blank2	INF	1	Time Series Oldest,	,
in_pie25_1	INF	1	Time Series Oldest,	,
in_pie25_2	INF	1	Time Series Oldest,	,
in_pie25_3	INF	1	Time Series Oldest,	,
in_Hyd	INF	1	Time Series Oldest,	,
in_bend35	INF	1	Time Series Oldest,	,
in_bend100	INF	1	Time Series Oldest,	,
in_cut100	INF	1	Time Series Oldest,	,
in_cut90_1	INF	1	Time Series Oldest,	,
in_cut90_2	INF	1	Time Series Oldest,	,
in_pie63_1	INF	1	Time Series Oldest,	,
in_pie63_2	INF	1	Time Series Oldest,	,
in_pie63_3	INF	1	Time Series Oldest,	,
in_Arm_XC	INF	1	Time Series Oldest,	,
in_Rod_XC	INF	1	Time Series Oldest,	,
in_Boss_XC	INF	1	Time Series Oldest,	,
in_Shoe_XC	INF	1	Time Series Oldest,	,
in_Arm_H10	INF	1	Time Series Oldest,	,
in_Rod_H10	INF	1	Time Series Oldest,	,
in_Boss_H10	INF	1	Time Series Oldest,	,
in_Shoe_H10	INF	1	Time Series Oldest,	,
in_Arm_H00	INF	1	Time Series Oldest,	,
in_Rod_H00	INF	1	Time Series Oldest,	,
in_Boss_H00	INF	1	Time Series Oldest,	,
in_Shoe_H00	INF	1	Time Series Oldest,	,
in_switc_XC	INF	1	Time Series Oldest,	,
in_spring_XC	INF	1	Time Series Oldest,	,
in_Pedal_XC	INF	1	Time Series Oldest,	,
in_switc_H10	INF	1	Time Series Oldest,	,
in_spring_H10	INF	1	Time Series Oldest,	,
in_Pedal_H10	INF	1	Time Series Oldest,	,
in_switc_H00	INF	1	Time Series Oldest,	,
in_spring_H00	INF	1	Time Series Oldest,	,
in_Pedal_H00	INF	1	Time Series Oldest,	,
in_expand	INF	1	Time Series Oldest,	,
out_forging	INF	1	Time Series Oldest,	,
out_blank1	INF	1	Time Series Oldest,	,
out_blank2	INF	1	Time Series Oldest,	,

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out_pie25_1    INF 1    Time Series Oldest, ,
out_pie25_2    INF 1    Time Series Oldest, ,
out_pie25_3    INF 1    Time Series Oldest, ,
out_Hyd        INF 1    Time Series Oldest, ,
out_bend35     INF 1    Time Series Oldest, ,
out_bend100    INF 1    Time Series Oldest, ,
out_cut100     INF 1    Time Series Oldest, ,
out_pie63_1    INF 1    Time Series Oldest, ,
out_pie63_2    INF 1    Time Series Oldest, ,
out_pie63_3    INF 1    Time Series Oldest, ,
out_cut90_1    INF 1    Time Series Oldest, ,
out_cut90_2    INF 1    Time Series Oldest, ,
out_assy1_XC   INF 1    Time Series Oldest, ,
out_assy1_H10  INF 1    Time Series Oldest, ,
out_assy1_H00  INF 1    Time Series Oldest, ,
out_assy2_XC   INF 1    Time Series Oldest, ,
out_assy2_H10  INF 1    Time Series Oldest, ,
out_assy2_H00  INF 1    Time Series Oldest, ,
out_expand     INF 1    Time Series Oldest, ,
Shi pping_XC   INF 1    Time Series Oldest, ,
Shi pping_H10  INF 1    Time Series Oldest, ,
Shi pping_H00  INF 1    Time Series Oldest, ,
Shi pping      1    1    Time Series Oldest, ,

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*****
*                               Entities                               *
*****

```

Name	Speed (fpm)	Stats	Cost
Boss	150	Time Series	
Brake_shoe	150	Time Series	
Arm_XC	150	Time Series	
Rod_XC	150	Time Series	
Swi tch_XC	150	Time Series	
Spri ng_XC	150	Time Series	
Pedal_XC	150	Time Series	
Box_Arm_XC	150	Time Series	
Box_Rod_XC	150	Time Series	
Box_Swi tch_XC	150	Time Series	
Box_Spri ng_XC	150	Time Series	
Box_Boss	150	Time Series	
Box_Shoe	150	Time Series	
Box_Arm_H10	150	Time Series	
Box_Rod_H10	150	Time Series	
Box_Swi tch_H10	150	Time Series	
Box_Spri ng_H10	150	Time Series	
Box_Arm_H00	150	Time Series	

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Box_Rod_H00      150      Time Series
Box_Switch_H00  150      Time Series
Box_Spring_H00  150      Time Series
Arm_H10          150      Time Series
Rod_H10          150      Time Series
Switch_H10      150      Time Series
Spring_H10      150      Time Series
Pedal_H10       150      Time Series
Arm_H00         150      Time Series
Rod_H00         150      Time Series
Switch_H00     150      Time Series
Spring_H00     150      Time Series
Pedal_H00      150      Time Series
Box_Pedal_XC   150      Time Series
Box_Pedal_H10  150      Time Series
Box_Pedal_H00  150      Time Series
Brake_pedal_XC 150      Time Series
Brake_pedal_H10 150     Time Series
Brake_pedal_H00 150     Time Series
pengiri man    150      Time Series

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*****
*                               Path Networks                               *
*****

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Name	Type	T/S	From	To	BI	Dist/Time	Speed Factor
WI P_to_assy1_XC	Passing	Time	N1	N2	Bi	W(14.9, 12) sec	
WI P_to_assy1_H10	Passing	Time	N1	N2	Bi	W(8.21, 12.6) sec	
WI P_to_assy1_H00	Passing	Time	N1	N2	Bi	W(4.8, 7.19) sec	
Forg_to_WIP	Passing	Time	N1	N2	Bi	W(12, 16.3) sec	
assy2_XC_to_exp	Passing	Time	N1	N2	Bi	W(8.56, 7.35) sec	
assy2_H10_to_exp	Passing	Time	N1	N2	Bi	W(5.21, 10.2) sec	
assy2_H00_to_exp	Passing	Time	N1	N2	Bi	W(7.92, 12.4) sec	
WI P_to_assy2_XC	Passing	Time	N1	N2	Bi	W(18.4, 17.8) sec	
WI P_to_assy2_H10	Passing	Time	N1	N2	Bi	W(21.1, 15.3) sec	
WI P_to_assy2_H00	Passing	Time	N1	N2	Bi	W(8.95, 13) sec	
Pie25_1_to_WIP	Passing	Time	N1	N2	Bi	W(14, 12.7) sec	
exp_to_Gd	Passing	Time	N1	N2	Bi	W(7.85, 7.9) sec	
pie25_2_to_WIP	Passing	Time	N1	N2	Bi	W(8.98, 7.4) sec	
bend35_to_blink	Passing	Time	N1	N2	Bi	W(4.03, 5.64) sec	
blink_to_pie63_2	Passing	Time	N1	N2	Bi	W(7.52, 9.86) sec	

```

*****
*                                     Interfaces                                     *
*****

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Net	Node	Location
WIP_to_assy1_XC	N1	WIP
	N2	in_Arm_XC
	N2	in_Rod_XC
	N2	in_Boss_XC
	N2	in_Shoe_XC
WIP_to_assy1_H10	N1	WIP
	N2	in_Arm_H10
	N2	in_Rod_H10
	N2	in_Boss_H10
	N2	in_Shoe_H10
WIP_to_assy1_H00	N1	WIP
	N2	in_Arm_H00
	N2	in_Rod_H00
	N2	in_Boss_H00
	N2	in_Shoe_H00
Forg_to_WIP	N1	out_forging
	N2	WIP
assy2_XC_to_exp	N1	out_assy2_XC
	N2	in_expand
assy2_H10_to_exp	N1	out_assy2_H10
	N2	in_expand
assy2_H00_to_exp	N1	out_assy2_H00
	N2	in_expand
WIP_to_assy2_XC	N1	WIP
	N2	in_switch_XC
	N2	in_spring_XC
	N2	in_Pedal_XC
	N2	in_Pedal_XC
WIP_to_assy2_H10	N1	WIP
	N2	in_switch_H10
	N2	in_spring_H10
	N2	in_Pedal_H10
WIP_to_assy2_H00	N1	WIP
	N2	in_switch_H00
	N2	in_spring_H00
	N2	in_Pedal_H00
Pie25_1_to_WIP	N1	out_pie25_1
	N2	WIP
exp_to_Gd	N1	out_expand
	N2	Shipping_XC
	N2	Shipping_H10
	N2	Shipping_H00
pie25_2_to_WIP	N1	out_pie25_2
	N2	WIP


```

bend35_to_blink N1      out_bend35
                  N2      in_blink2
blink_to_pie63_2 N1      out_blink2
                  N2      in_pie63_2

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*****
*                                     Processing
*****

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Entity	Location	Process		Routing			
		Operation	Blk	Output	Destination	Rule	Move Logic
Brake_shoe	Receiving_Area	GROUP 50 AS Box_Shoe					
Box_Shoe	Receiving_Area		1	Box_Shoe	in_forging	FIRST 1	MOVE FOR W(5.46, 3.01) SEC
Box_Shoe	in_forging	UNGROUP RENAME Brake_shoe					
Brake_shoe	in_forging		1	Brake_shoe	Ms_Forging	FIRST 1	
Brake_shoe	Ms_Forging	WAIT W(5.9, 6.33) SEC	1	Brake_shoe	out_forging	FIRST 1	GRAPHIC 2
Brake_shoe	out_forging	GROUP 50 AS Box_Shoe					
Box_Shoe	out_forging		1	Box_Shoe	WIP	FIRST 1	MOVE ON Forg_to_WIP
Brake_shoe	WIP	GROUP 50 AS Box_Shoe					
Box_Shoe	WIP		1	Box_Shoe	in_Shoe_XC	MOST 1	MOVE ON WIP_to_assy1_XC
				Box_Shoe	in_Shoe_H10	MOST	MOVE ON WIP_to_assy1_H10
				Box_Shoe	in_Shoe_H00	MOST	MOVE ON WIP_to_assy1_H00
Box_Shoe	in_Shoe_XC	UNGROUP RENAME Brake_shoe GRAPHIC 2					
Brake_shoe	in_Shoe_XC		1	Brake_shoe	Assy1_XC	JOIN 1	
Box_Shoe	in_Shoe_H10	UNGROUP RENAME Brake_shoe GRAPHIC 2					
Brake_shoe	in_Shoe_H10		1	Brake_shoe	Assy1_H10	JOIN 1	
Box_Shoe	in_Shoe_H00	UNGROUP RENAME Brake_shoe GRAPHIC 2					

Brake_shoe	i n_Shoe_H00		1	Brake_shoe	Assy1_H00	JOIN 1	
Boss	WIP	GROUP 30 AS Box_Boss	1	Box_Boss	i n_Boss_XC	TURN 1	MOVE ON WIP_to_assy1_XC
Box_Boss	WIP			Box_Boss	i n_Boss_H10	TURN	MOVE ON WIP_to_assy1_H10
				Box_Boss	i n_Boss_H00	TURN	MOVE ON WIP_to_assy1_H00
Box_Boss	i n_Boss_XC	UNGROUP RENAME Boss					
Boss	i n_Boss_XC		1	Boss	Assy1_XC	JOIN 1	
Box_Boss	i n_Boss_H10	UNGROUP RENAME Boss					
Boss	i n_Boss_H10		1	Boss	Assy1_H10	JOIN 1	
Box_Boss	i n_Boss_H00	UNGROUP RENAME Boss					
Boss	i n_Boss_H00		1	Boss	Assy1_H00	JOIN 1	
Swi tch_XC	WIP	GROUP 50 AS Box_Swi tch_XC	1	Box_Swi tch_XC	i n_swi tch_XC	FIRST 1	MOVE ON WIP_to_assy2_XC
Box_Swi tch_XC	WIP		1	Box_Swi tch_XC	i n_swi tch_XC	FIRST 1	MOVE ON WIP_to_assy2_XC
Box_Swi tch_XC	i n_swi tch_XC	UNGROUP RENAME Swi tch_XC					
Swi tch_XC	i n_swi tch_XC		1	Swi tch_XC	Assy2_XC	JOIN 1	
Spri ng_XC	WIP	GROUP 50 AS Box_Spri ng_XC	1	Box_Spri ng_XC	i n_spri ng_XC	FIRST 1	MOVE ON WIP_to_assy2_XC
Box_Spri ng_XC	WIP		1	Box_Spri ng_XC	i n_spri ng_XC	FIRST 1	MOVE ON WIP_to_assy2_XC
Box_Spri ng_XC	i n_spri ng_XC	UNGROUP RENAME Spr i ng_XC					
Spri ng_XC	i n_spri ng_XC		1	Spri ng_XC	Assy2_XC	JOIN 1	
Rod_XC	Recei vi ng_Area	GROUP 50 AS Box_Rod_XC	1	Box_Rod_XC	i n_bl ank1	FIRST 1	MOVE FOR W(3.85, 3.75) SEC
Box_Rod_XC	Recei vi ng_Area		1	Box_Rod_XC	i n_bl ank1	FIRST 1	MOVE FOR W(3.85, 3.75) SEC
Box_Rod_XC	i n_bl ank1	UNGROUP RENAME Rod_XC					
Rod_XC	i n_bl ank1		1	Rod_XC	Ms_Bl ank1	FIRST 1	
Rod_XC	Ms_Bl ank1	WAIT W(3.68, 4.16) SEC	1	Rod_XC	out_bl ank1	FIRST 1	GRAPHIC 2
Rod_XC	out_bl ank1		1	Rod_XC	out_bl ank1	FIRST 1	GRAPHIC 2
Box_Rod_XC	out_bl ank1	GROUP 50 AS Box_Rod_XC	1	Box_Rod_XC	i n_pi e25_1	FIRST 1	MOVE FOR W(5.83, 3.44) SEC

Box_Rod_XC	in_pie25_1	UNGROUP RENAME Rod_XC GRAPHIC 2					
Rod_XC	in_pie25_1		1	Rod_XC	Ms_Pie25_1	FIRST 1	
Rod_XC	Ms_Pie25_1	WAIT W(8.97, 16.5) SEC	1	Rod_XC	out_pie25_1	FIRST 1	GRAPHIC 3
Rod_XC Box_Rod_XC	out_pie25_1 out_pie25_1	GROUP 50 AS Box_Rod_XC	1	Box_Rod_XC	WIP	FIRST 1	MOVE ON Pie25_1_to_WIP
Rod_XC Box_Rod_XC Box_Rod_XC	WIP WIP in_Rod_XC	GROUP 50 AS Box_Rod_XC UNGROUP RENAME Rod_XC GRAPHIC 3	1	Box_Rod_XC	in_Rod_XC	FIRST 1	MOVE ON WIP_to_assy1_XC
Rod_XC Arm_XC	in_Rod_XC Receiving_Area	GROUP 30 AS Box_Arm_XC	1	Rod_XC	Assy1_XC	JOIN 1	
Box_Arm_XC	Receiving_Area		1	Box_Arm_XC	in_Hyd	FIRST 1	MOVE FOR W(4.67, 3.32) SEC
Box_Arm_XC	in_Hyd	UNGROUP RENAME Arm_XC					
Arm_XC	in_Hyd	INC hyd	1	Arm_XC	Ms_Hyd	FIRST 1	DEC hyd
Arm_XC	Ms_Hyd	WAIT W(16, 24.3) SEC IF jml_arm_XC < 1320 AND ruleroute_XC = 0 THEN { ROUTE 1 } ELSE { ruleroute_XC = 0 ROUTE 2 }					
			1	Arm_XC	out_Hyd	FIRST 1	GRAPHIC 2
			2	Arm_XC	out_Hyd	SEND 1	GRAPHIC 2

Arm_XC	out_Hyd	GROUP 30 AS Box_Arm_XC					
Box_Arm_XC	out_Hyd		1	Box_Arm_XC	in_pi e63_1	FIRST 1	MOVE FOR W(6.8, 4.11) SEC
Box_Arm_XC	in_pi e63_1	UNGROUP RENAME Arm_XC GRAPHIC 2					
Arm_XC	in_pi e63_1	INC in_63_1	1	Arm_XC	Ms_Pi e63_1	FIRST 1	DEC in_63_1
Arm_XC	Ms_Pi e63_1	WAIT W(23, 25.4) SEC IF jml_arm_XC < 1320 AND ruleroute_XC = 0 THEN { ROUTE 1 } ELSE { ruleroute_XC = 0 ROUTE 2 }					
			1	Arm_XC	out_pi e63_1	FIRST 1	GRAPHIC 3
			2	Arm_XC	out_pi e63_1	SEND 1	GRAPHIC 3
Arm_XC Box_Arm_XC	out_pi e63_1 out_pi e63_1	GROUP 30 AS Box_Arm_XC	1	Box_Arm_XC	in_cut90_1	FIRST 1	MOVE FOR W(5.06, 3.62) SEC
Box_Arm_XC	in_cut90_1	UNGROUP RENAME Arm_XC GRAPHIC 3					
Arm_XC	in_cut90_1	INC in_90_1	1	Arm_XC	Ms_Cut90_1	FIRST 1	DEC in_90_1
Arm_XC	Ms_Cut90_1	WAIT W(5.58, 13.2) SEC IF jml_arm_XC < 1320 AND ruleroute_XC = 0 THEN { ROUTE 1 } ELSE { ruleroute_XC = 0 ROUTE 2 }					
			1	Arm_XC	out_cut90_1	FIRST 1	GRAPHIC 4

```

                2   Arm_XC           out_cut90_1   SEND 1   GRAPHIC 4
Arm_XC           out_cut90_1   GROUP 30 AS Box_Arm_XC
Box_Arm_XC      out_cut90_1   1   Box_Arm_XC   WIP           FIRST 1   MOVE FOR W(14.6, 6.65) SEC
Arm_XC           WIP           GROUP 30 AS Box_Arm_XC
Box_Arm_XC      WIP           1   Box_Arm_XC   in_Arm_XC    FIRST 1   MOVE ON WIP_to_assy1_XC
Box_Arm_XC      in_Arm_XC     UNGROUP
                RENAME Arm_XC
                GRAPHIC 4
Arm_XC           in_Arm_XC     INC jml_arm_XC
                IF jml_arm_XC >= 1320 THEN
                {
                ruleroute_XC = 1
                henti_XC = 1
                }
                1   Arm_XC           Assy1_XC     FIRST 1   DEC jml_arm_XC
= 1) THEN
                IF (jml_arm_XC = 660) AND (henti_XC
                {
                SEND 1 Arm_XC TO out_cut90_1
                SEND 1 Arm_XC TO out_pie63_1
                SEND 1 Arm_XC TO out_Hyd
                henti_XC = 0
                }

Arm_XC           Assy1_XC     JOIN 1 Rod_XC
                JOIN 1 Boss
                JOIN 1 Brake_shoe
                WAIT W(15.3, 73.3) SEC
                1   Pedal_XC           out_assy1_XC   FIRST 1
Pedal_XC         out_assy1_XC   GROUP 30 AS Box_Pedal_XC
Box_Pedal_XC    out_assy1_XC     1   Box_Pedal_XC   in_Pedal_XC   FIRST 1   MOVE FOR W(4.58, 2.98) SEC
Box_Pedal_XC    in_Pedal_XC     UNGROUP
                RENAME Pedal_XC
Pedal_XC         in_Pedal_XC     INC in_pedal_XC
                1   Pedal_XC           Assy2_XC     FIRST 1   DEC in_pedal_XC
Pedal_XC         Assy2_XC     JOIN 1 Spring_XC
                JOIN 1 Switch_XC
                WAIT W(11.1, 38.7) SEC

```

			1	Pedal_XC	out_assy2_XC	FIRST 1	GRAPHIC 2
Pedal_XC Box_Pedal_XC	out_assy2_XC out_assy2_XC	GROUP 30 AS Box_Pedal_XC	1	Box_Pedal_XC	in_expand	FIRST 1	MOVE ON assy2_XC_to_exp
Box_Pedal_XC	in_expand	UNGROUP RENAME Pedal_XC GRAPHIC 2					
Pedal_XC	in_expand	INC in_ex	1	Pedal_XC	Ms_Expand	FIRST 1	DEC in_ex
Pedal_XC	Ms_Expand	WAIT W(7.44, 12.8) SEC	1	Pedal_XC	out_expand	FIRST 1	GRAPHIC 2
Pedal_XC Brake_pedal_XC Brake_pedal_XC	out_expand out_expand Shi ppi ng_XC	GROUP 30 AS Brake_pedal_XC	1	Brake_pedal_XC	Shi ppi ng_XC	FIRST 1	
		INC j ml_XC	1	Brake_pedal_XC	EXIT	SEND 1	
Swi tch_H10	WIP	GROUP 50 AS Box_Swi tch_H10					
Box_Swi tch_H10	WIP		1	Box_Swi tch_H10	in_swi tch_H10	FIRST 1	MOVE ON WIP_to_assy2_H10
Box_Swi tch_H10	in_swi tch_H10	UNGROUP RENAME Swi tch_H10					
Swi tch_H10 Spri ng_H10	in_swi tch_H10 WIP	GROUP 50 AS Box_Spri ng_H10	1	Swi tch_H10	Assy2_H10	JOIN 1	
Box_Spri ng_H10	WIP		1	Box_Spri ng_H10	in_spri ng_H10	FIRST 1	MOVE ON WIP_to_assy2_H10
Box_Spri ng_H10	in_spri ng_H10	UNGROUP RENAME Spri ng_H10					
Spri ng_H10 Rod_H10	in_spri ng_H10 Recei vi ng_Area	GROUP 50 AS Box_Rod_H10	1	Spri ng_H10	Assy2_H10	JOIN 1	
Box_Rod_H10 Box_Rod_H10	Recei vi ng_Area in_bl ank2	UNGROUP RENAME Rod_H10	1	Box_Rod_H10	in_bl ank2	FIRST 1	
Rod_H10 Rod_H10	in_bl ank2 Ms_Bl ank2	WAIT W(6.73, 5.52) SEC	1	Rod_H10	Ms_Bl ank2, 3	FIRST 1	
			1	Rod_H10	out_bl ank2	FIRST 1	GRAPHIC 2
Rod_H10	out_bl ank2	GROUP 50 AS Box_Rod_H10					
Box_Rod_H10	out_bl ank2		1	Box_Rod_H10	in_pi e25_3	FIRST 1	MOVE FOR W(4.45, 3.15) SEC

Box_Rod_H10	in_pi e25_3	UNGROUP RENAME Rod_H10 GRAPHIC 2					
Rod_H10	in_pi e25_3		1	Rod_H10	Ms_Pi e25_3, 2	FIRST 1	
Rod_H10	Ms_Pi e25_3	WAIT W(7.01, 14.6) SEC	1	Rod_H10	out_pi e25_3	FIRST 1	GRAPHIC 3
Rod_H10	out_pi e25_3	GROUP 50 AS Box_Rod_H10					
Box_Rod_H10	out_pi e25_3		1	Box_Rod_H10	in_pi e25_2	FIRST 1	MOVE FOR W(3.93, 3.27) SEC
Box_Rod_H10	in_pi e25_2	UNGROUP RENAME Rod_H10 GRAPHIC 3					
Rod_H10	in_pi e25_2		1	Rod_H10	Ms_Pi e25_2, 2	FIRST 1	
Rod_H10	Ms_Pi e25_2	WAIT W(9.69, 15) SEC	1	Rod_H10	out_pi e25_2	FIRST 1	GRAPHIC 3
Rod_H10	out_pi e25_2	GROUP 50 AS Box_Rod_H10					
Box_Rod_H10	out_pi e25_2		1	Box_Rod_H10	WIP	FIRST 1	MOVE ON pi e25_2_to_WIP
Rod_H10	WIP	GROUP 50 AS Box_Rod_H10					
Box_Rod_H10	WIP		1	Box_Rod_H10	in_Rod_H10	FIRST 1	MOVE ON WIP_to_assy1_H10
Box_Rod_H10	in_Rod_H10	UNGROUP RENAME Rod_H10 GRAPHIC 3					
Rod_H10	in_Rod_H10		1	Rod_H10	Assy1_H10	JOIN 1	
Arm_H10	Receiving_Area	GROUP 30 AS Box_Arm_H10					
Box_Arm_H10	Receiving_Area		1	Box_Arm_H10	in_bend35	FIRST 1	MOVE FOR W(4.13, 4.43) SEC
Box_Arm_H10	in_bend35	UNGROUP RENAME Arm_H10					
Arm_H10	in_bend35	INC in_35					
			1	Arm_H10	Ms_Bend35	FIRST 1	DEC in_35
Arm_H10	Ms_Bend35	WAIT W(16.8, 19.4) SEC IF jml_arm_H10 < 1560 AND ruleroute_H10 = 0 THEN { ROUTE 1 } ELSE {					

```

        ruleroute_H10 = 0
        ROUTE 2
    }
        1 Arm_H10 out_bend35 FIRST 1 GRAPHIC 2
        2 Arm_H10 out_bend35 SEND 1 GRAPHIC 2
Arm_H10 out_bend35 GROUP 30 AS Box_Arm_H10
Box_Arm_H10 out_bend35 1 Box_Arm_H10 in_bend100 FIRST 1 MOVE FOR W(8.74, 78) SEC
Box_Arm_H10 in_bend100 UNGROUP
RENAME Arm_H10
GRAPHIC 2
Arm_H10 in_bend100 INC in_bend_100
1 Arm_H10 Ms_Bend100 FIRST 1 DEC in_bend_100
Arm_H10 Ms_Bend100 WAIT W(5.34, 13.7) SEC
IF jml_arm_H10 < 1560 AND ruleroute_H10 = 0 THEN
{
ROUTE 1
}
ELSE
{
ruleroute_H10 = 0
ROUTE 2
}
        1 Arm_H10 out_bend100 FIRST 1 GRAPHIC 3
        2 Arm_H10 out_bend100 SEND 1 GRAPHIC 3
Arm_H10 out_bend100 GROUP 30 AS Box_Arm_H10
Box_Arm_H10 out_bend100 1 Box_Arm_H10 in_pi e63_3 FIRST 1 MOVE FOR W(2.28, 3.77) SEC
Box_Arm_H10 in_pi e63_3 UNGROUP
RENAME Arm_H10
GRAPHIC 3
Arm_H10 in_pi e63_3 INC in_63_3
1 Arm_H10 Ms_Pi e63_3 FIRST 1 DEC in_63_3
Arm_H10 Ms_Pi e63_3 WAIT W(18.1, 25) SEC
IF jml_arm_H10 < 1560 AND ruleroute_H10 = 0 THEN
{
ROUTE 1
}
ELSE
{
ruleroute_H10 = 0

```



```

        }
        ROUTE 2
        }
        1 Arm_H10 out_pi e63_3 FIRST 1 GRAPHIC 4
        2 Arm_H10 out_pi e63_3 SEND 1 GRAPHIC 4
Arm_H10 out_pi e63_3 GROUP 30 AS Box_Arm_H10
Box_Arm_H10 out_pi e63_3 1 Box_Arm_H10 in_cut100 FIRST 1 MOVE FOR W(5.81, 2.56) SEC
Box_Arm_H10 in_cut100 UNGROUP
RENAME Arm_H10
GRAPHIC 4
Arm_H10 in_cut100 INC in_cut_100 1 Arm_H10 Ms_Cut100 FIRST 1 DEC in_cut_100
Arm_H10 Ms_Cut100 WAIT W(5.88, 12.9) SEC
IF jml_arm_H10 < 1560 AND ruleroute_H10 = 0 THEN
{
ROUTE 1
}
ELSE
{
ruleroute_H10 = 0
ROUTE 2
}
        1 Arm_H10 out_cut100 FIRST 1 GRAPHIC 5
        2 Arm_H10 out_cut100 SEND 1 GRAPHIC 5
Arm_H10 out_cut100 GROUP 30 AS Box_Arm_H10
Box_Arm_H10 out_cut100 1 Box_Arm_H10 WIP FIRST 1 MOVE FOR W(7.62, 7.15) SEC
Arm_H10 WIP GROUP 30 AS Box_Arm_H10
Box_Arm_H10 WIP 1 Box_Arm_H10 in_Arm_H10 FIRST 1 MOVE ON WIP_to_assy1_H10
Box_Arm_H10 in_Arm_H10 UNGROUP
RENAME Arm_H10
GRAPHIC 5
Arm_H10 in_Arm_H10 INC jml_arm_H10
IF jml_arm_H10 >= 1560 THEN
{
ruleroute_H10 = 1
henti_H10 = 1
}

```

```

(henti_H10 = 1) THEN
    1 Arm_H10 Assy1_H10 FIRST 1 IF (jml_arm_H10 = 780) AND
    {
        SEND 1 Arm_H10 TO out_cut100
        SEND 1 Arm_H10 TO out_pie63_3
        SEND 1 Arm_H10 TO out_bend100
        SEND 1 Arm_H10 TO out_bend35
        henti_H10 = 0
    }
    DEC jml_arm_H10

Arm_H10 Assy1_H10 JOIN 1 Boss
JOIN 1 Brake_shoe
JOIN 1 Rod_H10
WAIT W(41.4, 103) SEC
1 Pedal_H10 out_assy1_H10 FIRST 1
Pedal_H10 out_assy1_H10 GROUP 30 AS Box_Pedal_H10
Box_Pedal_H10 out_assy1_H10 1 Box_Pedal_H10 in_Pedal_H10 FIRST 1 MOVE FOR W(6.47, 5.9) SEC
Box_Pedal_H10 in_Pedal_H10 UNGROUP
RENAME Pedal_H10
Pedal_H10 in_Pedal_H10 INC in_pedal_H10
1 Pedal_H10 Assy2_H10 FIRST 1 DEC in_pedal_H10
Pedal_H10 Assy2_H10 JOIN 1 Spring_H10
JOIN 1 Switch_H10
WAIT W(17.5, 33.3) SEC
1 Pedal_H10 out_assy2_H10 FIRST 1 GRAPHIC 2
Pedal_H10 out_assy2_H10 GROUP 30 AS Box_Pedal_H10
Box_Pedal_H10 out_assy2_H10 1 Box_Pedal_H10 in_expand FIRST 1 MOVE ON assy2_H10_to_exp
Box_Pedal_H10 in_expand UNGROUP
RENAME Pedal_H10
GRAPHIC 2
Pedal_H10 in_expand INC in_ex
1 Pedal_H10 Ms_Expand FIRST 1 DEC in_ex
Pedal_H10 Ms_Expand WAIT W(7.44, 12.8) SEC
1 Pedal_H10 out_expand FIRST 1 GRAPHIC 2
Pedal_H10 out_expand GROUP 30 AS Brake_pedal_H10
Brake_pedal_H10 out_expand 1 Brake_pedal_H10 Shipping_H10 FIRST 1 MOVE ON exp_to_Gd

```

Brake_pedal_H10	Shi ppi ng_H10	INC j ml_H10	1	Brake_pedal_H10	EXIT	SEND	1
Swi tch_H00	WI P	GROUP 50 AS Box_Swi tch_H00					
Box_Swi tch_H00	WI P		1	Box_Swi tch_H00	i n_swi tch_H00	FIRST	1 MOVE ON WI P_to_assy2_H00
Box_Swi tch_H00	i n_swi tch_H00	UNGROUP RENAME Swi tch_H00					
Swi tch_H00	i n_swi tch_H00		1	Swi tch_H00	Assy2_H00	JOIN	1
Spri ng_H00	WI P	GROUP 50 AS Box_Spri ng_H00					
Box_Spri ng_H00	WI P		1	Box_Spri ng_H00	i n_spri ng_H00	FIRST	1 MOVE ON WI P_to_assy2_H00
Box_Spri ng_H00	i n_spri ng_H00	UNGROUP RENAME Spr i ng_H00					
Spri ng_H00	i n_spri ng_H00		1	Spri ng_H00	Assy2_H00	JOIN	1
Rod_H00	Recei vi ng_Area	GROUP 50 AS Box_Rod_H00					
Box_Rod_H00	Recei vi ng_Area		1	Box_Rod_H00	i n_bl ank2	FIRST	1
Box_Rod_H00	i n_bl ank2	UNGROUP RENAME Rod_H00					
Rod_H00	i n_bl ank2		1	Rod_H00	Ms_Bl ank2, 2	FIRST	1
Rod_H00	Ms_Bl ank2	WAIT W(5. 67, 5. 25) SEC	1	Rod_H00	out_bl ank2	FIRST	1 GRAPHIC 2
Rod_H00	out_bl ank2	GROUP 50 AS Box_Rod_H00					
Box_Rod_H00	out_bl ank2		1	Box_Rod_H00	i n_pi e25_3	FIRST	1 MOVE FOR W(4. 45, 3. 15) SEC
Box_Rod_H00	i n_pi e25_3	UNGROUP RENAME Rod_H00 GRAPHIC 2					
Rod_H00	i n_pi e25_3		1	Rod_H00	Ms_Pi e25_3, 1	FIRST	1
Rod_H00	Ms_Pi e25_3	WAIT W(9. 92, 14. 8) SEC	1	Rod_H00	out_pi e25_3	FIRST	1 GRAPHIC 3
Rod_H00	out_pi e25_3	GROUP 50 AS Box_Rod_H00					
Box_Rod_H00	out_pi e25_3		1	Box_Rod_H00	i n_pi e25_2	FIRST	1 MOVE FOR W(3. 93, 3. 27) SEC
Box_Rod_H00	i n_pi e25_2	UNGROUP RENAME Rod_H00 GRAPHIC 3					
Rod_H00	i n_pi e25_2		1	Rod_H00	Ms_Pi e25_2, 1	FIRST	1

Rod_H00	Ms_Pie25_2	WAIT W(9.7, 16) SEC	1	Rod_H00	out_pie25_2	FIRST 1	GRAPHIC 3
Rod_H00	out_pie25_2	GROUP 50 AS Box_Rod_H00					
Box_Rod_H00	out_pie25_2		1	Box_Rod_H00	WIP	FIRST 1	MOVE ON pie25_2_to_WIP
Rod_H00	WIP	GROUP 50 AS Box_Rod_H00					
Box_Rod_H00	WIP		1	Box_Rod_H00	in_Rod_H00	FIRST 1	MOVE ON WIP_to_assy1_H00
Box_Rod_H00	in_Rod_H00	UNGROUP RENAME Rod_H00 GRAPHIC 3					
Rod_H00	in_Rod_H00		1	Rod_H00	Assy1_H00	JOIN 1	
Arm_H00	Receiving_Area	GROUP 30 AS Box_Arm_H00					
Box_Arm_H00	Receiving_Area		1	Box_Arm_H00	in_bend35	FIRST 1	MOVE FOR W(4.13, 4.43) SEC
Box_Arm_H00	in_bend35	UNGROUP RENAME Arm_H00					
Arm_H00	in_bend35	INC in_35	1	Arm_H00	Ms_Bend35_2	FIRST 1	DEC in_35
Arm_H00	Ms_Bend35_2	WAIT W(16.8, 19.4)SEC IF jml_arm_H00 < 1380 AND ruleroute_H00 = 0 THEN { ROUTE 1 } ELSE { ruleroute_H00 = 0 ROUTE 2 }					
			1	Arm_H00	out_bend35	FIRST 1	GRAPHIC 2
			2	Arm_H00	out_bend35	SEND 1	GRAPHIC 2
Arm_H00	out_bend35	GROUP 30 AS Box_Arm_H00					
Box_Arm_H00	out_bend35		1	Box_Arm_H00	in_blank2	FIRST 1	MOVE ON bend35_to_blank
Box_Arm_H00	in_blank2	UNGROUP RENAME Arm_H00 GRAPHIC 2					

Arm_H00	in_blank2	INC in_blank2	1	Arm_H00	Ms_Blank2, 1	FIRST 1	DEC in_blank2
Arm_H00	Ms_Blank2	WAIT W(11.1, 15.6) SEC IF jml_arm_H00 < 1380 AND ruleroute_H00 = 0 THEN { ROUTE 1 } ELSE { ruleroute_H00 = 0 ROUTE 2 } }					
Arm_H00	out_blank2	GROUP 30 AS Box_Arm_H00	1	Arm_H00	out_blank2	FIRST 1	GRAPHIC 3
Box_Arm_H00	out_blank2		2	Arm_H00	out_blank2	SEND 1	GRAPHIC 3
Box_Arm_H00	in_pie63_2	UNGROUP RENAME Arm_H00 GRAPHIC 3					
Box_Arm_H00	in_pie63_2	INC in_63_2	1	Box_Arm_H00	in_pie63_2	FIRST 1	MOVE ON blank_to_pie63_2
Arm_H00	in_pie63_2						
Arm_H00	Ms_Pie63_2	WAIT W(14.4, 27.2) SEC IF jml_arm_H00 < 1380 AND ruleroute_H00 = 0 THEN { ROUTE 1 } ELSE { ruleroute_H00 = 0 ROUTE 2 } }					
Arm_H00	out_pie63_2		1	Arm_H00	out_pie63_2	FIRST 1	GRAPHIC 4
Arm_H00	out_pie63_2		2	Arm_H00	out_pie63_2	SEND 1	GRAPHIC 4
Arm_H00	out_pie63_2	GROUP 30 AS Box_Arm_H00					
Box_Arm_H00	out_pie63_2		1	Box_Arm_H00	in_cut90_2	FIRST 1	MOVE FOR W(4.16, 3.52) SEC
Box_Arm_H00	in_cut90_2	UNGROUP RENAME Arm_H00 GRAPHIC 4					

```

Arm_H00      in_cut90_2      INC in_90_2
                                     1   Arm_H00      Ms_Cut90_2      FIRST 1  DEC in_90_2

Arm_H00      Ms_Cut90_2      WAIT W(17.1, 14.8) SEC
                                     IF jml_arm_H00 < 1380 AND ruleroute_H00 = 0 THEN
                                     {
                                     ROUTE 1
                                     }
                                     ELSE
                                     {
                                     ruleroute_H00 = 0
                                     ROUTE 2
                                     }
                                     1   Arm_H00      out_cut90_2      FIRST 1  GRAPHIC 5
                                     2   Arm_H00      out_cut90_2      SEND 1   GRAPHIC 5

Arm_H00      out_cut90_2      GROUP 30 AS Box_Arm_H00

Box_Arm_H00  out_cut90_2      1   Box_Arm_H00  WIP          FIRST 1  MOVE FOR W(8.22, 7.26) SEC

Arm_H00      WIP          GROUP 30 AS Box_Arm_H00

Box_Arm_H00  WIP          1   Box_Arm_H00  in_Arm_H00   FIRST 1  MOVE ON WIP_to_assy1_H00
Box_Arm_H00  in_Arm_H00      UNGROUP
                                     RENAME Arm_H00
                                     GRAPHIC 5

Arm_H00      in_Arm_H00      INC jml_arm_H00
                                     IF jml_arm_H00 >= 1380 THEN
                                     {
                                     ruleroute_H00 = 1
                                     henti_H00 = 1
                                     }
                                     1   Arm_H00      Assy1_H00      FIRST 1  DEC jml_arm_H00
(henti_H00 = 1) THEN
                                     IF (jml_arm_H00 = 690) AND
                                     {
                                     SEND 1 Arm_H00 TO out_cut90_2
                                     SEND 1 Arm_H00 TO out_pie63_2
                                     SEND 1 Arm_H00 TO out_blank2
                                     SEND 1 Arm_H00 TO out_bend35
                                     henti_H00 = 0
                                     }

```

```

Arm_H00      Assy1_H00      JOIN 1 Boss
              JOIN 1 Brake_shoe
              JOIN 1 Rod_H00
              WAIT W(25.6, 111) SEC
Pedal_H00    out_assy1_H00  GROUP 30 AS Box_Pedal_H00 1 Pedal_H00 out_assy1_H00 FIRST 1
Box_Pedal_H00 out_assy1_H00 1 Box_Pedal_H00 in_Pedal_H00 FIRST 1 MOVE FOR W(4.55, 3.3) SEC
Box_Pedal_H00 in_Pedal_H00 UNGROUP
              RENAME Pedal_H00
Pedal_H00    in_Pedal_H00 INC in_pedal H00 1 Pedal_H00 Assy2_H00 FIRST 1 DEC in_pedal H00
Pedal_H00    Assy2_H00 JOIN 1 Spring_H00
              JOIN 1 Swi tch_H00
              WAIT W(11.2, 37.8) SEC
              1 Pedal_H00 out_assy2_H00 FIRST 1 GRAPHI C 2
Pedal_H00    out_assy2_H00 GROUP 30 AS Box_Pedal_H00
Box_Pedal_H00 out_assy2_H00 1 Box_Pedal_H00 in_expand FIRST 1 MOVE ON assy2_H00_to_exp
Box_Pedal_H00 in_expand UNGROUP
              RENAME Pedal_H00
              GRAPHI C 2
Pedal_H00    in_expand INC in_ex 1 Pedal_H00 Ms_Expand FIRST 1 DEC in_ex
Pedal_H00    Ms_Expand WAIT W(7.44, 12.8) SEC
              1 Pedal_H00 out_expand FIRST 1 GRAPHI C 2
Pedal_H00    out_expand GROUP 30 AS Brake_pedal_H00
Brake_pedal_H00 out_expand 1 Brake_pedal_H00 Shi ppi ng_H00 FIRST 1 MOVE ON exp_to_Gd
Brake_pedal_H00 Shi ppi ng_H00 INC jml_H00 1 Brake_pedal_H00 EXI T SEND 1
pengi ri man Shi ppi ng SEND 34 Brake_pedal_XC TO Exi t
              SEND 26 Brake_pedal_H10 TO Exi t
              SEND 6 Brake_pedal_H00 TO Exi t
              IF jml_XC <= 34 THEN
              {
              kekurangan_XC = 34 - jml_XC
              SEND 15 Brake_pedal_XC TO Exi t
              total_kurang_XC = total_kurang_XC + (34 - jml_XC)

```

```

}

IF jml_H10 <= 26 THEN
{
kekurangan_H10 = 26 - jml_H10
SEND 13 Brake_pedal_H10 TO Exit
total_kurang_H10 = total_kurang_H10 + (26 - jml_H10)
}

IF jml_H00 <= 6 THEN
{
kekurangan_H00 = 6 - jml_H00
SEND 3 Brake_pedal_H00 TO Exit
total_kurang_H00 = total_kurang_H00 + (6 - jml_H00)
}

if total_kurang_XC < 0 then total_kurang_XC = 0
if total_kurang_H10 < 0 then total_kurang_H10 = 0
if total_kurang_H00 < 0 then total_kurang_H00 = 0
1 pengiriman EXIT

```

```

FIRST 1 DEC jml_XC, 34
DEC jml_H10, 26
DEC jml_H00, 6

```

```

if jml_XC < 0 then jml_XC = 0
if jml_H10 < 0 then jml_H10 = 0
if jml_H00 < 0 then jml_H00 = 0

```

* Arrivals *

Entity	Location	Qty each	First	Time	Occurrences	Frequency	Logic
Boss	WIP	4500	0		inf	7 hr	
Brake_shoe	Receiving_Area	2500	0		INF	7 hr	
Brake_shoe	WIP	500	0		1		
Arm_XC	Receiving_Area	1500	0		INF	7 hr	
Arm_XC	in_pi e63_1	150	0		1		
Arm_XC	in_cut90_1	120	0		1		
Arm_XC	WIP	600	0		1		
Pedal_XC	in_expand	150	0		1		
Rod_XC	Receiving_Area	1500	0		INF	7 hr	
Rod_XC	in_pi e25_1	90	0		1		
Rod_XC	WIP	500	0		1		


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Swi tch_XC  WIP          1500      0      INF      7 hr
Spring_XC  WIP          1500      0      inf      7 hr
Arm_H10    Recei vi ng_Area 1500      0      INF      7 hr
Arm_H10    in_bend100      120      0      1
Arm_H10    in_pi e63_3     90       0      1
Arm_H10    in_cut100       90       0      1
Arm_H10    WIP            660      0      1
Pedal_H10  in_expand       120      0      1
Rod_H10    Recei vi ng_Area 1500      0      INF      7 hr
Rod_H10    in_pi e25_3     200      0      1
Rod_H10    in_pi e25_2     150      0      1
Rod_H10    WIP            500      0      1
Swi tch_H10 WIP          1500      0      INF      7 hr
Spring_H10 WIP          1500      0      INF      7 hr
Arm_H00    Recei vi ng_Area 1500      0      INF      35 hr
Arm_H00    in_bl ank2      120      0      1
Arm_H00    in_pi e63_2     120      0      1
Arm_H00    in_cut90_2     90       0      1
Arm_H00    WIP            600      0      1
Pedal_H00  in_expand       120      0      1
Rod_H00    Recei vi ng_Area 1500      0      INF      35 hr
Rod_H00    in_pi e25_3     200      0      1
Rod_H00    in_pi e25_2     150      0      1
Rod_H00    WIP            600      0      1
Swi tch_H00 WIP          1500      0      INF      35 hr
Swi tch_H00 WIP          1000      0      1
Spring_H00 WIP          1500      0      INF      35 hr
Spring_H00 WIP          1000      0      1
pengi ri man Shi ppi ng 1          7 hr      INF      7 hr

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*****
*                               Variables (global)                               *
*****

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ID	Type	Initial value	Stats
kekurangan_XC	Integer	0	Time Series
kekurangan_H10	Integer	0	Time Series
kekurangan_H00	Integer	0	Time Series
jml_XC	Integer	0	Time Series
jml_H10	Integer	0	Time Series
jml_H00	Integer	0	Time Series
status_XC	Integer	0	Time Series
rul eroute_XC	Integer	0	Time Series
henti_XC	Integer	0	Time Series
status_H10	Integer	0	Time Series
rul eroute_H10	Integer	0	Time Series
henti_H10	Integer	0	Time Series

status_H00	Integer	0	Time Series
rul eroute_H00	Integer	0	Time Series
henti_H00	Integer	0	Time Series
jml_arm_XC	Integer	0	Time Series
jml_arm_H10	Integer	0	Time Series
jml_arm_H00	Integer	0	Time Series
total_kurang_XC	Integer	0	Time Series
total_kurang_H10	Integer	0	Time Series
total_kurang_H00	Integer	0	Time Series
hyd	Integer	0	Time Series
in_63_1	Integer	0	Time Series
in_90_1	Integer	0	Time Series
in_pedal XC	Integer	0	Time Series
in_ex	Integer	0	Time Series
in_35	Integer	0	Time Series
in_bend_100	Integer	0	Time Series
in_63_3	Integer	0	Time Series
in_cut_100	Integer	0	Time Series
in_pedal H10	Integer	0	Time Series
in_bl ank_2	Integer	0	Time Series
in_63_2	Integer	0	Time Series
in_90_2	Integer	0	Time Series
in_pedal H00	Integer	0	Time Series

OUTPUT SIMULASI AKTUAL

 General Report
 Output from D:\Lina's Document\TA\Aktual.MOD
 Date: Apr/21/2008 Time: 07:19:27 AM

Scenario : Normal Run
 Replication : 1 of 1
 Simulation Time : 154 hr

LOCATIONS

Location Name	Scheduled Hours	Capacity	Total Entries	Average Minutes Per Entry	Average Contents	Maximum Contents	Current Contents	% Util
Ms Forging	154	1	55000	0.09	0.58	1	0	58.18
Ms Blank1	154	1	33000	0.06	0.22	1	0	22.36
Ms Pie25 1	154	2	33090	0.26	0.93	2	0	46.60
Ms Hyd	154	2	33000	0.39	1.39	2	0	69.96
Ms Pie63 1	154	2	22440	0.82	2	2	2	100.00
Ms Cut90 1	154	1	22530	0.21	0.52	1	0	52.45
Ms Blank2	154	1	48121	0.11	0.57	1	1	57.69
Ms Pie25 2	154	2	41200	0.24	1.07	2	0	53.66
Ms Pie25 3	154	2	40900	0.22	1.01	2	0	50.62
Ms Bend35	154	2	23428	0.72	1.83	2	2	91.98
Ms Bend35 2	154	2	7500	0.31	0.25	2	0	12.71
Ms Bend100	154	1	23520	0.28	0.72	1	0	72.74
Ms Pie63 3	154	2	16950	1.09	1.99	2	2	99.99
Ms Cut100	154	1	17010	0.22	0.41	1	0	41.58
Ms Pie63 2	154	2	7740	0.43	0.36	2	0	18.34
Ms Cut90 2	154	1	7830	0.23	0.20	1	0	20.27
Assy1 XC. 1	154	1	7712	1.18	0.98	1	1	98.56
Assy1 XC. 2	154	1	7703	1.18	0.98	1	1	98.43
Assy1 XC. 3	154	1	7699	1.18	0.98	1	1	98.48
Assy1 XC	462	3	23114	1.18	0.98	69345	3	98.49
Assy1 H10. 1	154	1	5457	1.69	0.99	1	1	100.00
Assy1 H10. 2	154	1	5457	1.69	0.99	1	1	100.00
Assy1 H10. 3	154	1	5455	1.69	0.99	1	1	100.00
Assy1 H10	462	3	16369	1.69	0.99	49110	3	100.00
Assy1 H00. 1	154	1	2622	1.81	0.51	1	1	51.44
Assy1 H00. 2	154	1	2625	1.81	0.51	1	1	51.43
Assy1 H00. 3	154	1	2627	1.80	0.51	1	1	51.40
Assy1 H00	462	3	7874	1.81	0.51	23625	3	51.42

Assy2 XC	154	1	14973	0.61	0.99	1	1	99.87
Assy2 H10	154	1	16337	0.53	0.95	1	1	95.15
Assy2 H00	154	1	7839	0.60	0.51	1	1	51.06
Ms Expand	154	1	39443	0.20	0.85	1	1	85.46
Recei vi ng Area	154	999999	210500	0.00	0	50	0	0.00
WIP	154	999999	266624	0.00	0	50	0	0.00
in forging	154	999999	1100	124.57	14.83	50	0	0.00
in blank1	154	999999	660	48.44	3.46	30	0	0.00
in blank2	154	999999	1210	168.73	22.09	180	30	0.00
in pie25 1	154	999999	750	49.76	4.03	88	0	0.00
in pie25 2	154	999999	1118	42.35	5.12	298	0	0.00
in pie25 3	154	999999	1210	60.63	7.94	398	0	0.00
in Hyd	154	999999	1100	149.54	17.80	50	0	0.00
in bend35	154	999999	1350	1097.38	160.33	400	320	0.02
in bend100	154	999999	900	77.48	7.54	119	0	0.00
in cut100	154	999999	654	7.60	0.53	89	0	0.00
in cut90 1	154	999999	867	8.18	0.76	119	0	0.00
in cut90 2	154	999999	348	8.09	0.30	89	0	0.00
in pie63 1	154	999999	1250	1379.70	186.64	368	357	0.02
in pie63 2	154	999999	374	8.34	0.33	118	0	0.00
in pie63 3	154	999999	874	1379.96	130.52	223	222	0.01
in Arm XC	154	999999	771	122.24	10.20	45	1	0.00
in Rod XC	154	999999	671	1594.55	115.79	220	209	0.01
in Boss XC	154	999999	1100	1563.90	186.18	364	330	0.02
in Shoe XC	154	999999	515	512.18	28.54	62	53	0.00
in Arm H10	154	999999	589	609.69	38.86	53	44	0.00
in Rod H10	154	999999	677	2611.61	191.34	358	350	0.02
in Boss H10	154	999999	1100	2542.17	302.63	580	555	0.03
in Shoe H10	154	999999	383	695.68	28.83	62	56	0.00
in Arm H00	154	999999	281	243.24	7.39	38	19	0.00
in Rod H00	154	999999	169	482.40	8.82	31	12	0.00
in Boss H00	154	999999	1100	3608.80	429.62	861	838	0.04
in Shoe H00	154	999999	212	1290.83	29.61	61	55	0.00
in swi tch XC	154	999999	660	2741.98	195.85	375	361	0.02
in spr i ng XC	154	999999	660	2741.97	195.85	375	361	0.02
in Pedal XC	154	999999	770	1677.87	139.82	272	271	0.01
in swi tch H10	154	999999	660	2553.66	182.40	349	334	0.02
in spr i ng H10	154	999999	660	2553.66	182.40	349	334	0.02
in Pedal H10	154	999999	545	15.59	0.92	1	1	0.00
in swi tch H00	154	999999	170	833.01	15.32	50	14	0.00
in spr i ng H00	154	999999	170	833.01	15.32	50	14	0.00
in Pedal H00	154	999999	262	17.98	0.51	2	1	0.00
in expand	154	999999	1694	25.28	4.63	389	3	0.00
out forging	154	999999	55000	2.39	14.25	50	0	0.00
out blank1	154	999999	33000	1.53	5.46	50	0	0.00
out blank2	154	999999	48120	2.67	13.91	78	0	0.00
out pie25 1	154	999999	33090	9.14	32.76	50	40	0.00
out pie25 2	154	999999	41200	2.97	13.24	55	0	0.00
out pie25 3	154	999999	40900	2.80	12.39	51	0	0.00

out Hyd	154	999999	33000	2.84	10.15	30	0	0.00
out bend35	154	999999	30926	4.88	16.36	59	26	0.00
out bend100	154	999999	23520	4.78	12.17	30	0	0.00
out cut100	154	999999	17010	2.92	5.38	30	0	0.00
out pie63 1	154	999999	22438	6.11	14.84	30	28	0.00
out pie63 2	154	999999	7740	3.14	2.63	30	0	0.00
out pie63 3	154	999999	16948	8.21	15.07	30	28	0.00
out cut90 1	154	999999	22530	2.97	7.24	30	0	0.00
out cut90 2	154	999999	7830	3.47	2.94	30	0	0.00
out assy1 XC	154	999999	23111	5.66	14.17	30	11	0.00
out assy1 H10	154	999999	16366	8.17	14.47	30	16	0.00
out assy1 H00	154	999999	7871	8.76	7.46	30	11	0.00
out assy2 XC	154	999999	14972	8.93	14.48	30	2	0.00
out assy2 H10	154	999999	16336	7.79	13.78	30	16	0.00
out assy2 H00	154	999999	7838	8.71	7.39	30	8	0.00
out expand	154	999999	39442	2.90	12.38	30	22	0.00
Shi ppi ng XC	154	999999	503	10.28	0.56	23	0	0.00
Shi ppi ng H10	154	999999	547	10.17	0.60	24	0	0.00
Shi ppi ng H00	154	999999	264	2972.01	84.91	138	132	0.01
Shi ppi ng	154	1	22	0.00	0	1	0	0.00

LOCATION STATES BY PERCENTAGE (Multiple Capacity)

Location Name	Scheduled Hours	% Empty	% Partially Occupied	% Full	% Down
Ms Pie25 1	154	53.38	0.03	46.59	0.00
Ms Hyd	154	30.01	0.06	69.93	0.00
Ms Pie63 1	154	0.00	0.00	100.00	0.00
Ms Pie25 2	154	46.32	0.03	53.65	0.00
Ms Pie25 3	154	49.36	0.03	50.61	0.00
Ms Bend35	154	8.01	0.01	91.98	0.00
Ms Bend35 2	154	87.29	0.01	12.71	0.00
Ms Pie63 3	154	0.01	0.01	99.98	0.00
Ms Pie63 2	154	81.44	0.44	18.12	0.00
Receiving Area	154	100.00	0.00	0.00	0.00
WIP	154	100.00	0.00	0.00	0.00
in forging	154	41.85	58.15	0.00	0.00
in blank1	154	77.65	22.35	0.00	0.00
in blank2	154	42.34	57.66	0.00	0.00
in pie25 1	154	53.45	46.55	0.00	0.00
in pie25 2	154	46.39	53.61	0.00	0.00
in pie25 3	154	49.42	50.58	0.00	0.00
in Hyd	154	30.10	69.90	0.00	0.00
in bend35	154	8.03	91.97	0.00	0.00
in bend100	154	28.47	71.53	0.00	0.00

in cut100	154	59.53	40.47	0.00	0.00
in cut90 1	154	49.07	50.93	0.00	0.00
in cut90 2	154	80.36	19.64	0.00	0.00
in pie63 1	154	0.00	100.00	0.00	0.00
in pie63 2	154	82.65	17.35	0.00	0.00
in pie63 3	154	0.02	99.98	0.00	0.00
in Arm XC	154	3.83	96.17	0.00	0.00
in Rod XC	154	0.00	100.00	0.00	0.00
in Boss XC	154	0.00	100.00	0.00	0.00
in Shoe XC	154	0.00	100.00	0.00	0.00
in Arm H10	154	0.00	100.00	0.00	0.00
in Rod H10	154	0.00	100.00	0.00	0.00
in Boss H10	154	0.00	100.00	0.00	0.00
in Shoe H10	154	0.00	100.00	0.00	0.00
in Arm H00	154	48.62	51.38	0.00	0.00
in Rod H00	154	0.00	100.00	0.00	0.00
in Boss H00	154	0.00	100.00	0.00	0.00
in Shoe H00	154	0.00	100.00	0.00	0.00
in swi tch XC	154	0.00	100.00	0.00	0.00
in sprin g XC	154	0.00	100.00	0.00	0.00
in Pedal XC	154	0.13	99.87	0.00	0.00
in swi tch H10	154	0.00	100.00	0.00	0.00
in sprin g H10	154	0.00	100.00	0.00	0.00
in Pedal H10	154	8.00	92.00	0.00	0.00
in swi tch H00	154	0.00	100.00	0.00	0.00
in sprin g H00	154	0.00	100.00	0.00	0.00
in Pedal H00	154	49.69	50.31	0.00	0.00
in expand	154	15.24	84.76	0.00	0.00
out forgi ng	154	42.99	57.01	0.00	0.00
out blank1	154	78.08	21.92	0.00	0.00
out blank2	154	43.49	56.51	0.00	0.00
out pie25 1	154	0.95	99.05	0.00	0.00
out pie25 2	154	47.38	52.62	0.00	0.00
out pie25 3	154	50.39	49.61	0.00	0.00
out Hyd	154	32.35	67.65	0.00	0.00
out bend35	154	9.99	90.01	0.00	0.00
out bend100	154	29.04	70.96	0.00	0.00
out cut100	154	59.64	40.36	0.00	0.00
out pie63 1	154	3.28	96.72	0.00	0.00
out pie63 2	154	82.59	17.41	0.00	0.00
out pie63 3	154	2.41	97.59	0.00	0.00
out cut90 1	154	49.20	50.80	0.00	0.00
out cut90 2	154	80.41	19.59	0.00	0.00
out assy1 XC	154	5.89	94.11	0.00	0.00
out assy1 H10	154	3.53	96.47	0.00	0.00
out assy1 H00	154	50.25	49.75	0.00	0.00
out assy2 XC	154	3.46	96.54	0.00	0.00
out assy2 H10	154	8.03	91.97	0.00	0.00
out assy2 H00	154	50.64	49.36	0.00	0.00

out expand	154	17.41	82.59	0.00	0.00
Shi ppi ng XC	154	95.52	4.48	0.00	0.00
Shi ppi ng H10	154	94.22	5.78	0.00	0.00
Shi ppi ng H00	154	0.65	99.35	0.00	0.00

LOCATION STATES BY PERCENTAGE (Si ngl e Capaci ty/Tanks)

Locati on Name	Schedul ed Hours	% Operati on	% Setup	% Idle	% Wai ti ng	% Bl ocked	% Down
Ms Forgi ng	154	58.18	0.00	41.82	0.00	0.00	0.00
Ms Bl ank1	154	22.36	0.00	77.64	0.00	0.00	0.00
Ms Cut90 1	154	49.61	0.00	47.55	2.84	0.00	0.00
Ms Bl ank2	154	57.69	0.00	42.31	0.00	0.00	0.00
Ms Bend100	154	53.53	0.00	27.26	19.21	0.00	0.00
Ms Cut100	154	36.74	0.00	58.42	4.84	0.00	0.00
Ms Cut90 2	154	20.27	0.00	79.73	0.00	0.00	0.00
Assy1 XC. 1	154	98.56	0.00	1.44	0.00	0.00	0.00
Assy1 XC. 2	154	98.43	0.00	1.57	0.00	0.00	0.00
Assy1 XC. 3	154	98.48	0.00	1.52	0.00	0.00	0.00
Assy1 XC	462	98.49	0.00	1.51	0.00	0.00	0.00
Assy1 H10. 1	154	100.00	0.00	0.00	0.00	0.00	0.00
Assy1 H10. 2	154	100.00	0.00	0.00	0.00	0.00	0.00
Assy1 H10. 3	154	100.00	0.00	0.00	0.00	0.00	0.00
Assy1 H10	462	100.00	0.00	0.00	0.00	0.00	0.00
Assy1 H00. 1	154	51.44	0.00	48.56	0.00	0.00	0.00
Assy1 H00. 2	154	51.43	0.00	48.57	0.00	0.00	0.00
Assy1 H00. 3	154	51.40	0.00	48.60	0.00	0.00	0.00
Assy1 H00	462	51.42	0.00	48.58	0.00	0.00	0.00
Assy2 XC	154	99.87	0.00	0.13	0.00	0.00	0.00
Assy2 H10	154	95.15	0.00	4.85	0.00	0.00	0.00
Assy2 H00	154	51.06	0.00	48.94	0.00	0.00	0.00
Ms Expand	154	85.46	0.00	14.54	0.00	0.00	0.00
Shi ppi ng	154	0.00	0.00	100.00	0.00	0.00	0.00

FAI LED ARR I VALS

Enti ty Name	Locati on Name	Total Fai led
Boss	WI P	0
Brake shoe	Recei vi ng Area	0
Brake shoe	WI P	0
Arm XC	Recei vi ng Area	0
Arm XC	WI P	0
Arm XC	i n cut90 1	0

Arm XC	in pie63 1	0
Rod XC	Receiving Area	0
Rod XC	WIP	0
Rod XC	in pie25 1	0
Swi tch XC	WIP	0
Spring XC	WIP	0
Pedal XC	in expand	0
Arm H10	Receiving Area	0
Arm H10	WIP	0
Arm H10	in bend100	0
Arm H10	in cut100	0
Arm H10	in pie63 3	0
Rod H10	Receiving Area	0
Rod H10	WIP	0
Rod H10	in pie25 2	0
Rod H10	in pie25 3	0
Swi tch H10	WIP	0
Spring H10	WIP	0
Pedal H10	in expand	0
Arm H00	Receiving Area	0
Arm H00	WIP	0
Arm H00	in blank2	0
Arm H00	in cut90 2	0
Arm H00	in pie63 2	0
Rod H00	Receiving Area	0
Rod H00	WIP	0
Rod H00	in pie25 2	0
Rod H00	in pie25 3	0
Swi tch H00	WIP	0
Spring H00	WIP	0
Pedal H00	in expand	0
pengiri man	Shi pping	0

ENTITY ACTIVITY

Entity Name	Total Exits	Current Quantity In System	Average Minutes In System	Average Minutes In Move Logic	Average Minutes Wait For Res, etc.	Average Minutes In Operati on	Average Minutes Bl ocked
Boss	47357	56143	2163.97	0.18	0.00	0.00	2163.79
Brake shoe	47357	10643	799.59	0.48	2.37	0.09	796.64
Arm XC	0	12259	-	-	-	-	-
Rod XC	23114	11976	1703.14	0.50	10.43	0.31	1691.89
Swi tch XC	14973	19527	2737.02	0.28	0.00	0.00	2736.73
Spring XC	14973	19527	2737.02	0.28	0.00	0.00	2736.73
Pedal XC	15090	8171	2960.87	0.60	28.72	2.92	2928.61
Box Arm XC	3718	50	0.10	0.10	0.00	0.00	0.00

Box Rod XC	1991	30	0.16	0.16	0.00	0.00	0.00
Box Swi tch XC	660	30	0.28	0.28	0.00	0.00	0.00
Box Spring XC	660	30	0.28	0.28	0.00	0.00	0.00
Box Boss	3300	150	0.16	0.16	0.00	0.00	0.00
Box Shoe	2210	50	0.24	0.24	0.00	0.00	0.00
Box Arm H10	3817	50	0.33	0.33	0.00	0.00	0.00
Box Rod H10	2691	0	0.10	0.10	0.00	0.00	0.00
Box Swi tch H10	660	30	0.24	0.24	0.00	0.00	0.00
Box Spring H10	660	30	0.24	0.24	0.00	0.00	0.00
Box Arm H00	1293	0	0.11	0.11	0.00	0.00	0.00
Box Rod H00	623	0	0.08	0.08	0.00	0.00	0.00
Box Swi tch H00	170	0	0.20	0.20	0.00	0.00	0.00
Box Spring H00	170	0	0.20	0.20	0.00	0.00	0.00
Arm H10	0	19094	-	-	-	-	-
Rod H10	16369	18981	2754.85	0.40	7.49	0.53	2746.42
Swi tch H10	16337	18163	2549.64	0.24	0.00	0.00	2549.39
Spr ing H10	16337	18163	2549.64	0.24	0.00	0.00	2549.39
Pedal H10	16410	76	2807.82	1.97	38.79	3.47	2763.57
Arm H00	0	559	-	-	-	-	-
Rod H00	7874	576	727.64	0.30	7.42	0.51	719.40
Swi tch H00	7839	661	800.72	0.20	0.00	0.00	800.51
Spr ing H00	7839	661	800.72	0.20	0.00	0.00	800.51
Pedal H00	3960	4031	4082.27	0.83	31.15	3.50	4046.77
Box Pedal XC	1269	0	0.07	0.07	0.00	0.00	0.00
Box Pedal H10	1089	0	0.12	0.12	0.00	0.00	0.00
Box Pedal H00	523	0	0.12	0.12	0.00	0.00	0.00
Brake pedal XC	503	0	10.28	0.00	0.00	0.00	10.28
Brake pedal H10	547	0	10.29	0.12	0.00	0.00	10.17
Brake pedal H00	132	132	3308.70	0.12	0.00	0.00	3308.58
pengi ri man	22	0	0.00	0.00	0.00	0.00	0.00

ENTITY STATES BY PERCENTAGE

Entity Name	% In Move Logic	% Wait For Res, etc.	% In Operation	% Blocked
Boss	0.01	0.00	0.00	99.99
Brake shoe	0.06	0.30	0.01	99.63
Arm XC	-	-	-	-
Rod XC	0.03	0.61	0.02	99.34
Swi tch XC	0.01	0.00	0.00	99.99
Spr ing XC	0.01	0.00	0.00	99.99
Pedal XC	0.02	0.97	0.10	98.91
Box Arm XC	100.00	0.00	0.00	0.00
Box Rod XC	100.00	0.00	0.00	0.00
Box Swi tch XC	100.00	0.00	0.00	0.00
Box Spr ing XC	100.00	0.00	0.00	0.00

Box Boss	100.00	0.00	0.00	0.00
Box Shoe	100.00	0.00	0.00	0.00
Box Arm H10	100.00	0.00	0.00	0.00
Box Rod H10	100.00	0.00	0.00	0.00
Box Swi tch H10	100.00	0.00	0.00	0.00
Box Spring H10	100.00	0.00	0.00	0.00
Box Arm H00	100.00	0.00	0.00	0.00
Box Rod H00	100.00	0.00	0.00	0.00
Box Swi tch H00	100.00	0.00	0.00	0.00
Box Spring H00	100.00	0.00	0.00	0.00
Arm H10	-	-	-	-
Rod H10	0.01	0.27	0.02	99.69
Swi tch H10	0.01	0.00	0.00	99.99
Spring H10	0.01	0.00	0.00	99.99
Pedal H10	0.07	1.38	0.12	98.42
Arm H00	-	-	-	-
Rod H00	0.04	1.02	0.07	98.87
Swi tch H00	0.03	0.00	0.00	99.97
Spring H00	0.03	0.00	0.00	99.97
Pedal H00	0.02	0.76	0.09	99.13
Box Pedal XC	100.00	0.00	0.00	0.00
Box Pedal H10	100.00	0.00	0.00	0.00
Box Pedal H00	100.00	0.00	0.00	0.00
Brake pedal XC	0.00	0.00	0.00	100.00
Brake pedal H10	1.20	0.00	0.00	98.80
Brake pedal H00	0.00	0.00	0.00	100.00
pengi ri man	-	-	-	-

VARI ABLES

Vari abl e Name	Total Changes	Average Minutes Per Change	Mi ni mum Val ue	Maxi mum Val ue	Current Val ue	Average Val ue
kekurangan XC	22	420.00	0	12	11	10.63
kekurangan H10	20	462.00	0	2	2	1.13
kekurangan H00	0	0.00	0	0	0	0
jml XC	547	16.89	-12	26	0	11.40
jml H10	586	15.76	-2	27	0	12.46
jml H00	286	32.30	0	138	132	84.91
status XC	0	0.00	0	0	0	0
ruleroute XC	11	27.67	0	1	0	1.07
henti XC	9	62.96	0	1	0	0.02
status H10	0	0.00	0	0	0	0
ruleroute H10	58	138.58	0	1	0	5.09
henti H10	43	197.28	0	1	0	0.28
status H00	0	0.00	0	0	0	0
ruleroute H00	0	0.00	0	0	0	0

henti H00	0	0.00	0	0	0	0
jml arm XC	46244	0.19	0	1327	16	291.83
jml arm H10	34039	0.27	0	1571	1301	1151.46
jml arm H00	16304	0.56	0	1111	556	214.45
total kurang XC	22	420.00	0	245	245	115.63
total kurang H10	20	462.00	0	25	25	11.36
total kurang H00	0	0.00	0	0	0	0
hyd	66000	0.13	0	1498	0	523.93
in 63 1	55590	0.16	0	11014	10710	5577.38
in 90 1	45060	0.20	0	119	0	11.29
in pedal XC	38073	0.24	0	8135	8127	4180.21
in ex	78953	0.11	0	395	67	79.14
in 35	71428	0.12	0	11981	9572	4795.99
in bend 100	47040	0.19	0	1800	0	210.93
in 63 3	40560	0.22	0	6662	6660	3897.73
in cut 100	34020	0.27	0	90	0	8.19
in pedal H10	32687	0.28	0	30	13	13.81
in blank 2	15240	0.60	0	1620	0	323.19
in 63 2	15480	0.59	0	118	0	2.69
in 90 2	15660	0.58	0	101	0	3.22
in pedal H00	15699	0.58	0	35	21	7.90

LAMPIRAN 6

- **INPUT SIMULASI USULAN**
- **OUTPUT SIMULASI USULAN**

INPUT SIMULASI USULAN

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*           Formatted Listing of Model :
*           D: \Li na' s Document \TA \Usul an. MOD
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Time Units:           Minutes
Distance Units:      Feet
Initializati on Logic:

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*****
*
*           Locations
*
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Name	Cap	Units	Stats	Rules	Cost
Ms_Forging	1	1	Time Series	Oldest,	
Ms_Blank1	1	1	Time Series	Oldest,	
Ms_Pie25_1	2	1	Time Series	Oldest,	
Ms_Hyd	2	1	Time Series	Oldest,	
Ms_Pie63_1	2	1	Time Series	Oldest,	
Ms_Cut90_1	1	1	Time Series	Oldest,	
Ms_Blank2	1	1	Time Series	Oldest,	
Ms_Pie25_2	2	1	Time Series	Oldest,	
Ms_Pie25_3	2	1	Time Series	Oldest,	
Ms_Bend35	2	1	Time Series	Oldest,	
Ms_Bend35_2	2	1	Time Series	Oldest,	
Ms_Bend100	1	1	Time Series	Oldest,	
Ms_Pie63_3	2	1	Time Series	Oldest,	
Ms_Cut100	1	1	Time Series	Oldest,	
Ms_Pie63_2	2	1	Time Series	Oldest,	
Ms_Cut90_2	1	1	Time Series	Oldest,	
Assy1_XC	1	3	Time Series	Oldest,	First
Assy1_XC.1	1	1	Time Series	Oldest,	
Assy1_XC.2	1	1	Time Series	Oldest,	
Assy1_XC.3	1	1	Time Series	Oldest,	
Assy1_H10	1	3	Time Series	Oldest,	First
Assy1_H10.1	1	1	Time Series	Oldest,	
Assy1_H10.2	1	1	Time Series	Oldest,	
Assy1_H10.3	1	1	Time Series	Oldest,	
Assy1_H00	1	3	Time Series	Oldest,	First

Assy1_H00.1	1	1	Time Series Oldest,	,
Assy1_H00.2	1	1	Time Series Oldest,	,
Assy1_H00.3	1	1	Time Series Oldest,	,
Assy2_XC	1	1	Time Series Oldest,	,
Assy2_H10	1	1	Time Series Oldest,	,
Assy2_H00	1	1	Time Series Oldest,	,
Ms_Expand	1	1	Time Series Oldest,	,
Receiving_Area	INF	1	Time Series Oldest,	,
WIP	INF	1	Time Series Oldest,	,
in_forging	INF	1	Time Series Oldest,	,
in_blank1	INF	1	Time Series Oldest,	,
in_blank2	INF	1	Time Series Oldest,	,
in_pie25_1	INF	1	Time Series Oldest,	,
in_pie25_2	INF	1	Time Series Oldest,	,
in_pie25_3	INF	1	Time Series Oldest,	,
in_Hyd	INF	1	Time Series Oldest,	,
in_bend35	INF	1	Time Series Oldest,	,
in_bend100	INF	1	Time Series Oldest,	,
in_cut100	INF	1	Time Series Oldest,	,
in_cut90_1	INF	1	Time Series Oldest,	,
in_cut90_2	INF	1	Time Series Oldest,	,
in_pie63_1	INF	1	Time Series Oldest,	,
in_pie63_2	INF	1	Time Series Oldest,	,
in_pie63_3	INF	1	Time Series Oldest,	,
in_Arm_XC	INF	1	Time Series Oldest,	,
in_Rod_XC	INF	1	Time Series Oldest,	,
in_Boss_XC	INF	1	Time Series Oldest,	,
in_Shoe_XC	INF	1	Time Series Oldest,	,
in_Arm_H10	INF	1	Time Series Oldest,	,
in_Rod_H10	INF	1	Time Series Oldest,	,
in_Boss_H10	INF	1	Time Series Oldest,	,
in_Shoe_H10	INF	1	Time Series Oldest,	,
in_Arm_H00	INF	1	Time Series Oldest,	,
in_Rod_H00	INF	1	Time Series Oldest,	,
in_Boss_H00	INF	1	Time Series Oldest,	,
in_Shoe_H00	INF	1	Time Series Oldest,	,
in_switch_XC	INF	1	Time Series Oldest,	,
in_spring_XC	INF	1	Time Series Oldest,	,
in_Pedal_XC	INF	1	Time Series Oldest,	,
in_switch_H10	INF	1	Time Series Oldest,	,
in_spring_H10	INF	1	Time Series Oldest,	,
in_Pedal_H10	INF	1	Time Series Oldest,	,
in_switch_H00	INF	1	Time Series Oldest,	,
in_spring_H00	INF	1	Time Series Oldest,	,
in_Pedal_H00	INF	1	Time Series Oldest,	,
in_expand	INF	1	Time Series Oldest,	,
out_forging	INF	1	Time Series Oldest,	,
out_blank1	INF	1	Time Series Oldest,	,
out_blank2	INF	1	Time Series Oldest,	,

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out_pi e25_1    INF 1      Time Series Oldest, ,
out_pi e25_2    INF 1      Time Series Oldest, ,
out_pi e25_3    INF 1      Time Series Oldest, ,
out_Hyd         INF 1      Time Series Oldest, ,
out_bend35     INF 1      Time Series Oldest, ,
out_bend100    INF 1      Time Series Oldest, ,
out_cut100     INF 1      Time Series Oldest, ,
out_pi e63_1    INF 1      Time Series Oldest, ,
out_pi e63_2    INF 1      Time Series Oldest, ,
out_pi e63_3    INF 1      Time Series Oldest, ,
out_cut90_1    INF 1      Time Series Oldest, ,
out_cut90_2    INF 1      Time Series Oldest, ,
out_assy1_XC   INF 1      Time Series Oldest, ,
out_assy1_H10  INF 1      Time Series Oldest, ,
out_assy1_H00  INF 1      Time Series Oldest, ,
out_assy2_XC   INF 1      Time Series Oldest, ,
out_assy2_H10  INF 1      Time Series Oldest, ,
out_assy2_H00  INF 1      Time Series Oldest, ,
out_expand     INF 1      Time Series Oldest, ,
Shi pping_XC   INF 1      Time Series Oldest, ,
Shi pping_H10  INF 1      Time Series Oldest, ,
Shi pping_H00  INF 1      Time Series Oldest, ,
Shi pping      1 1      Time Series Oldest, ,

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*                                     *
*                               Entities                               *
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Name	Speed (fpm)	Stats	Cost
Boss	150	Time Series	
Brake_shoe	150	Time Series	
Arm_XC	150	Time Series	
Rod_XC	150	Time Series	
Swi tch_XC	150	Time Series	
Spring_XC	150	Time Series	
Pedal_XC	150	Time Series	
Box_Arm_XC	150	Time Series	
Box_Rod_XC	150	Time Series	
Box_Swi tch_XC	150	Time Series	
Box_Spri ng_XC	150	Time Series	
Box_Boss	150	Time Series	
Box_Shoe	150	Time Series	
Box_Arm_H10	150	Time Series	
Box_Rod_H10	150	Time Series	
Box_Swi tch_H10	150	Time Series	
Box_Spri ng_H10	150	Time Series	
Box_Arm_H00	150	Time Series	

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Box_Rod_H00      150      Time Series
Box_Switch_H00  150      Time Series
Box_Spring_H00  150      Time Series
Arm_H10          150      Time Series
Rod_H10          150      Time Series
Switch_H10      150      Time Series
Spring_H10      150      Time Series
Pedal_H10       150      Time Series
Arm_H00         150      Time Series
Rod_H00         150      Time Series
Switch_H00      150      Time Series
Spring_H00      150      Time Series
Pedal_H00       150      Time Series
Box_Pedal_XC    150      Time Series
Box_Pedal_H10   150      Time Series
Box_Pedal_H00   150      Time Series
Brake_pedal_XC  150      Time Series
Brake_pedal_H10 150      Time Series
Brake_pedal_H00 150      Time Series
pengiri man     150      Time Series

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*                                     *
*                               Path Networks                               *
*                                     *
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Name	Type	T/S	From	To	BI	Dist/Time	Speed Factor
WIP_to_assy1_XC	Passing	Time	N1	N2	Bi	W(14.9, 12) sec	
WIP_to_assy1_H10	Passing	Time	N1	N2	Bi	W(8.21, 12.6) sec	
WIP_to_assy1_H00	Passing	Time	N1	N2	Bi	W(4.8, 7.19) sec	
Forg_to_WIP	Passing	Time	N1	N2	Bi	W(12, 16.3) sec	
assy2_XC_to_exp	Passing	Time	N1	N2	Bi	W(8.56, 7.35) sec	
assy2_H10_to_exp	Passing	Time	N1	N2	Bi	W(5.21, 10.2) sec	
assy2_H00_to_exp	Passing	Time	N1	N2	Bi	W(7.92, 12.4) sec	
WIP_to_assy2_XC	Passing	Time	N1	N2	Bi	W(18.4, 17.8) sec	
WIP_to_assy2_H10	Passing	Time	N1	N2	Bi	W(21.1, 15.3) sec	
WIP_to_assy2_H00	Passing	Time	N1	N2	Bi	W(8.95, 13) sec	
pie25_1_to_WIP	Passing	Time	N1	N2	Bi	W(14, 12.7) sec	
exp_to_gudang	Passing	Time	N1	N2	Bi	W(7.85, 7.9) sec	
pie25_2_to_WIP	Passing	Time	N1	N2	Bi	W(8.98, 7.4) sec	
bend35_to_blank	Passing	Time	N1	N2	Bi	W(4.03, 5.64) sec	
blank_to_pie63_2	Passing	Time	N1	N2	Bi	W(7.52, 9.86) sec	


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*****
*                                     Interfaces                                     *
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Net	Node	Location
WIP_to_assy1_XC	N1	WIP
	N2	in_Arm_XC
	N2	in_Rod_XC
	N2	in_Boss_XC
	N2	in_Shoe_XC
WIP_to_assy1_H10	N1	WIP
	N2	in_Arm_H10
	N2	in_Rod_H10
	N2	in_Boss_H10
	N2	in_Shoe_H10
WIP_to_assy1_H00	N1	WIP
	N2	in_Arm_H00
	N2	in_Rod_H00
	N2	in_Boss_H00
	N2	in_Shoe_H00
Forg_to_WIP	N1	out_forging
	N2	WIP
assy2_XC_to_exp	N1	out_assy2_XC
	N2	in_expand
assy2_H10_to_exp	N1	out_assy2_H10
	N2	in_expand
assy2_H00_to_exp	N1	out_assy2_H00
	N2	in_expand
WIP_to_assy2_XC	N1	WIP
	N2	in_swit ch_XC
	N2	in_spring_XC
	N2	in_Pedal_XC
	N2	in_Pedal_XC
WIP_to_assy2_H10	N1	WIP
	N2	in_swit ch_H10
	N2	in_spring_H10
	N2	in_Pedal_H10
	N2	in_Pedal_H10
WIP_to_assy2_H00	N1	WIP
	N2	in_swit ch_H00
	N2	in_spring_H00
	N2	in_Pedal_H00
	N2	in_Pedal_H00
pie25_1_to_WIP	N1	out_pie25_1
	N2	WIP
exp_to_gudang	N1	out_expand
	N2	Shipping_XC
	N2	Shipping_H10
	N2	Shipping_H00
	N2	Shipping_H00
pie25_2_to_WIP	N1	out_pie25_2
	N2	WIP

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bend35_to_blink N1      out_bend35
                  N2      in_blink2
blink_to_pie63_2 N1      out_blink2
                  N2      in_pie63_2

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*                                     *
*                               Processing                               *
*                                     *
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		Process		Routing			
Entity	Location	Operation	Blk	Output	Destination	Rule	Move Logic
Brake_shoe	Receiving_Area	GROUP 50 AS Box_Shoe					
Box_Shoe	Receiving_Area		1	Box_Shoe	in_forging	FIRST 1	MOVE FOR W(5.46, 3.01) SEC
Box_Shoe	in_forging	UNGROUP RENAME Brake_shoe					
Brake_shoe	in_forging		1	Brake_shoe	Ms_Forging	FIRST 1	
Brake_shoe	Ms_Forging	WAIT W(5.9, 6.33) SEC	1	Brake_shoe	out_forging	FIRST 1	GRAPHIC 2
Brake_shoe	out_forging	GROUP 50 AS Box_Shoe					
Box_Shoe	out_forging		1	Box_Shoe	WIP	FIRST 1	MOVE ON Forg_to_WIP
Brake_shoe	WIP	GROUP 50 AS Box_Shoe					
Box_Shoe	WIP		1	Box_Shoe	in_Shoe_XC	MOST 1	MOVE ON WIP_to_assy1_XC
				Box_Shoe	in_Shoe_H10	MOST	MOVE ON WIP_to_assy1_H10
				Box_Shoe	in_Shoe_H00	MOST	MOVE ON WIP_to_assy1_H00
Box_Shoe	in_Shoe_XC	UNGROUP RENAME Brake_shoe GRAPHIC 2					
Brake_shoe	in_Shoe_XC		1	Brake_shoe	Assy1_XC	JOIN 1	
Box_Shoe	in_Shoe_H10	UNGROUP RENAME Brake_shoe GRAPHIC 2					
Brake_shoe	in_Shoe_H10		1	Brake_shoe	Assy1_H10	JOIN 1	
Box_Shoe	in_Shoe_H00	UNGROUP RENAME Brake_shoe GRAPHIC 2					

Brake_shoe Boss	i n_Shoe_H00 WIP	GROUP 30 AS Box_Boss	1	Brake_shoe	Assy1_H00	JOIN 1	
Box_Boss	WIP		1	Box_Boss	i n_Boss_XC	MOST 1	MOVE ON WIP_to_assy1_XC
				Box_Boss	i n_Boss_H10	MOST	MOVE ON WIP_to_assy1_H10
				Box_Boss	i n_Boss_H00	MOST	MOVE ON WIP_to_assy1_H00
Box_Boss	i n_Boss_XC	UNGROUP RENAME Boss					
Boss Box_Boss	i n_Boss_XC i n_Boss_H10	UNGROUP RENAME Boss	1	Boss	Assy1_XC	JOIN 1	
Boss Box_Boss	i n_Boss_H10 i n_Boss_H00	UNGROUP RENAME Boss	1	Boss	Assy1_H10	JOIN 1	
Boss Swi tch_XC	i n_Boss_H00 WIP	GROUP 50 AS Box_Swi tch_XC	1	Boss	Assy1_H00	JOIN 1	
Box_Swi tch_XC	WIP		1	Box_Swi tch_XC	i n_swi tch_XC	FIRST 1	MOVE ON WIP_to_assy2_XC
Box_Swi tch_XC	i n_swi tch_XC	UNGROUP RENAME Swi tch_XC					
Swi tch_XC Spri ng_XC	i n_swi tch_XC WIP	GROUP 50 AS Box_Spri ng_XC	1	Swi tch_XC	Assy2_XC	JOIN 1	
Box_Spri ng_XC	WIP		1	Box_Spri ng_XC	i n_spri ng_XC	FIRST 1	MOVE ON WIP_to_assy2_XC
Box_Spri ng_XC	i n_spri ng_XC	UNGROUP RENAME Spri ng_XC					
Spri ng_XC Rod_XC	i n_spri ng_XC Recei vi ng_Area	GROUP 50 AS Box_Rod_XC	1	Spri ng_XC	Assy2_XC	JOIN 1	
Box_Rod_XC	Recei vi ng_Area		1	Box_Rod_XC	i n_bl ank1	FIRST 1	MOVE FOR W(3. 85, 3. 75) SEC
Box_Rod_XC	i n_bl ank1	UNGROUP RENAME Rod_XC					
Rod_XC Rod_XC	i n_bl ank1 Ms_Bl ank1	WAIT W(3. 68, 4. 16) SEC	1	Rod_XC	Ms_Bl ank1	FIRST 1	

			1	Rod_XC	out_blink1	FIRST 1	GRAPHIC 2
Rod_XC Box_Rod_XC	out_blink1 out_blink1	GROUP 50 AS Box_Rod_XC	1	Box_Rod_XC	in_pie25_1	FIRST 1	MOVE FOR W(5.83, 3.44) SEC
Box_Rod_XC	in_pie25_1	UNGROUP RENAME Rod_XC GRAPHIC 2					
Rod_XC Rod_XC	in_pie25_1 Ms_Pie25_1	WAIT W(8.97, 16.5) SEC	1	Rod_XC	Ms_Pie25_1	FIRST 1	
			1	Rod_XC	out_pie25_1	FIRST 1	GRAPHIC 3
Rod_XC Box_Rod_XC	out_pie25_1 out_pie25_1	GROUP 50 AS Box_Rod_XC	1	Box_Rod_XC	WIP	FIRST 1	MOVE ON pie25_1_to_WIP
Rod_XC Box_Rod_XC Box_Rod_XC	WIP WIP in_Rod_XC	GROUP 50 AS Box_Rod_XC	1	Box_Rod_XC	in_Rod_XC	FIRST 1	MOVE ON WIP_to_assy1_XC
		UNGROUP RENAME Rod_XC GRAPHIC 3					
Rod_XC Arm_XC	in_Rod_XC Receiving_Area	GROUP 30 AS Box_Arm_XC	1	Rod_XC	Assy1_XC	JOIN 1	
Box_Arm_XC	Receiving_Area		1	Box_Arm_XC	in_Hyd	FIRST 1	MOVE FOR W(4.67, 3.32) SEC
Box_Arm_XC	in_Hyd	UNGROUP RENAME Arm_XC					
Arm_XC	in_Hyd	INC hyd					
			1	Arm_XC	Ms_Hyd	FIRST 1	DEC hyd
Arm_XC	Ms_Hyd	WAIT W(16, 24.3) SEC IF jml_pedal_XC < buffer_XC AND ruleroute_XC = 0 THEN { ROUTE 1 } ELSE { ruleroute_XC = 0 ROUTE 2 }					
			1	Arm_XC	out_Hyd	FIRST 1	GRAPHIC 2
			2	Arm_XC	out_Hyd	SEND 1	GRAPHIC 2

Arm_XC	out_Hyd	GROUP 30 AS Box_Arm_XC					
Box_Arm_XC	out_Hyd		1	Box_Arm_XC	in_pi e63_1	FIRST 1	MOVE FOR W(6.8, 4.11) SEC
Box_Arm_XC	in_pi e63_1	UNGROUP RENAME Arm_XC GRAPHIC 2					
Arm_XC	in_pi e63_1	INC in_63_1	1	Arm_XC	Ms_Pi e63_1	FIRST 1	DEC in_63_1
Arm_XC	Ms_Pi e63_1	WAIT W(23, 25.4) SEC IF jml_pedal_XC < buffer_XC AND ruleroute_XC = 0 THEN { ROUTE 1 } ELSE { ruleroute_XC = 0 ROUTE 2 }					
			1	Arm_XC	out_pi e63_1	FIRST 1	GRAPHIC 3
			2	Arm_XC	out_pi e63_1	SEND 1	GRAPHIC 3
Arm_XC Box_Arm_XC	out_pi e63_1 out_pi e63_1	GROUP 30 AS Box_Arm_XC	1	Box_Arm_XC	in_cut90_1	FIRST 1	MOVE FOR W(5.06, 3.62) SEC
Box_Arm_XC	in_cut90_1	UNGROUP RENAME Arm_XC GRAPHIC 3					
Arm_XC	in_cut90_1	INC in_90_1	1	Arm_XC	Ms_Cut90_1	FIRST 1	DEC in_90_1
Arm_XC	Ms_Cut90_1	WAIT W(5.58, 13.2) SEC IF jml_pedal_XC < buffer_XC AND ruleroute_XC = 0 THEN { ROUTE 1 } ELSE { ruleroute_XC = 0 ROUTE 2 }					
			1	Arm_XC	out_cut90_1	FIRST 1	GRAPHIC 4

```

                2   Arm_XC      out_cut90_1  SEND 1   GRAPHIC 4
Arm_XC      out_cut90_1  GROUP 30 AS Box_Arm_XC
Box_Arm_XC  out_cut90_1      1   Box_Arm_XC  WIP      FIRST 1   MOVE FOR W(14.6, 6.65) SEC
Arm_XC      WIP      GROUP 30 AS Box_Arm_XC
Box_Arm_XC  WIP      1   Box_Arm_XC  in_Arm_XC  FIRST 1   MOVE ON WIP_to_assy1_XC
Box_Arm_XC  in_Arm_XC  UNGROUP
                RENAME Arm_XC
                GRAPHIC 4
Arm_XC      in_Arm_XC  INC jml_arm_XC
                1   Arm_XC      Assy1_XC   FIRST 1   DEC jml_arm_XC
Arm_XC      Assy1_XC  JOIN 1 Rod_XC
                JOIN 1 Boss
                JOIN 1 Brake_shoe
                WAIT W(15.3, 73.3) SEC
                IF jml_pedal_XC < buffer_XC AND ruleroute_XC = 0 THEN
                {
                ROUTE 1
                }
                ELSE
                {
                ruleroute_XC = 0
                ROUTE 2
                }
                1   Pedal_XC      out_assy1_XC  FIRST 1
                2   Pedal_XC      out_assy1_XC  SEND 1
Pedal_XC      out_assy1_XC  GROUP 30 AS Box_Pedal_XC
Box_Pedal_XC  out_assy1_XC  1   Box_Pedal_XC  in_Pedal_XC  FIRST 1   MOVE FOR W(4.58, 2.98) SEC
Box_Pedal_XC  in_Pedal_XC  UNGROUP
                RENAME Pedal_XC
Pedal_XC      in_Pedal_XC  INC jml_pedal_XC
                IF jml_pedal_XC >= buffer_XC THEN
                {
                ruleroute_XC = 1
                henti_XC = 1
                }
                1   Pedal_XC      Assy2_XC   FIRST 1   DEC jml_pedal_XC
                IF (jml_pedal_XC = buffer_XC/3) AND
(henti_XC = 1) THEN
                {

```

```

SEND 1 Arm_XC TO out_cut90_1
SEND 1 Arm_XC TO out_pie63_1
SEND 1 Arm_XC TO out_Hyd
SEND 3 Pedal_XC TO out_assy1_XC
henti_XC = 0
ruleroute_XC = 0
}

```

```

Pedal_XC      Assy2_XC      JOIN 1 Spring_XC
                JOIN 1 Swi tch_XC
                WAIT W(11.1, 38.7) SEC
                1      Pedal_XC      out_assy2_XC  FIRST 1  GRAPHIC 2

Pedal_XC      out_assy2_XC  GROUP 30 AS Box_Pedal_XC
Box_Pedal_XC  out_assy2_XC      1      Box_Pedal_XC  i n_expand  FIRST 1  MOVE ON assy2_XC_to_exp

Box_Pedal_XC  i n_expand    UNGROUP
                RENAME Pedal_XC
                GRAPHIC 2

Pedal_XC      i n_expand    INC i n_ex
                1      Pedal_XC      Ms_Expand    FIRST 1  DEC i n_ex

Pedal_XC      Ms_Expand    WAIT W(7.44, 12.8) SEC
                1      Pedal_XC      out_expand    FIRST 1  GRAPHIC 2

Pedal_XC      out_expand    GROUP 30 AS Brake_pedal_XC
Brake_pedal_XC  out_expand    1      Brake_pedal_XC  Shi ppi ng_XC  FIRST 1
Brake_pedal_XC  Shi ppi ng_XC  INC j ml_XC
                1      Brake_pedal_XC  EXIT          SEND 1

Swi tch_H10    WIP          GROUP 50 AS Box_Swi tch_H10
                1      Box_Swi tch_H10  i n_swi tch_H10  FIRST 1  MOVE ON WIP_to_assy2_H10

Box_Swi tch_H10  WIP          1      Box_Swi tch_H10  i n_swi tch_H10  FIRST 1  MOVE ON WIP_to_assy2_H10

Box_Swi tch_H10  i n_swi tch_H10  UNGROUP
                RENAME Swi tch_H10

Swi tch_H10    i n_swi tch_H10  1      Swi tch_H10    Assy2_H10    JOIN 1
Spri ng_H10    WIP          GROUP 50 AS Box_Spri ng_H10

Box_Spri ng_H10  WIP          1      Box_Spri ng_H10  i n_spri ng_H10  FIRST 1  MOVE ON WIP_to_assy2_H10

Box_Spri ng_H10  i n_spri ng_H10  UNGROUP
                RENAME Spri ng_H10

Spri ng_H10    i n_spri ng_H10  1      Spri ng_H10    Assy2_H10    JOIN 1
Rod_H10        Recei vi ng_Area  GROUP 50 AS Box_Rod_H10

Box_Rod_H10    Recei vi ng_Area  1      Box_Rod_H10    i n_bl ank2    FIRST 1

```

Box_Rod_H10	in_blink2	UNGROUP RENAME Rod_H10					
Rod_H10	in_blink2		1	Rod_H10	Ms_Blink2, 3	FIRST 1	
Rod_H10	Ms_Blink2	WAIT W(6.73, 5.52) SEC	1	Rod_H10	out_blink2	FIRST 1	GRAPHIC 2
Rod_H10	out_blink2	GROUP 50 AS Box_Rod_H10					
Box_Rod_H10	out_blink2		1	Box_Rod_H10	in_pie25_3	FIRST 1	MOVE FOR W(4.45, 3.15) SEC
Box_Rod_H10	in_pie25_3	UNGROUP RENAME Rod_H10 GRAPHIC 2					
Rod_H10	in_pie25_3		1	Rod_H10	Ms_Pie25_3, 2	FIRST 1	
Rod_H10	Ms_Pie25_3	WAIT W(7.01, 14.6) SEC	1	Rod_H10	out_pie25_3	FIRST 1	GRAPHIC 3
Rod_H10	out_pie25_3	GROUP 50 AS Box_Rod_H10					
Box_Rod_H10	out_pie25_3		1	Box_Rod_H10	in_pie25_2	FIRST 1	MOVE FOR W(3.93, 3.27) SEC
Box_Rod_H10	in_pie25_2	UNGROUP RENAME Rod_H10 GRAPHIC 3					
Rod_H10	in_pie25_2		1	Rod_H10	Ms_Pie25_2, 2	FIRST 1	
Rod_H10	Ms_Pie25_2	WAIT W(9.69, 15) SEC	1	Rod_H10	out_pie25_2	FIRST 1	GRAPHIC 3
Rod_H10	out_pie25_2	GROUP 50 AS Box_Rod_H10					
Box_Rod_H10	out_pie25_2		1	Box_Rod_H10	WIP	FIRST 1	MOVE ON pie25_2_to_WIP
Rod_H10	WIP	GROUP 50 AS Box_Rod_H10					
Box_Rod_H10	WIP		1	Box_Rod_H10	in_Rod_H10	FIRST 1	MOVE ON WIP_to_assy1_H10
Box_Rod_H10	in_Rod_H10	UNGROUP RENAME Rod_H10 GRAPHIC 3					
Rod_H10	in_Rod_H10		1	Rod_H10	Assy1_H10	JOIN 1	
Arm_H10	Receiving_Area	GROUP 30 AS Box_Arm_H10					
Box_Arm_H10	Receiving_Area		1	Box_Arm_H10	in_bend35	FIRST 1	MOVE FOR W(4.13, 4.43) SEC
Box_Arm_H10	in_bend35	UNGROUP RENAME Arm_H10					

Arm_H10	in_bend35	INC in_35	1	Arm_H10	Ms_Bend35_2	FIRST 1	DEC in_35
Arm_H10	Ms_Bend35_2	WAIT W(16.8, 19.4) SEC IF jml_arm_H10 < buffer_H10 AND ruleroute_H10 = 0 THEN { ROUTE 1 } ELSE { ruleroute_H10 = 0 ROUTE 2 }	1	Arm_H10	out_bend35	FIRST 1	GRAPHIC 2
			2	Arm_H10	out_bend35	SEND 1	GRAPHIC 2
Arm_H10	out_bend35	GROUP 30 AS Box_Arm_H10					
Box_Arm_H10	out_bend35		1	Box_Arm_H10	in_bend100	FIRST 1	MOVE FOR W(8.74, 78) SEC
Box_Arm_H10	in_bend100	UNGROUP RENAME Arm_H10 GRAPHIC 2					
Arm_H10	in_bend100	INC in_bend_100	1	Arm_H10	Ms_Bend100	FIRST 1	DEC in_bend_100
Arm_H10	Ms_Bend100	WAIT W(5.34, 13.7) SEC IF jml_arm_H10 < buffer_H10 AND ruleroute_H10 = 0 THEN { ROUTE 1 } ELSE { ruleroute_H10 = 0 ROUTE 2 }	1	Arm_H10	out_bend100	FIRST 1	GRAPHIC 3
			2	Arm_H10	out_bend100	SEND 1	GRAPHIC 3
Arm_H10	out_bend100	GROUP 30 AS Box_Arm_H10					
Box_Arm_H10	out_bend100		1	Box_Arm_H10	in_pi e63_3	FIRST 1	MOVE FOR W(2.28, 3.77) SEC
Box_Arm_H10	in_pi e63_3	UNGROUP RENAME Arm_H10 GRAPHIC 3					

Arm_H10	in_pi e63_3	INC in_63_3	1	Arm_H10	Ms_Pi e63_3	FIRST 1	DEC in_63_3
Arm_H10	Ms_Pi e63_3	WAIT W(18.1, 25) SEC IF jml_arm_H10 < buffer_H10 AND ruleroute_H10 = 0 THEN { ROUTE 1 } ELSE { ruleroute_H10 = 0 ROUTE 2 }					
			1	Arm_H10	out_pi e63_3	FIRST 1	GRAPHIC 4
			2	Arm_H10	out_pi e63_3	SEND 1	GRAPHIC 4
Arm_H10	out_pi e63_3	GROUP 30 AS Box_Arm_H10					
Box_Arm_H10	out_pi e63_3		1	Box_Arm_H10	in_cut100	FIRST 1	MOVE FOR W(5.81, 2.56) SEC
Box_Arm_H10	in_cut100	UNGROUP RENAME Arm_H10 GRAPHIC 4					
Arm_H10	in_cut100	INC in_cut_100	1	Arm_H10	Ms_Cut100	FIRST 1	DEC in_cut_100
Arm_H10	Ms_Cut100	WAIT W(5.88, 12.9) SEC IF jml_arm_H10 < buffer_H10 AND ruleroute_H10 = 0 THEN { ROUTE 1 } ELSE { ruleroute_H10 = 0 ROUTE 2 }					
			1	Arm_H10	out_cut100	FIRST 1	GRAPHIC 5
			2	Arm_H10	out_cut100	SEND 1	GRAPHIC 5
Arm_H10	out_cut100	GROUP 30 AS Box_Arm_H10					
Box_Arm_H10	out_cut100		1	Box_Arm_H10	WIP	FIRST 1	MOVE FOR W(7.62, 7.15) SEC
Arm_H10	WIP	GROUP 30 AS Box_Arm_H10					
Box_Arm_H10	WIP		1	Box_Arm_H10	in_Arm_H10	FIRST 1	MOVE ON WIP_to_assy1_H10

```

Box_Arm_H10    in_Arm_H10    UNGROUP
                RENAME Arm_H10
                GRAPHIC 5

Arm_H10        in_Arm_H10    INC jml_arm_H10
                IF jml_arm_H10 >= buffer_H10 THEN
                {
                ruleroute_H10 = 1
                henti_H10 = 1
                }

(henti_H10 = 1) THEN

                1    Arm_H10    Assy1_H10    FIRST 1    IF (jml_arm_H10 = buffer_H10/3) AND
                {
                SEND 1 Arm_H10 TO out_cut100
                SEND 1 Arm_H10 TO out_pi e63_3
                SEND 1 Arm_H10 TO out_bend100
                SEND 1 Arm_H10 TO out_bend35
                henti_H10 = 0
                }
                DEC jml_arm_H10

Arm_H10        Assy1_H10    JOIN 1 Boss
                JOIN 1 Brake_shoe
                JOIN 1 Rod_H10
                WAIT W(41.4, 103) SEC
                1    Pedal_H10    out_assy1_H10    FIRST 1

Pedal_H10      out_assy1_H10    GROUP 30 AS Box_Pedal_H10

Box_Pedal_H10 out_assy1_H10    1    Box_Pedal_H10    in_Pedal_H10    FIRST 1    MOVE FOR W(6.47, 5.9) SEC

Box_Pedal_H10 in_Pedal_H10    UNGROUP
                RENAME Pedal_H10

Pedal_H10      in_Pedal_H10    INC in_pedal_H10
                1    Pedal_H10    Assy2_H10    FIRST 1    DEC in_pedal_H10

Pedal_H10      Assy2_H10    JOIN 1 Spring_H10
                JOIN 1 Switch_H10
                WAIT W(17.5, 33.3) SEC
                1    Pedal_H10    out_assy2_H10    FIRST 1    GRAPHIC 2

Pedal_H10      out_assy2_H10    GROUP 30 AS Box_Pedal_H10

Box_Pedal_H10 out_assy2_H10    1    Box_Pedal_H10    in_expand    FIRST 1    MOVE ON assy2_H10_to_exp
Box_Pedal_H10 in_expand
                UNGROUP
                RENAME Pedal_H10
                GRAPHIC 2

```

Pedal_H10	in_expand	INC in_ex	1	Pedal_H10	Ms_Expand	FIRST 1	DEC in_ex
Pedal_H10	Ms_Expand	WAIT W(7.44, 12.8) SEC	1	Pedal_H10	out_expand	FIRST 1	GRAPHIC 2
Pedal_H10	out_expand	GROUP 30 AS Brake_pedal_H10					
Brake_pedal_H10	out_expand		1	Brake_pedal_H10	Shi ppi ng_H10	FIRST 1	MOVE ON exp_to_gudang
Brake_pedal_H10	Shi ppi ng_H10	INC jml_H10	1	Brake_pedal_H10	EXIT	SEND 1	
Swi tch_H00	WIP	GROUP 50 AS Box_Swi tch_H00					
Box_Swi tch_H00	WIP		1	Box_Swi tch_H00	in_swi tch_H00	FIRST 1	MOVE ON WIP_to_assy2_H00
Box_Swi tch_H00	in_swi tch_H00	UNGROUP RENAME Swi tch_H00					
Swi tch_H00	in_swi tch_H00		1	Swi tch_H00	Assy2_H00	JOIN 1	
Spri ng_H00	WIP	GROUP 50 AS Box_Spri ng_H00					
Box_Spri ng_H00	WIP		1	Box_Spri ng_H00	in_spri ng_H00	FIRST 1	MOVE ON WIP_to_assy2_H00
Box_Spri ng_H00	in_spri ng_H00	UNGROUP RENAME Spri ng_H00					
Spri ng_H00	in_spri ng_H00		1	Spri ng_H00	Assy2_H00	JOIN 1	
Rod_H00	Recei vi ng_Area	GROUP 50 AS Box_Rod_H00					
Box_Rod_H00	Recei vi ng_Area		1	Box_Rod_H00	in_bl ank2	FIRST 1	
Box_Rod_H00	in_bl ank2	UNGROUP RENAME Rod_H00					
Rod_H00	in_bl ank2		1	Rod_H00	Ms_Bl ank2, 2	FIRST 1	
Rod_H00	Ms_Bl ank2	WAIT W(5.67, 5.25) SEC	1	Rod_H00	out_bl ank2	FIRST 1	GRAPHIC 2
Rod_H00	out_bl ank2	GROUP 50 AS Box_Rod_H00					
Box_Rod_H00	out_bl ank2		1	Box_Rod_H00	in_pi e25_3	FIRST 1	MOVE FOR W(4.45, 3.15) SEC
Box_Rod_H00	in_pi e25_3	UNGROUP RENAME Rod_H00 GRAPHIC 2					
Rod_H00	in_pi e25_3		1	Rod_H00	Ms_Pi e25_3, 1	FIRST 1	
Rod_H00	Ms_Pi e25_3	WAIT W(9.92, 14.8) SEC	1	Rod_H00	out_pi e25_3	FIRST 1	GRAPHIC 3
Rod_H00	out_pi e25_3	GROUP 50 AS Box_Rod_H00					

Box_Rod_H00	out_pi e25_3		1	Box_Rod_H00	in_pi e25_2	FIRST 1	MOVE FOR W(3.93, 3.27) SEC
Box_Rod_H00	in_pi e25_2	UNGROUP RENAME Rod_H00 GRAPHIC 3					
Rod_H00	in_pi e25_2		1	Rod_H00	Ms_Pi e25_2, 1	FIRST 1	
Rod_H00	Ms_Pi e25_2	WAIT W(9.7, 16) SEC	1	Rod_H00	out_pi e25_2	FIRST 1	GRAPHIC 3
Rod_H00	out_pi e25_2	GROUP 50 AS Box_Rod_H00					
Box_Rod_H00	out_pi e25_2		1	Box_Rod_H00	WIP	FIRST 1	MOVE ON pi e25_2_to_WIP
Rod_H00	WIP	GROUP 50 AS Box_Rod_H00					
Box_Rod_H00	WIP		1	Box_Rod_H00	in_Rod_H00	FIRST 1	MOVE ON WIP_to_assy1_H00
Box_Rod_H00	in_Rod_H00	UNGROUP RENAME Rod_H00 GRAPHIC 3					
Rod_H00	in_Rod_H00		1	Rod_H00	Assy1_H00	JOIN 1	
Arm_H00	Receiv ing_Area	GROUP 30 AS Box_Arm_H00					
Box_Arm_H00	Receiv ing_Area		1	Box_Arm_H00	in_bend35	FIRST 1	MOVE FOR W(4.13, 4.43) SEC
Box_Arm_H00	in_bend35	UNGROUP RENAME Arm_H00					
Arm_H00	in_bend35	INC in_35	1	Arm_H00	Ms_Bend35	FIRST 1	DEC in_35
Arm_H00	Ms_Bend35	WAIT W(16.8, 19.4)SEC IF jml_arm_H00 < buffer_H00 AND ruleroute_H00 = 0 THEN { ROUTE 1 } ELSE { ruleroute_H00 = 0 ROUTE 2 }					
			1	Arm_H00	out_bend35	FIRST 1	GRAPHIC 2
			2	Arm_H00	out_bend35	SEND 1	GRAPHIC 2
Arm_H00	out_bend35	GROUP 30 AS Box_Arm_H00					

Box_Arm_H00	out_bend35		1	Box_Arm_H00	in_blink2	FIRST 1	MOVE ON bend35_to_blink
Box_Arm_H00	in_blink2	UNGROUP RENAME Arm_H00 GRAPHIC 2					
Arm_H00	in_blink2	INC in_blink2	1	Arm_H00	Ms_Blink2, 1	FIRST 1	DEC in_blink2
Arm_H00	Ms_Blink2	WAIT W(11.1, 15.6) SEC IF jml_arm_H00 < buffer_H00 AND ruleroute_H00 = 0 THEN { ROUTE 1 } ELSE { ruleroute_H00 = 0 ROUTE 2 }					
Arm_H00	out_blink2	GROUP 30 AS Box_Arm_H00	1 2	Arm_H00 Arm_H00	out_blink2 out_blink2	FIRST 1 SEND 1	GRAPHIC 3 GRAPHIC 3
Box_Arm_H00	out_blink2		1	Box_Arm_H00	in_pie63_2	FIRST 1	MOVE ON blink_to_pie63_2
Box_Arm_H00	in_pie63_2	UNGROUP RENAME Arm_H00 GRAPHIC 3					
Arm_H00	in_pie63_2	INC in_63_2	1	Arm_H00	Ms_Pie63_2	FIRST 1	DEC in_63_2
Arm_H00	Ms_Pie63_2	WAIT W(14.4, 27.2) SEC IF jml_arm_H00 < buffer_H00 AND ruleroute_H00 = 0 THEN { ROUTE 1 } ELSE { ruleroute_H00 = 0 ROUTE 2 }					
			1	Arm_H00	out_pie63_2	FIRST 1	GRAPHIC 4
			2	Arm_H00	out_pie63_2	SEND 1	GRAPHIC 4

Arm_H00	out_pie63_2	GROUP 30 AS Box_Arm_H00					
Box_Arm_H00	out_pie63_2		1	Box_Arm_H00	in_cut90_2	FIRST 1	MOVE FOR W(4.16, 3.52) SEC
Box_Arm_H00	in_cut90_2	UNGROUP RENAME Arm_H00 GRAPHIC 4					
Arm_H00	in_cut90_2	INC in_90_2	1	Arm_H00	Ms_Cut90_2	FIRST 1	DEC in_90_2
Arm_H00	Ms_Cut90_2	WAIT W(17.1, 14.8) SEC IF jml_arm_H00 < buffer_H00 AND ruleroute_H00 = 0 THEN { ROUTE 1 } ELSE { ruleroute_H00 = 0 ROUTE 2 }					
			1	Arm_H00	out_cut90_2	FIRST 1	GRAPHIC 5
			2	Arm_H00	out_cut90_2	SEND 1	GRAPHIC 5
Arm_H00	out_cut90_2	GROUP 30 AS Box_Arm_H00					
Box_Arm_H00	out_cut90_2		1	Box_Arm_H00	WIP	FIRST 1	MOVE FOR W(8.22, 7.26) SEC
Arm_H00	WIP	GROUP 30 AS Box_Arm_H00					
Box_Arm_H00	WIP		1	Box_Arm_H00	in_Arm_H00	FIRST 1	MOVE ON WIP_to_assy1_H00
Box_Arm_H00	in_Arm_H00	UNGROUP RENAME Arm_H00 GRAPHIC 5					
Arm_H00	in_Arm_H00	INC jml_arm_H00 IF jml_arm_H00 >= buffer_H00 THEN { ruleroute_H00 = 1 henti_H00 = 1 }					
			1	Arm_H00	Assy1_H00	FIRST 1	DEC jml_arm_H00 IF (jml_arm_H00 = buffer_H00/3) AND { SEND 1 Arm_H00 TO out_cut90_2
(henti_H00 = 1) THEN							

```

SEND 1 Arm_H00 TO out_pi e63_2
SEND 1 Arm_H00 TO out_bl ank2
SEND 1 Arm_H00 TO out_bend35
henti_H00 = 0
}

```

```

Arm_H00      Assy1_H00      JOIN 1 Boss
              JOIN 1 Brake_shoe
              JOIN 1 Rod_H00
              WAIT W(25.6, 111) SEC
Pedal_H00    out_assy1_H00  GROUP 30 AS Box_Pedal_H00      1 Pedal_H00      out_assy1_H00  FIRST 1
Box_Pedal_H00 out_assy1_H00      1 Box_Pedal_H00  in_Pedal_H00  FIRST 1  MOVE FOR W(4.55, 3.3) SEC
Box_Pedal_H00 in_Pedal_H00      UNGROUP
              RENAME Pedal_H00
Pedal_H00    in_Pedal_H00  INC in_pedal H00      1 Pedal_H00      Assy2_H00      FIRST 1  DEC in_pedal H00
Pedal_H00    Assy2_H00      JOIN 1 Spring_H00
              JOIN 1 Switch_H00
              WAIT W(11.2, 37.8) SEC
              1 Pedal_H00      out_assy2_H00  FIRST 1  GRAPHIC 2
Pedal_H00    out_assy2_H00  GROUP 30 AS Box_Pedal_H00
Box_Pedal_H00 out_assy2_H00      1 Box_Pedal_H00  in_expand      FIRST 1  MOVE ON assy2_H00_to_exp
Box_Pedal_H00 in_expand      UNGROUP
              RENAME Pedal_H00
              GRAPHIC 2
Pedal_H00    in_expand      INC in_ex      1 Pedal_H00      Ms_Expand      FIRST 1  DEC in_ex
Pedal_H00    Ms_Expand      WAIT W(7.44, 12.8) SEC
              1 Pedal_H00      out_expand      FIRST 1  GRAPHIC 2
Pedal_H00    out_expand      GROUP 30 AS Brake_pedal_H00
Brake_pedal_H00 out_expand      1 Brake_pedal_H00 Shi ppi ng_H00  FIRST 1  MOVE ON exp_to_gudang
Brake_pedal_H00 Shi ppi ng_H00  INC j ml_H00      1 Brake_pedal_H00 EXIT      SEND 1
pengiri man  Shi ppi ng      SEND 34 Brake_pedal_XC TO Exit
              SEND 26 Brake_pedal_H10 TO Exit

```



```

SEND 6 Brake_pedal_H00 TO Exit

IF jml_XC < 34 THEN
{
kekurangan_XC = 34 - jml_XC
SEND 15 Brake_pedal_XC TO Exit
total_kurang_XC = total_kurang_XC + (34 - jml_XC)
}

IF jml_H10 < 26 THEN
{
kekurangan_H10 = 26 - jml_H10
SEND 13 Brake_pedal_H10 TO Exit
total_kurang_H10 = total_kurang_H10 + (26 - jml_H10)
}

IF jml_H00 < 6 THEN
{
kekurangan_H00 = 6 - jml_H00
SEND 3 Brake_pedal_H00 TO Exit
total_kurang_H00 = total_kurang_H00 + (6 - jml_H00)
}

if total_kurang_XC < 0 then total_kurang_XC = 0
if total_kurang_H10 < 0 then total_kurang_H10 = 0
if total_kurang_H00 < 0 then total_kurang_H00 = 0
1 pengiriman EXIT

```

```

FIRST 1 DEC jml_XC, 34
DEC jml_H10, 26
DEC jml_H00, 6

if jml_XC < 0 then jml_XC = 0
if jml_H10 < 0 then jml_H10 = 0
if jml_H00 < 0 then jml_H00 = 0

```

* Arrivals *

Entity	Location	Qty each	First Time	Occurrences	Frequency	Logic
Boss	WIP	4500	0	INF	7 hr	
Brake_shoe	Receiving Area	2500	0	INF	7 hr	
Brake_shoe	WIP	500	0	1		
Arm_XC	Receiving Area	1500	0	INF	7 hr	
Arm_XC	in_pie63_1	150	0	1		

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Arm_XC      in_cut90_1    120      0      1
Arm_XC      WIP          600      0      1
Pedal_XC    in_expand    150      0      1
Rod_XC      Receiving_Area 1500     0      INF      7 hr
Rod_XC      in_pie25_1   90       0      1
Rod_XC      WIP          500      0      1
Swi_tch_XC WIP          1500     0      INF      7 hr
Spring_XC   WIP          1500     0      inf      7 hr
Arm_H10     Receiving_Area 1500     0      INF      7 hr
Arm_H10     in_bend100   120      0      1
Arm_H10     in_pie63_3   90       0      1
Arm_H10     in_cut100    90       0      1
Arm_H10     WIP          660      0      1
Pedal_H10   in_expand    120      0      1
Rod_H10     Receiving_Area 1500     0      INF      7 hr
Rod_H10     in_pie25_3   200      0      1
Rod_H10     in_pie25_2   150      0      1
Rod_H10     WIP          500      0      1
Swi_tch_H10 WIP          1500     0      INF      7 hr
Spring_H10 WIP          1500     0      INF      7 hr
Arm_H00     Receiving_Area 1500     1      INF      35 hr
Arm_H00     in_blank2    120      0      1
Arm_H00     in_pie63_2   120      0      1
Arm_H00     in_cut90_2   90       0      1
Arm_H00     WIP          600      0      1
Pedal_H00   in_expand    120      0      1
Rod_H00     Receiving_Area 1500     0      INF      35 hr
Rod_H00     in_pie25_3   200      0      1
Rod_H00     in_pie25_2   150      0      1
Rod_H00     WIP          600      0      1
Swi_tch_H00 WIP          1500     0      INF      35 hr
Swi_tch_H00 WIP          1000     0      1
Spring_H00 WIP          1500     0      INF      35 hr
Spring_H00 WIP          1000     0      1
pengiriman Shipment      1        7 hr    INF      7 hr

```

```

*****
*                               Variables (global)                               *
*****

```

ID	Type	Initial value	Stats
kekurangan_XC	Integer	0	Time Series
kekurangan_H10	Integer	0	Time Series
kekurangan_H00	Integer	0	Time Series
jml_XC	Integer	0	Time Series
jml_H10	Integer	0	Time Series
jml_H00	Integer	0	Time Series

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status_XC      Integer      0      Time Series
rul eroute_XC  Integer      0      Time Series
henti_XC       Integer      0      Time Series
status_H10     Integer      0      Time Series
rul eroute_H10 Integer      0      Time Series
henti_H10     Integer      0      Time Series
status_H00     Integer      0      Time Series
rul eroute_H00 Integer      0      Time Series
henti_H00     Integer      0      Time Series
jml _pedal_XC  Integer      0      Time Series
jml _arm_H10   Integer      0      Time Series
jml _arm_H00   Integer      0      Time Series
jml _arm_XC    Integer      0      Time Series
total _kurang_XC Integer      0      Time Series
total _kurang_H10 Integer      0      Time Series
total _kurang_H00 Integer      0      Time Series
hyd            Integer      0      Time Series
in_63_1       Integer      0      Time Series
in_90_1       Integer      0      Time Series
in_35         Integer      0      Time Series
in_bend_100   Integer      0      Time Series
in_63_3       Integer      0      Time Series
in_cut_100    Integer      0      Time Series
in_bl ank_2   Integer      0      Time Series
in_63_2       Integer      0      Time Series
in_90_2       Integer      0      Time Series
in_ex         Integer      0      Time Series
in_pedal H10  Integer      0      Time Series
in_pedal H00  Integer      0      Time Series

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```

*****
*                                     *
*                               Macros                               *
*                                     *
*****

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ID          Text
-----
buffer_XC   90
buffer_H10  90
buffer_H00  60

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OUTPUT SIMULASI USULAN

 General Report
 Output from D:\Lina's Document\TA\Usulan 5.MOD
 Date: Apr/18/2008 Time: 10:44:55 AM

Scenario : Normal Run
 Replication : 1 of 1
 Simulation Time : 154 hr

LOCATIONS

Location Name	Scheduled Hours	Capacity	Total Entries	Average Minutes Per Entry	Average Contents	Maximum Contents	Current Contents	% Util
Ms Forging	154	1	55000	0.09	0.58	1	0	58.23
Ms Blank1	154	1	33000	0.06	0.22	1	0	22.32
Ms Pie25 1	154	2	33090	0.26	0.93	2	0	46.62
Ms Hyd	154	2	15066	1.22	2	2	2	100.00
Ms Pie63 1	154	2	14297	1.29	2	2	2	100.00
Ms Cut90 1	154	1	14400	0.31	0.48	1	0	48.91
Ms Blank2	154	1	48080	0.12	0.66	1	1	66.11
Ms Pie25 2	154	2	41200	0.24	1.07	2	0	53.64
Ms Pie25 3	154	2	40900	0.22	1.01	2	0	50.65
Ms Bend35	154	2	7500	0.53	0.43	2	0	21.64
Ms Bend35 2	154	2	22047	0.83	2	2	2	100.00
Ms Bend100	154	1	22140	0.32	0.76	1	0	76.81
Ms Pie63 3	154	2	15677	1.17	2	2	2	100.00
Ms Cut100	154	1	15750	0.22	0.38	1	0	38.28
Ms Pie63 2	154	2	7229	1.92	1.50	2	2	75.28
Ms Cut90 2	154	1	7290	0.29	0.22	1	0	22.98
Assy1 XC. 1	154	1	5007	1.83	0.99	1	0	99.46
Assy1 XC. 2	154	1	4998	1.83	0.99	1	0	99.44
Assy1 XC. 3	154	1	4995	1.83	0.99	1	0	99.46
Assy1 XC	462	3	15000	1.83	0.99	45003	0	99.45
Assy1 H10. 1	154	1	5460	1.69	0.99	1	1	100.00
Assy1 H10. 2	154	1	5453	1.69	0.99	1	1	100.00
Assy1 H10. 3	154	1	5456	1.69	0.99	1	1	100.00
Assy1 H10	462	3	16369	1.69	0.99	49110	3	100.00
Assy1 H00. 1	154	1	2616	1.81	0.51	1	1	51.31
Assy1 H00. 2	154	1	2615	1.81	0.51	1	1	51.26
Assy1 H00. 3	154	1	2621	1.81	0.51	1	1	51.36

Assy1 H00	462	3	7852	1.81	0.51	23559	3	51.31
Assy2 XC	154	1	14966	0.61	0.99	1	1	99.87
Assy2 H10	154	1	16338	0.53	0.95	1	1	95.22
Assy2 H00	154	1	7814	0.60	0.51	1	1	51.03
Ms Expand	154	1	39401	0.20	0.85	1	1	85.31
Recei vi ng Area	154	999999	210500	0.00	0	50	0	0.00
WIP	154	999999	266293	0.00	0	50	0	0.00
in forging	154	999999	1100	124.68	14.84	50	0	0.00
in blank1	154	999999	660	48.34	3.45	30	0	0.00
in blank2	154	999999	1210	180.29	23.60	180	32	0.00
in pie25 1	154	999999	750	49.78	4.04	88	0	0.00
in pie25 2	154	999999	1118	42.57	5.15	298	0	0.00
in pie25 3	154	999999	1210	60.35	7.90	398	0	0.00
in Hyd	154	999999	1100	2680.94	319.16	619	598	0.03
in bend35	154	999999	1350	1715.29	250.61	442	366	0.03
in bend100	154	999999	854	68.88	6.36	119	0	0.00
in cut100	154	999999	612	58.08	3.84	89	0	0.00
in cut90 1	154	999999	596	10.41	0.67	119	0	0.00
in cut90 2	154	999999	330	102.24	3.65	89	0	0.00
in pie63 1	154	999999	652	262.20	18.50	148	31	0.00
in pie63 2	154	999999	372	206.26	8.30	118	16	0.00
in pie63 3	154	999999	828	991.91	88.88	219	219	0.01
in Arm XC	154	999999	500	275.19	14.89	30	0	0.00
in Rod XC	154	999999	671	2734.23	198.55	379	371	0.02
in Boss XC	154	999999	1166	2781.82	351.03	688	666	0.04
in Shoe XC	154	999999	410	1279.04	56.75	115	110	0.01
in Arm H10	154	999999	547	43.73	2.58	22	2	0.00
in Rod H10	154	999999	677	2608.91	191.15	358	350	0.02
in Boss H10	154	999999	1208	2676.01	349.85	688	663	0.03
in Shoe H10	154	999999	435	1194.23	56.22	115	108	0.01
in Arm H00	154	999999	263	39.41	1.12	20	2	0.00
in Rod H00	154	999999	169	491.46	8.98	31	12	0.00
in Boss H00	154	999999	926	3553.32	356.10	688	665	0.04
in Shoe H00	154	999999	265	1984.67	56.91	114	108	0.01
in swit ch XC	154	999999	660	2744.23	196.01	375	361	0.02
in spring XC	154	999999	660	2744.23	196.01	375	361	0.02
in Pedal XC	154	999999	500	42.73	2.31	4	2	0.00
in swit ch H10	154	999999	660	2553.55	182.39	349	334	0.02
in spring H10	154	999999	660	2553.55	182.39	349	334	0.02
in Pedal H10	154	999999	545	15.60	0.92	1	1	0.00
in swit ch H00	154	999999	170	841.71	15.48	50	14	0.00
in spring H00	154	999999	170	841.70	15.48	50	14	0.00
in Pedal H00	154	999999	261	18.03	0.50	2	1	0.00
in expand	154	999999	1692	24.67	4.51	389	2	0.00
out forging	154	999999	55000	2.39	14.26	50	0	0.00
out blank1	154	999999	33000	1.53	5.46	50	0	0.00
out blank2	154	999999	48079	2.85	14.86	77	19	0.00
out pie25 1	154	999999	33090	9.15	32.77	50	40	0.00
out pie25 2	154	999999	41200	2.95	13.17	52	0	0.00

out pi e25 3	154	999999	40900	2.80	12.42	51	0	0.00
out Hyd	154	999999	15064	8.64	14.09	30	4	0.00
out bend35	154	999999	29545	5.28	16.89	59	25	0.00
out bend100	154	999999	22140	4.48	10.75	30	0	0.00
out cut100	154	999999	15750	2.88	4.92	30	0	0.00
out pi e63 1	154	999999	14295	9.43	14.59	30	15	0.00
out pi e63 2	154	999999	7227	27.35	21.39	30	27	0.00
out pi e63 3	154	999999	15675	8.26	14.02	30	15	0.00
out cut90 1	154	999999	14400	4.65	7.26	30	0	0.00
out cut90 2	154	999999	7290	3.46	2.73	30	0	0.00
out assy1 XC	154	999999	15000	5.69	9.23	30	0	0.00
out assy1 H10	154	999999	16366	8.18	14.50	30	16	0.00
out assy1 H00	154	999999	7849	8.72	7.41	30	19	0.00
out assy2 XC	154	999999	14965	8.93	14.47	30	25	0.00
out assy2 H10	154	999999	16337	7.80	13.80	30	17	0.00
out assy2 H00	154	999999	7813	8.73	7.38	30	13	0.00
out expand	154	999999	39400	2.89	12.36	30	10	0.00
Shi ppi ng XC	154	999999	503	10.32	0.56	23	0	0.00
Shi ppi ng H10	154	999999	547	10.22	0.60	24	0	0.00
Shi ppi ng H00	154	999999	263	2958.09	84.19	137	131	0.01
Shi ppi ng	154	1	22	0.00	0	1	0	0.00

LOCATION STATES BY PERCENTAGE (Mul ti ple Capaci ty)

Locati on Name	Schedul ed Hours	% Empty	% Partially Occupied	% Full	% Down
Ms Pi e25 1	154	53.36	0.04	46.60	0.00
Ms Hyd	154	0.00	0.00	100.00	0.00
Ms Pi e63 1	154	0.00	0.00	100.00	0.00
Ms Pi e25 2	154	46.35	0.02	53.63	0.00
Ms Pi e25 3	154	49.34	0.03	50.63	0.00
Ms Bend35	154	78.00	0.71	21.29	0.00
Ms Bend35 2	154	0.00	0.00	100.00	0.00
Ms Pi e63 3	154	0.00	0.00	100.00	0.00
Ms Pi e63 2	154	0.00	49.44	50.56	0.00
Recei vi ng Area	154	100.00	0.00	0.00	0.00
WIP	154	100.00	0.00	0.00	0.00
i n forgi ng	154	41.79	58.21	0.00	0.00
i n bl ank1	154	77.69	22.31	0.00	0.00
i n bl ank2	154	33.91	66.09	0.00	0.00
i n pi e25 1	154	53.43	46.57	0.00	0.00
i n pi e25 2	154	46.41	53.59	0.00	0.00
i n pi e25 3	154	49.39	50.61	0.00	0.00
i n Hyd	154	0.00	100.00	0.00	0.00
i n bend35	154	0.00	100.00	0.00	0.00
i n bend100	154	25.22	74.78	0.00	0.00

in cut100	154	62.86	37.14	0.00	0.00
in cut90 1	154	52.57	47.43	0.00	0.00
in cut90 2	154	77.64	22.36	0.00	0.00
in pie63 1	154	0.00	100.00	0.00	0.00
in pie63 2	154	49.47	50.53	0.00	0.00
in pie63 3	154	0.00	100.00	0.00	0.00
in Arm XC	154	0.68	99.32	0.00	0.00
in Rod XC	154	0.00	100.00	0.00	0.00
in Boss XC	154	0.00	100.00	0.00	0.00
in Shoe XC	154	0.00	100.00	0.00	0.00
in Arm H10	154	0.00	100.00	0.00	0.00
in Rod H10	154	0.00	100.00	0.00	0.00
in Boss H10	154	0.00	100.00	0.00	0.00
in Shoe H10	154	0.00	100.00	0.00	0.00
in Arm H00	154	49.09	50.91	0.00	0.00
in Rod H00	154	0.00	100.00	0.00	0.00
in Boss H00	154	0.00	100.00	0.00	0.00
in Shoe H00	154	0.00	100.00	0.00	0.00
in swi tch XC	154	0.00	100.00	0.00	0.00
in sprin g XC	154	0.00	100.00	0.00	0.00
in Pedal XC	154	0.13	99.87	0.00	0.00
in swi tch H10	154	0.00	100.00	0.00	0.00
in sprin g H10	154	0.00	100.00	0.00	0.00
in Pedal H10	154	7.96	92.04	0.00	0.00
in swi tch H00	154	0.00	100.00	0.00	0.00
in sprin g H00	154	0.00	100.00	0.00	0.00
in Pedal H00	154	49.81	50.19	0.00	0.00
in expand	154	15.40	84.60	0.00	0.00
out forgi ng	154	42.94	57.06	0.00	0.00
out blank1	154	78.13	21.87	0.00	0.00
out blank2	154	36.55	63.45	0.00	0.00
out pie25 1	154	0.90	99.10	0.00	0.00
out pie25 2	154	47.43	52.57	0.00	0.00
out pie25 3	154	50.35	49.65	0.00	0.00
out Hyd	154	2.99	97.01	0.00	0.00
out bend35	154	6.66	93.34	0.00	0.00
out bend100	154	26.86	73.14	0.00	0.00
out cut100	154	67.17	32.83	0.00	0.00
out pie63 1	154	2.98	97.02	0.00	0.00
out pie63 2	154	4.90	95.10	0.00	0.00
out pie63 3	154	6.60	93.40	0.00	0.00
out cut90 1	154	52.59	47.41	0.00	0.00
out cut90 2	154	81.78	18.22	0.00	0.00
out assy1 XC	154	34.72	65.28	0.00	0.00
out assy1 H10	154	3.49	96.51	0.00	0.00
out assy1 H00	154	50.68	49.32	0.00	0.00
out assy2 XC	154	3.46	96.54	0.00	0.00
out assy2 H10	154	7.98	92.02	0.00	0.00
out assy2 H00	154	50.67	49.33	0.00	0.00

out expand	154	17.55	82.45	0.00	0.00
Shi ppi ng XC	154	95.52	4.48	0.00	0.00
Shi ppi ng H10	154	94.21	5.79	0.00	0.00
Shi ppi ng H00	154	0.65	99.35	0.00	0.00

LOCATION STATES BY PERCENTAGE (Single Capacity/Tanks)

Locati on Name	Schedul ed Hours	% Operati on	% Setup	% Idle	% Wai ti ng	% Bl ocked	% Down
Ms Forging	154	58.23	0.00	41.77	0.00	0.00	0.00
Ms Blank1	154	22.32	0.00	77.68	0.00	0.00	0.00
Ms Cut90 1	154	31.77	0.00	51.09	17.14	0.00	0.00
Ms Blank2	154	57.64	0.00	33.89	8.47	0.00	0.00
Ms Bend100	154	50.44	0.00	23.19	26.37	0.00	0.00
Ms Cut100	154	33.95	0.00	61.72	4.33	0.00	0.00
Ms Cut90 2	154	18.84	0.00	77.02	4.14	0.00	0.00
Assy1 XC. 1	154	63.81	0.00	0.54	35.65	0.00	0.00
Assy1 XC. 2	154	63.82	0.00	0.56	35.62	0.00	0.00
Assy1 XC. 3	154	63.82	0.00	0.54	35.64	0.00	0.00
Assy1 XC	462	63.82	0.00	0.55	35.63	0.00	0.00
Assy1 H10. 1	154	100.00	0.00	0.00	0.00	0.00	0.00
Assy1 H10. 2	154	100.00	0.00	0.00	0.00	0.00	0.00
Assy1 H10. 3	154	100.00	0.00	0.00	0.00	0.00	0.00
Assy1 H10	462	100.00	0.00	0.00	0.00	0.00	0.00
Assy1 H00. 1	154	51.30	0.00	48.69	0.01	0.00	0.00
Assy1 H00. 2	154	51.26	0.00	48.74	0.00	0.00	0.00
Assy1 H00. 3	154	51.36	0.00	48.64	0.00	0.00	0.00
Assy1 H00	462	51.31	0.00	48.69	0.00	0.00	0.00
Assy2 XC	154	99.87	0.00	0.13	0.00	0.00	0.00
Assy2 H10	154	95.22	0.00	4.78	0.00	0.00	0.00
Assy2 H00	154	51.03	0.00	48.97	0.00	0.00	0.00
Ms Expand	154	85.31	0.00	14.69	0.00	0.00	0.00
Shi ppi ng	154	0.00	0.00	100.00	0.00	0.00	0.00

FAILED ARRIVALS

Enti ty Name	Locati on Name	Total Fai led
Boss	WIP	0
Brake shoe	Recei vi ng Area	0
Brake shoe	WIP	0
Arm XC	Recei vi ng Area	0
Arm XC	WIP	0
Arm XC	in cut90 1	0
Arm XC	in pi e63 1	0

Rod XC	Recei vi ng Area	0
Rod XC	WI P	0
Rod XC	i n pi e25 1	0
Swi tch XC	WI P	0
Spri ng XC	WI P	0
Pedal XC	i n expand	0
Arm H10	Recei vi ng Area	0
Arm H10	WI P	0
Arm H10	i n bend100	0
Arm H10	i n cut100	0
Arm H10	i n pi e63 3	0
Rod H10	Recei vi ng Area	0
Rod H10	WI P	0
Rod H10	i n pi e25 2	0
Rod H10	i n pi e25 3	0
Swi tch H10	WI P	0
Spri ng H10	WI P	0
Pedal H10	i n expand	0
Arm H00	Recei vi ng Area	0
Arm H00	WI P	0
Arm H00	i n bl ank2	0
Arm H00	i n cut90 2	0
Arm H00	i n pi e63 2	0
Rod H00	Recei vi ng Area	0
Rod H00	WI P	0
Rod H00	i n pi e25 2	0
Rod H00	i n pi e25 3	0
Swi tch H00	WI P	0
Spri ng H00	WI P	0
Pedal H00	i n expand	0
pengi ri man	Shi ppi ng	0

ENTITY ACTIVITY

Enti ty Name	Total Exi ts	Current Quantity In System	Average Mi nutes In System	Average Mi nutes In Move Logi c	Average Mi nutes Wai t For Res, etc.	Average Mi nutes In Operati on	Average Mi nutes Bl ocked
Boss	39221	64279	2797.05	0.17	0.00	0.00	2796.88
Brake shoe	39221	18779	1463.65	0.47	2.36	0.09	1460.70
Arm XC	0	20370	-	-	-	-	-
Rod XC	15000	20090	2854.18	0.49	9.93	0.31	2843.45
Swi tch XC	14966	19534	2740.73	0.28	0.00	0.00	2740.44
Spri ng XC	14966	19534	2740.73	0.28	0.00	0.00	2740.44
Pedal XC	15090	60	2965.45	0.60	38.66	2.92	2923.26
Box Arm XC	2578	50	0.10	0.10	0.00	0.00	0.00
Box Rod XC	1991	30	0.16	0.16	0.00	0.00	0.00

Box Swi tch XC	660	30	0.28	0.28	0.00	0.00	0.00
Box Spring XC	660	30	0.28	0.28	0.00	0.00	0.00
Box Boss	3300	150	0.17	0.17	0.00	0.00	0.00
Box Shoe	2210	50	0.24	0.24	0.00	0.00	0.00
Box Arm H10	3641	50	0.33	0.33	0.00	0.00	0.00
Box Rod H10	2691	0	0.10	0.10	0.00	0.00	0.00
Box Swi tch H10	660	30	0.24	0.24	0.00	0.00	0.00
Box Spring H10	660	30	0.24	0.24	0.00	0.00	0.00
Box Arm H00	1255	0	0.11	0.11	0.00	0.00	0.00
Box Rod H00	623	0	0.08	0.08	0.00	0.00	0.00
Box Swi tch H00	170	0	0.20	0.20	0.00	0.00	0.00
Box Spring H00	170	0	0.20	0.20	0.00	0.00	0.00
Arm H10	0	19094	-	-	-	-	-
Rod H10	16369	18981	2754.61	0.40	7.51	0.53	2746.16
Swi tch H10	16338	18162	2549.57	0.24	0.00	0.00	2549.32
Spring H10	16338	18162	2549.57	0.24	0.00	0.00	2549.32
Pedal H10	16410	76	2807.09	1.97	39.52	3.47	2762.11
Arm H00	0	581	-	-	-	-	-
Rod H00	7852	598	753.96	0.31	7.32	0.51	745.80
Swi tch H00	7814	686	827.26	0.20	0.00	0.00	827.06
Spring H00	7814	686	827.26	0.20	0.00	0.00	827.06
Pedal H00	3960	4009	4081.53	0.83	45.60	3.50	4031.58
Box Pedal XC	998	0	0.08	0.08	0.00	0.00	0.00
Box Pedal H10	1089	0	0.12	0.12	0.00	0.00	0.00
Box Pedal H00	521	0	0.12	0.12	0.00	0.00	0.00
Brake pedal XC	503	0	10.32	0.00	0.00	0.00	10.32
Brake pedal H10	547	0	10.35	0.12	0.00	0.00	10.22
Brake pedal H00	132	131	3299.11	0.12	0.00	0.00	3298.98
pengi ri man	22	0	0.00	0.00	0.00	0.00	0.00

ENTITY STATES BY PERCENTAGE

Enti ty Name	% In Move Logic	% Wait For Res, etc.	% In Operati on	% Blocked
Boss	0.01	0.00	0.00	99.99
Brake shoe	0.03	0.16	0.01	99.80
Arm XC	-	-	-	-
Rod XC	0.02	0.35	0.01	99.62
Swi tch XC	0.01	0.00	0.00	99.99
Spring XC	0.01	0.00	0.00	99.99
Pedal XC	0.02	1.30	0.10	98.58
Box Arm XC	100.00	0.00	0.00	0.00
Box Rod XC	100.00	0.00	0.00	0.00
Box Swi tch XC	100.00	0.00	0.00	0.00
Box Spring XC	100.00	0.00	0.00	0.00
Box Boss	100.00	0.00	0.00	0.00

Box Shoe	100.00	0.00	0.00	0.00
Box Arm H10	100.00	0.00	0.00	0.00
Box Rod H10	100.00	0.00	0.00	0.00
Box Swi tch H10	100.00	0.00	0.00	0.00
Box Spring H10	100.00	0.00	0.00	0.00
Box Arm H00	100.00	0.00	0.00	0.00
Box Rod H00	100.00	0.00	0.00	0.00
Box Swi tch H00	100.00	0.00	0.00	0.00
Box Spring H00	100.00	0.00	0.00	0.00
Arm H10	-	-	-	-
Rod H10	0.01	0.27	0.02	99.69
Swi tch H10	0.01	0.00	0.00	99.99
Spring H10	0.01	0.00	0.00	99.99
Pedal H10	0.07	1.41	0.12	98.40
Arm H00	-	-	-	-
Rod H00	0.04	0.97	0.07	98.92
Swi tch H00	0.02	0.00	0.00	99.98
Spring H00	0.02	0.00	0.00	99.98
Pedal H00	0.02	1.12	0.09	98.78
Box Pedal XC	100.00	0.00	0.00	0.00
Box Pedal H10	100.00	0.00	0.00	0.00
Box Pedal H00	100.00	0.00	0.00	0.00
Brake pedal XC	0.00	0.00	0.00	100.00
Brake pedal H10	1.20	0.00	0.00	98.80
Brake pedal H00	0.00	0.00	0.00	100.00
pengi ri man	-	-	-	-

VARI ABLES

Vari abl e Name	Total Changes	Average Mi nutes Per Change	Mi ni mum Val ue	Maxi mum Val ue	Current Val ue	Average Val ue
kekurangan XC	22	420.00	0	12	11	10.63
kekurangan H10	18	513.33	0	2	2	1.40
kekurangan H00	0	0.00	0	0	0	0
jml XC	547	16.89	-12	25	0	11.35
jml H10	587	15.74	-2	28	0	12.47
jml H00	285	32.42	0	137	131	84.19
status XC	0	0.00	0	0	0	0
ruleroute XC	1250	7.35	0	1	1	0.00
henti XC	756	12.16	0	1	1	0.37
status H10	0	0.00	0	0	0	0
ruleroute H10	1224	7.52	0	1	0	0.00
henti H10	1080	8.53	0	1	1	0.32
status H00	0	0.00	0	0	0	0
ruleroute H00	823	11.14	0	1	0	0.00
henti H00	763	12.05	0	1	0	0.16

jml pedal XC	29966	0.30	0	101	34	54.89
jml arm H10	32779	0.28	0	657	41	63.16
jml arm H00	15742	0.58	0	597	38	26.24
jml arm XC	30000	0.30	0	885	0	436.44
total kurang XC	22	420.00	0	245	245	115.81
total kurang H10	18	513.33	0	25	25	11.31
total kurang H00	0	0.00	0	0	0	0
hyd	48066	0.19	0	18567	17934	9560.79
in 63 1	29507	0.31	0	917	913	533.45
in 90 1	28800	0.31	0	120	0	8.26
in 35	70047	0.13	0	13252	10953	7501.6
in bend 100	44280	0.20	0	505	0	43.41
in 63 3	37907	0.24	0	6554	6553	2544.92
in cut 100	31500	0.29	0	89	0	8.56
in blank 2	15200	0.60	0	1500	40	321.38
in 63 2	14909	0.61	0	468	451	95.25
in 90 2	14580	0.63	0	89	0	6.30
in ex	78851	0.11	0	389	49	75.99
in pedal H10	32688	0.28	0	30	12	13.81
in pedal H00	15644	0.59	0	36	16	7.89

KOMENTAR DOSEN PENGUJI

Nama Mahasiswa : Limia Verlina
NRP : 0423072
Judul Tugas Akhir : Analisis Penerapan *Theory Of Constraint* Dalam
Meminimasi Inventory Melalui Studi Simulasi (Studi
Kasus di PT. Sinar Terang Logamjaya (STALLION))

Komentar-Komentar Dosen Penguji :

1. Konsep berfikir anda bagus
2. Kembangkan terus kemampuan anda
3. Tingkatan kemampuan berbahasa inggris
4. GBU
5. Rumus kenapa ada yang tidak ada di bab 2?
6. Skenario 5 buat apa? Seharusnya 4 skenario saja, kemudian usulin salah satu (yang terbaik)
7. Penjelasan penentuan constraint (untuk yang jumlah mesin bukan 1) → belum ada
8. Hal 5-24 → kenapa bukan skenario 2 yang terpilih? Kalau skenario 2 & 5 sama, kenapa throughput, output dan total kurangnya beda?
9. Alasan perusahaan menyimpan ± 600 unit? Karena usulan jauh banget. Apa perusahaan meu terima usulan? Jangan-jangan mereka punya alasan sendiri.
10. Tahap penentuan metode pemecahan masalah belum ada
11. Perumusan masalah no 1 tidak perlu karena sudah diketahui pada identifikasi masalah.
12. Informasi total kurang pada tabel 5.16 → bisa untuk usulan peningkatan kapasitas (penelitian lebih lanjut)

DATA PENULIS

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SDK 6 BPK Penabur Bandung
SLTPK 5 BPK Penabur Bandung
SMUK 3 BPK Penabur Bandung
Jurusan Teknik Industri, Universitas Kristen Maranatha
Bandung
Nilai Tugas Akhir : A
Tanggal USTA : 13 Juni 2008