

## DAFTAR PUSTAKA

1. Balas, Gary., Richard,Chiang., Andy,Packard., Michael, Safonov.*Robust Control Toolbox™ 3:Getting Started Guide*.
2. Balchen, J.G., dan Kenneth I.M., *Process Control*, Van Nostrand Reinhold Company, United States of America, 1988.
3. Doyle, J.C., dan Glover, K., *Robust and Optimal Control*, Prentice Hall, Upper Saddle River, NJ, 1995.
4. Lin, F. 2007. *Robust Control Design: An Optimal Control Approach*. England: John Wiley & Sons, Ltd.
5. Ogata, K., *Modern Control Engineering*, Fourth Edition, Prentice-Hall International, United States of America, 2002.
6. Petkov, & Konstantinov.2005. *Robust Control Design with MATLAB:LE-TEX* Jelonek, Schmidt&Vöckler GbR, Leipzig, Germany.
7. Sanchez-Pena, R. S. dan M. Sznaier. 1998. *Robust Systems Theory and Applications*. New York: John Wiley & Sons, Inc
8. Shariati, A., Taghirad, H.D., & Fatehi,A. 2004. *Decentralized Robust  $H_\infty$  Controller Design For A Half-Car Active Suspension System*.UK: University of Bath.
9. <http://abuhasanannn.wordpress.com/2010/07/14/cara-kerja-suspensi/>
10. [http://id.wikipedia.org/wiki/Hukum\\_Hooke](http://id.wikipedia.org/wiki/Hukum_Hooke)
11. <http://www.gurumuda.com/hukum-newton-2>
12. <http://www.otomotif.web.id/sistem-suspensi-a40.html>