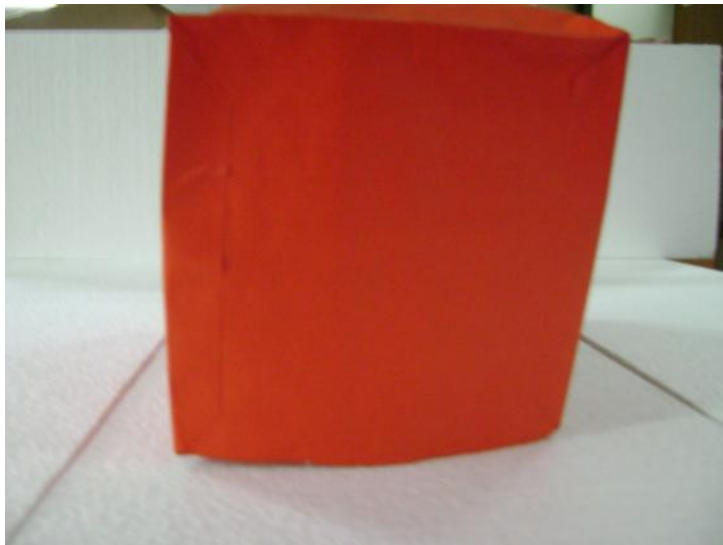


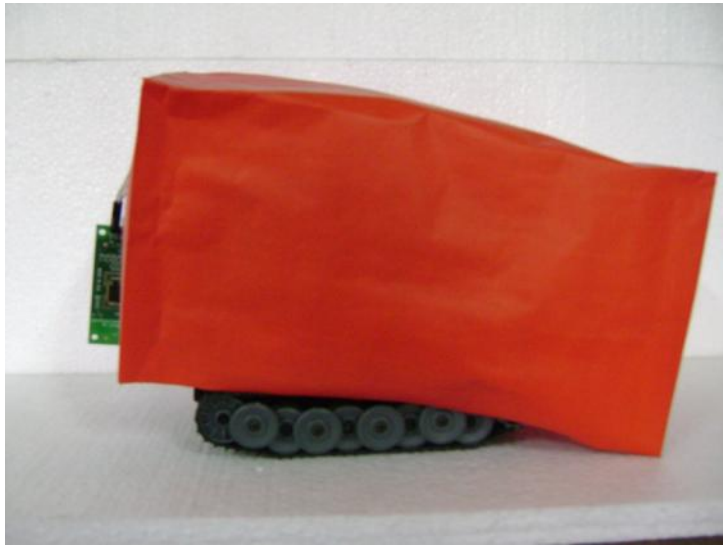
**LAMPIRAN A**  
**FOTO ROBOT MOBIL TANK**



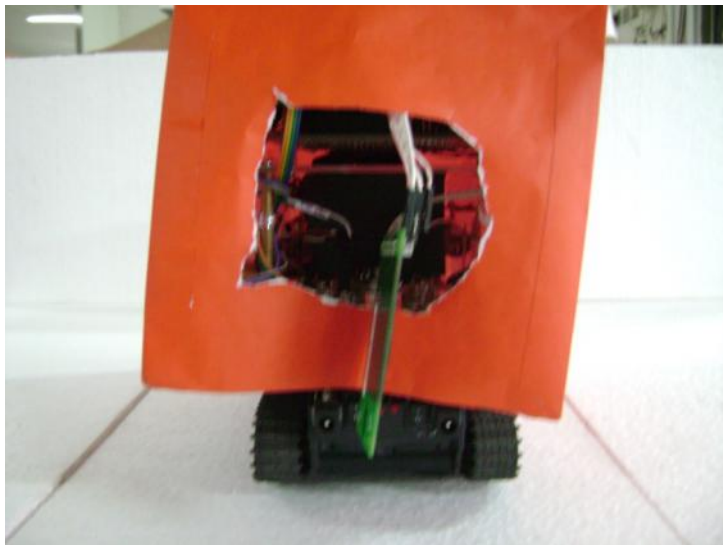
**Gambar A.1.** Foto Robot Mobil Dengan Penutup Dilihat Dari Atas



**Gambar A.2** Foto Robot Mobil Dengan Penutup Dilihat Dari depan



**Gambar A.3** Foto Robot Mobil Dengan Penutup Dilihat Dari samping



**Gambar A.4** Foto Robot Mobil Dengan Penutup Dilihat Dari Belakang

**LAMPIRAN B**  
**PROGRAM PADA PENGONTROL MIKRO**

```
/******
```

```
This program was produced by the  
CodeWizardAVR V1.25.3 Professional  
Automatic Program Generator  
© Copyright 1998-2007 Pavel Haiduc, HP InfoTech s.r.l.  
http://www.hpinfotech.com
```

```
Project :  
Version :  
Date : 7/23/2009  
Author : Lab Instrumentasi  
Company : UKM  
Comments:
```

```
Chip type : ATmega16  
Program type : Application  
Clock frequency : 11.059200 MHz  
Memory model : Small  
External SRAM size : 0  
Data Stack size : 256  
*****/
```

```
#include <mega16.h>
```

```
// Standard Input/Output functions  
#include <stdio.h>  
#include <delay.h>  
// Declare your global variables here  
void maju()  
{ PORTD.2=0;  
PORTD.3=1;  
PORTD.4=1;  
PORTD.5=1;  
PORTD.6=0;  
PORTD.7=1;  
  
}
```

```
void kiri()  
{ PORTD.2=0;  
PORTD.3=1;  
PORTD.4=1;  
PORTD.5=1;  
PORTD.6=1;  
PORTD.7=0;  
delay_ms(450);  
PORTD.4=0;  
PORTD.5=0;  
  
}
```

```
void kanan()  
{ PORTD.2=1;  
PORTD.3=0;  
PORTD.4=1;  
PORTD.5=1;  
PORTD.6=0;  
PORTD.7=1;  
delay_ms(450);
```

```

        PORTD.4=0;
        PORTD.5=0;
    }
void stop()
{
PORTD.4=0;
PORTD.5=0;
}
void main(void)
{char a;
// Declare your local variables here

// Input/Output Ports initialization
// Port A initialization
// Func7=In Func6=In Func5=In Func4=In Func3=In Func2=In Func1=In Func0=In
// State7=T State6=T State5=T State4=T State3=T State2=T State1=T State0=T
PORTA=0x00;
DDRA=0x3F;

// Port B initialization
// Func7=In Func6=In Func5=In Func4=In Func3=In Func2=In Func1=In Func0=In
// State7=T State6=T State5=T State4=T State3=T State2=T State1=T State0=T
PORTB=0x00;
DDRB=0x00;

// Port C initialization
// Func7=In Func6=In Func5=In Func4=In Func3=In Func2=In Func1=In Func0=In
// State7=T State6=T State5=T State4=T State3=T State2=T State1=T State0=T
PORTC=0x00;
DDRC=0x3F;

// Port D initialization
// Func7=Out Func6=Out Func5=Out Func4=Out Func3=Out Func2=Out Func1=In Func0=In
// State7=0 State6=0 State5=0 State4=0 State3=0 State2=0 State1=T State0=T
PORTD=0x00;
DDRD=0xFC;

// Timer/Counter 0 initialization
// Clock source: System Clock
// Clock value: Timer 0 Stopped
// Mode: Normal top=FFh
// OC0 output: Disconnected
TCCR0=0x00;
TCNT0=0x00;
OCR0=0x00;

// Timer/Counter 1 initialization
// Clock source: System Clock
// Clock value: Timer 1 Stopped
// Mode: Normal top=FFFFh
// OC1A output: Discon.
// OC1B output: Discon.
// Noise Canceler: Off
// Input Capture on Falling Edge
// Timer 1 Overflow Interrupt: Off
// Input Capture Interrupt: Off
// Compare A Match Interrupt: Off
// Compare B Match Interrupt: Off

```

```

TCCR1A=0x00;
TCCR1B=0x00;
TCNT1H=0x00;
TCNT1L=0x00;
ICR1H=0x00;
ICR1L=0x00;
OCR1AH=0x00;
OCR1AL=0x00;
OCR1BH=0x00;
OCR1BL=0x00;

// Timer/Counter 2 initialization
// Clock source: System Clock
// Clock value: Timer 2 Stopped
// Mode: Normal top=FFh
// OC2 output: Disconnected
ASSR=0x00;
TCCR2=0x00;
TCNT2=0x00;
OCR2=0x00;

// External Interrupt(s) initialization
// INT0: Off
// INT1: Off
// INT2: Off
MCUCR=0x00;
MCUCSR=0x00;

// Timer(s)/Counter(s) Interrupt(s) initialization
TIMSK=0x00;

// USART initialization
// Communication Parameters: 8 Data, 1 Stop, No Parity
// USART Receiver: On
// USART Transmitter: On
// USART Mode: Asynchronous
// USART Baud rate: 9600
UCSRA=0x00;
UCSRB=0x18;
UCSRC=0x86;
UBRRH=0x00;
UBRRL=0x47;

// Analog Comparator initialization
// Analog Comparator: Off
// Analog Comparator Input Capture by Timer/Counter 1: Off
ACSR=0x80;
SFIOR=0x00;

while (1)
{
    // Place your code here
    a=getchar();
    if (a=='w')
    {maju();}
    if (a=='q')
    {kiri();}
    if (a=='e')

```

```
{kanan();  
if(a=='s')  
{stop();}  
};  
}
```



**LAMPIRAN C**  
**PROGRAM PADA VISUAL C#**

```

using System.IO;
using System.Drawing;
using System.Collections;
using System.ComponentModel;
using System.Windows.Forms;
using System.Data;
using System.Drawing.Imaging;
using Mehroz;
using System.IO.Ports;
using System.Threading;

namespace MazeSolverDemo
{
    /// <summary>
    /// Summary description for MazeSolver
    /// Version 1.2
    /// Developed by: Syed Mehroz Alam
    /// Email: smehrozalam@yahoo.com
    /// URL: Programming Home "http://www.geocities.com/smehrozalam/"
    ///
    ///
    /// New in version 1.1
    ///      * Extended the program so that it can work on rectangular maze
    (previous version
    ///      worked for only square maze)
    ///
    /// New in version 1.2
    ///      * The class can now handle diagonal paths also
    /// </summary>
    public class frmMain : System.Windows.Forms.Form
    {
        Bitmap _image;
        Mehroz.MazeSolver m_Maze;
        MazeSolver.StringA stringA;
        MazeSolver.StringT stringT;
        int[,] m_iMaze;
        int m_iSize=20;
        int m_iRowDimensions=7;
        int m_iColDimensions=7;
        string RxString;

        private System.Windows.Forms.PictureBox pictureBox1;
        private System.Windows.Forms.Button cmdReset;
        private System.Windows.Forms.Button cmdExit;
        private System.Windows.Forms.Button button2;
        private System.Windows.Forms.OpenFileDialog OP;
        private System.Windows.Forms.Button button3;
        private System.Windows.Forms.Button button4;
        private SerialPort serialPort1;
        private TextBox Xbox;
        private Label label1;
    }
}

```

```

private Label label2;
private TextBox Ybox;
private Button Start;
private TextBox textBox1;
private Button Stop;
private TextBox xx;
private TextBox yy;
private Button run;
private TextBox posisi;
private TextBox aa;
private IContainer components;

public frmMain()
{
    //
    // Required for Windows Form Designer support
    //
    InitializeComponent();

    //
    // TODO: Add any constructor code after InitializeComponent call
    //
}

/// <summary>
/// Clean up any resources being used.
/// </summary>
protected override void Dispose( bool disposing )
{
    if( disposing )
    {
        if (components != null)
        {
            components.Dispose();
        }
    }
    base.Dispose( disposing );
}

#region Windows Form Designer generated code
/// <summary>
/// Required method for Designer support - do not modify
/// the contents of this method with the code editor.
/// </summary>
private void InitializeComponent()
{
    this.components = new System.ComponentModel.Container();
    this.pictureBox1 = new System.Windows.Forms.PictureBox();
    this.cmdReset = new System.Windows.Forms.Button();
    this.cmdExit = new System.Windows.Forms.Button();
    this.button2 = new System.Windows.Forms.Button();
    this.OP = new System.Windows.Forms.OpenFileDialog();
    this.button3 = new System.Windows.Forms.Button();
    this.button4 = new System.Windows.Forms.Button();
    this.serialPort1 = new System.IO.Ports.SerialPort(this.components);
}

```

```

this.Xbox = new System.Windows.Forms.TextBox();
this.label1 = new System.Windows.Forms.Label();
this.label2 = new System.Windows.Forms.Label();
this.Ybox = new System.Windows.Forms.TextBox();
this.Start = new System.Windows.Forms.Button();
this.textBox1 = new System.Windows.Forms.TextBox();
this.Stop = new System.Windows.Forms.Button();
this.xx = new System.Windows.Forms.TextBox();
this.yy = new System.Windows.Forms.TextBox();
this.run = new System.Windows.Forms.Button();
this.posisi = new System.Windows.Forms.TextBox();
this.aa = new System.Windows.Forms.TextBox();
((System.ComponentModel.ISupportInitialize)(this.pictureBox1)).BeginInit();
this.SuspendLayout();
//
// pictureBox1
//
this.pictureBox1.BorderStyle = System.Windows.Forms.BorderStyle.FixedSingle;
this.pictureBox1.Location = new System.Drawing.Point(24, 16);
this.pictureBox1.Name = "pictureBox1";
this.pictureBox1.Size = new System.Drawing.Size(184, 168);
this.pictureBox1.TabIndex = 0;
this.pictureBox1.TabStop = false;
this.pictureBox1.Paint += new
System.Windows.Forms.PaintEventHandler(this.pictureBox1_Paint);
//
// cmdReset
//
this.cmdReset.Location = new System.Drawing.Point(328, 136);
this.cmdReset.Name = "cmdReset";
this.cmdReset.Size = new System.Drawing.Size(104, 24);
this.cmdReset.TabIndex = 6;
this.cmdReset.Text = "&Reset Maze";
this.cmdReset.Click += new System.EventHandler(this.cmdReset_Click);
//
// cmdExit
//
this.cmdExit.Location = new System.Drawing.Point(328, 176);
this.cmdExit.Name = "cmdExit";
this.cmdExit.Size = new System.Drawing.Size(104, 24);
this.cmdExit.TabIndex = 8;
this.cmdExit.Text = "E&xit";
this.cmdExit.Click += new System.EventHandler(this.cmdExit_Click);
//
// button2
//
this.button2.Location = new System.Drawing.Point(328, 16);
this.button2.Name = "button2";
this.button2.Size = new System.Drawing.Size(104, 24);
this.button2.TabIndex = 11;
this.button2.Text = "Open";
this.button2.Click += new System.EventHandler(this.button2_Click);
//
// button3
//

```

```

this.button3.Location = new System.Drawing.Point(328, 96);
this.button3.Name = "button3";
this.button3.Size = new System.Drawing.Size(104, 23);
this.button3.TabIndex = 12;
this.button3.Text = "Solve";
this.button3.Click += new System.EventHandler(this.button3_Click);
//
// button4
//
this.button4.Location = new System.Drawing.Point(328, 56);
this.button4.Name = "button4";
this.button4.Size = new System.Drawing.Size(104, 23);
this.button4.TabIndex = 15;
this.button4.Text = "Wall";
this.button4.Click += new System.EventHandler(this.button4_Click);
//
// serialPort1
//
this.serialPort1.DataReceived += new
System.IO.Ports.SerialDataReceivedEventHandler(this.serialPort1_DataReceived);
//
// Xbox
//
this.Xbox.Location = new System.Drawing.Point(232, 255);
this.Xbox.Name = "Xbox";
this.Xbox.Size = new System.Drawing.Size(40, 20);
this.Xbox.TabIndex = 18;
//
// label1
//
this.label1.AutoSize = true;
this.label1.Location = new System.Drawing.Point(244, 239);
this.label1.Name = "label1";
this.label1.Size = new System.Drawing.Size(14, 13);
this.label1.TabIndex = 19;
this.label1.Text = "X";
//
// label2
//
this.label2.AutoSize = true;
this.label2.Location = new System.Drawing.Point(325, 239);
this.label2.Name = "label2";
this.label2.Size = new System.Drawing.Size(14, 13);
this.label2.TabIndex = 20;
this.label2.Text = "Y";
//
// Ybox
//
this.Ybox.Location = new System.Drawing.Point(310, 255);
this.Ybox.Name = "Ybox";
this.Ybox.Size = new System.Drawing.Size(41, 20);
this.Ybox.TabIndex = 21;
//
// Start
//

```

```

this.Start.Location = new System.Drawing.Point(232, 294);
this.Start.Name = "Start";
this.Start.Size = new System.Drawing.Size(75, 23);
this.Start.TabIndex = 22;
this.Start.Text = "Start";
this.Start.UseVisualStyleBackColor = true;
this.Start.Click += new System.EventHandler(this.button1_Click);
//
// textBox1
//
this.textBox1.Location = new System.Drawing.Point(232, 216);
this.textBox1.Name = "textBox1";
this.textBox1.Size = new System.Drawing.Size(100, 20);
this.textBox1.TabIndex = 23;
this.textBox1.KeyPress += new
System.Windows.Forms.KeyPressEventHandler(this.textBox1_KeyPress);
//
// Stop
//
this.Stop.Location = new System.Drawing.Point(348, 294);
this.Stop.Name = "Stop";
this.Stop.Size = new System.Drawing.Size(75, 23);
this.Stop.TabIndex = 24;
this.Stop.Text = "Stop";
this.Stop.UseVisualStyleBackColor = true;
this.Stop.Click += new System.EventHandler(this.Stop_Click);
//
// xx
//
this.xx.Location = new System.Drawing.Point(236, 334);
this.xx.Name = "xx";
this.xx.Size = new System.Drawing.Size(55, 20);
this.xx.TabIndex = 25;
//
// yy
//
this.yy.Location = new System.Drawing.Point(310, 334);
this.yy.Name = "yy";
this.yy.Size = new System.Drawing.Size(51, 20);
this.yy.TabIndex = 26;
//
// run
//
this.run.Location = new System.Drawing.Point(74, 255);
this.run.Name = "run";
this.run.Size = new System.Drawing.Size(75, 23);
this.run.TabIndex = 27;
this.run.Text = "run";
this.run.UseVisualStyleBackColor = true;
this.run.Click += new System.EventHandler(this.run_Click);
//
// posisi
//
this.posisi.Location = new System.Drawing.Point(63, 216);
this.posisi.Name = "posisi";

```

```

this.posisi.Size = new System.Drawing.Size(100, 20);
this.posisi.TabIndex = 28;
//
// aa
//
this.aa.Location = new System.Drawing.Point(63, 297);
this.aa.Name = "aa";
this.aa.Size = new System.Drawing.Size(100, 20);
this.aa.TabIndex = 30;
//
// frmMain
//
this.AutoScaleBaseSize = new System.Drawing.Size(5, 13);
this.ClientSize = new System.Drawing.Size(472, 382);
this.Controls.Add(this.aa);
this.Controls.Add(this.posisi);
this.Controls.Add(this.run);
this.Controls.Add(this.yy);
this.Controls.Add(this.xx);
this.Controls.Add(this.Stop);
this.Controls.Add(this.textBox1);
this.Controls.Add(this.Start);
this.Controls.Add(this.Ybox);
this.Controls.Add(this.label2);
this.Controls.Add(this.label1);
this.Controls.Add(this.Xbox);
this.Controls.Add(this.button4);
this.Controls.Add(this.button3);
this.Controls.Add(this.button2);
this.Controls.Add(this.cmdExit);
this.Controls.Add(this.cmdReset);
this.Controls.Add(this.pictureBox1);
this.Name = "frmMain";
this.Text = "Maze Solver by Syed Mehroz Alam";
this.Load += new System.EventHandler(this.Form1_Load);
this.FormClosing += new
System.Windows.Forms.FormClosingEventHandler(this.frmMain_FormClosing);
((System.ComponentModel.ISupportInitialize)(this.pictureBox1)).EndInit();
this.ResumeLayout(false);
this.PerformLayout();

}
#endregion

/// <summary>
/// The main entry point for the application.
/// </summary>
[STAThread]
static void Main()
{
    try
    {
        Application.Run(new frmMain());
    }
    catch(Exception exp)

```

```

        {
            System.Windows.Forms.MessageBox.Show("An unhandled
exception '"+exp.Message+"' has occurred. \nPlease tell me at smehrozalam@yahoo.com so that I
can fix this bug. Thank you", "Error");
        }
    }

    private void Form1_Load(object sender, System.EventArgs e)
    {
        m_Maze = new Mehroz.MazeSolver(m_iRowDimensions,
m_iColDimensions);
        this.pictureBox1.Size=new
System.Drawing.Size(m_iColDimensions*m_iSize+3, m_iRowDimensions*m_iSize+3);
        m_iMaze=m_Maze.GetMaze;
    }

    private void pictureBox1_Paint(object sender,
System.Windows.Forms.PaintEventArgs e)
    {
        Graphics myGraphics = e.Graphics;
        for (int i=0;i<m_iRowDimensions;i++)
            for (int j=0;j<m_iColDimensions;j++)
            {
                // print grids
                myGraphics.DrawRectangle(new Pen(Color.Black) , j*m_iSize, i*m_iSize,
m_iSize, m_iSize);

                // print walls
                if ( m_iMaze[i,j]==1 )
                    myGraphics.FillRectangle(new
SolidBrush(Color.DarkGray) , j*m_iSize+1, i*m_iSize+1, m_iSize-1, m_iSize-1);
                //print path
                if ( m_iMaze[i,j]==100 )
                    myGraphics.FillRectangle(new
SolidBrush(Color.Cyan) , j*m_iSize+1, i*m_iSize+1, m_iSize-1, m_iSize-1);
                if (m_iMaze[i, j] == 10)
                    myGraphics.FillRectangle(new SolidBrush(Color.Red), j * m_iSize + 1, i *
m_iSize + 1, m_iSize - 1, m_iSize - 1);
            }
    }

    private void cmdReset_Click(object sender, System.EventArgs e)
    {
        m_Maze = new Mehroz.MazeSolver(m_iRowDimensions,
m_iColDimensions);
        m_iMaze=m_Maze.GetMaze;
        this.Refresh();
    }

    private void cmdExit_Click(object sender, System.EventArgs e)
    {
        this.Close();
    }

```



```

private void button2_Click(object sender, System.EventArgs e)
{
    OP.InitialDirectory="C:.";
    OP.Title="insert";
    OP.FileName="";
    OP.ShowDialog();
    //pictureBox2.Visible=true;
    //increase contrast
    _image=(Bitmap)Image.FromFile(OP.FileName,true);
    Image oldImage=this.pictureBox1.Image;
    Bitmap bm=new Bitmap(this._image.Width, this._image.Height);
    Graphics g=Graphics.FromImage(bm);
    ImageAttributes ia=new ImageAttributes();
    ColorMatrix cm=new ColorMatrix(new float[][]{ new
float[] {2f,0f,0f,0f,0f},

                                new float[] {0f,2f,0f,0f,0f},

                                new float[] {0f,0f,2f,0f,0f},

                                new float[] {0f,0f,0f,2f,0f},

                                new float[] {0.001f,0.001f,0.001f,0f,1f} });
    ia.SetColorMatrix(cm);
    g.DrawImage(_image,new
Rectangle(0,0,_image.Width,_image.Height),0,0,_image.Width,_image.Height,GraphicsUnit.Pixel
,ia);

    g.Dispose();
    ia.Dispose();
    this.pictureBox1.Image=bm;
    if(oldImage!=null)
        oldImage.Dispose();
}

private void button3_Click(object sender, System.EventArgs e)
{
    int[,] iSolvedMaze=m_Maze.FindPath(6,1, 1,6);
    if (iSolvedMaze!=null)
    {
        m_iMaze=iSolvedMaze;
    }

    this.Refresh();
}

private void pictureBox2_Click(object sender, System.EventArgs e)
{
}

private void button4_Click(object sender, System.EventArgs e)
{
    m_iMaze=m_Maze.GetMaze;
    for(int i=0;i<m_iRowDimensions;i++)

```

```

        {
            for (int j=0;j<m_iColDimensions;j++)
            {
                int wall=0;
                for(int a=0;a<m_iSize;a++)
                {
                    for(int b=0;b<m_iSize;b++)
                    {
                        string c = ((pictureBox1.Image as
Bitmap).GetPixel(a+m_iSize*j,b+m_iSize*i) ).ToString();
                        if (c=="Color [A=255, R=255,
G=255, B=255]")
                            {wall ++;}
                    }
                    if (wall>=15)
                        {m_iMaze[i,j]=1;}
                }
            }
            this.Refresh();
        }

public void maju()
{
    SerialPort port = new SerialPort("Com14", 9600, Parity.None, 8, StopBits.One);
    port.Open();
    port.Write("w");
    port.Close();
}
public void kanan()
{
    SerialPort port = new SerialPort("Com14", 9600, Parity.None, 8, StopBits.One);
    port.Open();
    port.Write("e");
    port.Close();
}
public void kiri()
{
    SerialPort port = new SerialPort("Com14", 9600, Parity.None, 8, StopBits.One);
    port.Open();
    port.Write("q");
    port.Close();
}
public void stop()
{
    SerialPort port = new SerialPort("Com14", 9600, Parity.None, 8, StopBits.One);
    port.Open();
    port.Write("s");
    port.Close();
}

private void button1_Click(object sender, EventArgs e)
{

```

```

serialPort1.PortName = "COM1";
serialPort1.BaudRate = 115200;

serialPort1.Open();
if (serialPort1.IsOpen)
{
    Start.Enabled = false;
    Stop.Enabled = true;
    textBox1.ReadOnly = false;
}
}

private void serialPort1_DataReceived(object sender, SerialDataReceivedEventArgs e)
{
    RxString = serialPort1.ReadExisting();
    this.Invoke(new EventHandler(DisplayText));
}

private void frmMain_FormClosing(object sender, FormClosingEventArgs e)
{
    if (serialPort1.IsOpen) serialPort1.Close();
}

private void textBox1_KeyPress(object sender, KeyPressEventArgs e)
{
    // If the port is closed, don't try to send a character.

    if (!serialPort1.IsOpen) return;

    // If the port is Open, declare a char[] array with one element.
    char[] buff = new char[1];

    // Load element 0 with the key character.

    buff[0] = e.KeyChar;

    // Send the one character buffer.
    serialPort1.Write(buff, 0, 1);

    // Set the KeyPress event as handled so the character won't
    // display locally. If you want it to display, omit the next line.
    e.Handled = true;
}

private void DisplayText(object sender, EventArgs e)
{
    string l = char.ConvertFromUtf32(13);
    textBox1.Text = "";
    textBox1.AppendText(RxString);
    stringT = new MazeSolver.StringT(RxString);
    stringA = new MazeSolver.StringA(RxString);
}

```

```

Ybox.Text = stringA.nextElement();
Xbox.Text = stringT.nextElement();
string c = Xbox.Text;
string d = Convert.ToString(Ybox.Text);
string i, j;
if (c == "8" || c == "9" || c == "7" || c == "10" || c == "6" || c == "11" || c == "5")
{ i = "0"; }
else if (c == "18" || c == "19" || c == "17" || c == "20" || c == "16" || c == "21" || c == "15")
{ i = "1"; }
else if (c == "28" || c == "29" || c == "27" || c == "30" || c == "26" || c == "31" || c == "25")
{ i = "2"; }
else if (c == "38" || c == "39" || c == "37" || c == "40" || c == "36" || c == "41" || c == "35")
{ i = "3"; }
else if (c == "48" || c == "49" || c == "47" || c == "50" || c == "46" || c == "51" || c == "45")
{ i = "4"; }
else if (c == "58" || c == "59" || c == "57" || c == "60" || c == "56" || c == "61" || c == "55")
{ i = "5"; }
else if (c == "68" || c == "69" || c == "67" || c == "70" || c == "66" || c == "71" || c == "65")
{ i = "6"; }
else { i = " "; };

if (d == "8" + 1 || d == "7" + 1 || d == "9" + 1 || d == "10" + 1 || d == "6" + 1 || d == "5" + 1 || d
== "11" + 1 || d == "4" + 1 || d == "12" + 1 || d == "3" + 1 || d == "13" + 1 || d == "2" + 1 || d == "14" +
1 || d == "1" + 1 || d == "15" + 1)
{ j = "0"; }
else if (d == "28" + 1 || d == "27" + 1 || d == "29" + 1 || d == "30" + 1 || d == "26" + 1 || d ==
"25" + 1 || d == "31" + 1 || d == "24" + 1 || d == "32" + 1 || d == "23" + 1 || d == "33" + 1 || d == "22"
+ 1 || d == "34" + 1 || d == "21" + 1 || d == "35" + 1)
{ j = "1"; }
else if (d == "48" + 1 || d == "47" + 1 || d == "49" + 1 || d == "50" + 1 || d == "46" + 1 || d ==
"45" + 1 || d == "51" + 1 || d == "44" + 1 || d == "52" + 1 || d == "43" + 1 || d == "53" + 1 || d == "42"
+ 1 || d == "54" + 1 || d == "41" + 1 || d == "55" + 1)
{ j = "2"; }
else if (d == "68" + 1 || d == "67" + 1 || d == "69" + 1 || d == "70" + 1 || d == "66" + 1 || d ==
"65" + 1 || d == "71" + 1 || d == "64" + 1 || d == "72" + 1 || d == "63" + 1 || d == "73" + 1 || d == "6"
+ 1 || d == "74" + 1 || d == "61" + 1 || d == "75" + 1)
{ j = "3"; }
else if (d == "88" + 1 || d == "87" + 1 || d == "89" + 1 || d == "90" + 1 || d == "86" + 1 || d ==
"85" + 1 || d == "91" + 1 || d == "84" + 1 || d == "92" + 1 || d == "83" + 1 || d == "93" + 1 || d == "82"
+ 1 || d == "94" + 1 || d == "81" + 1 || d == "95" + 1)
{ j = "4"; }
else if (d == "108" + 1 || d == "107" + 1 || d == "109" + 1 || d == "110" + 1 || d == "106" + 1 ||
d == "105" + 1 || d == "111" + 1 || d == "104" + 1 || d == "112" + 1 || d == "103" + 1 || d == "113" + 1
|| d == "102" + 1 || d == "114" + 1 || d == "101" + 1 || d == "115" + 1)
{ j = "5"; }
else if (d == "128" + 1 || d == "127" + 1 || d == "129" + 1 || d == "130" + 1 || d == "126" + 1 ||
d == "125" + 1 || d == "131" + 1 || d == "124" + 1 || d == "132" + 1 || d == "123" + 1 || d == "133" + 1
|| d == "122" + 1 || d == "134" + 1 || d == "121" + 1 || d == "135" + 1)
{ j = "6"; }
else { j = " "; };
yy.Text = j;
xx.Text = i;

```

```

}

private void Stop_Click(object sender, EventArgs e)
{
    if (serialPort1.IsOpen)
    {
        serialPort1.Close();
        Start.Enabled = true;
        Stop.Enabled = false;
        textBox1.ReadOnly = true;
    }
}

private void run_Click(object sender, EventArgs e)
{
    string a = yy.Text; string b = xx.Text;

    if (a == "1" || a == "2" || a == "3" || a == "4" || a == "5" || a == "6" || a == "0" )
    if (b == "1" || b == "2" || b == "3" || b == "4" || b == "5" || b == "6" || b == "0")
    {
        int j = Convert.ToInt32(b);
        int i = Convert.ToInt32(a);
        if (i == 1 && j == 6)
        { posisi.Text = "selesai"; }
        else if (m_iMaze[i - 1, j] == 100 && posisi.Text == "1")
        {
            maju();
            Thread.Sleep(1000);
            stop();
            aa.Text = "maju";
        }
        else if (m_iMaze[i, j + 1] == 100 && posisi.Text == "1")
        {
            kanan();
            aa.Text = "kanan";
            posisi.Text = "2";
        }
        else if (m_iMaze[i, j - 1] == 100 && posisi.Text == "1")
        {
            kiri();
            aa.Text = "kiri";
            posisi.Text = "4";
        }
        else if (m_iMaze[i, j + 1] == 100 && posisi.Text == "2")
        {
            maju();
            Thread.Sleep(1000);
            stop();
            aa.Text = "maju";
        }
        else if (m_iMaze[i + 1, j] == 100 && posisi.Text == "2")
        {
            kanan();
            aa.Text = "kanan";
            posisi.Text = "3";
        }
    }
}

```

```

    }
    else if (m_iMaze[i - 1, j] == 100 && posisi.Text == "2")
    {
        kiri();
        aa.Text = "kiri";
        posisi.Text = "1";
    }
    else if (m_iMaze[i + 1, j] == 100 && posisi.Text == "3")
    {
        maju();
        Thread.Sleep(1000);
        stop();
        aa.Text = "maju";
    }
    else if (m_iMaze[i, j - 1] == 100 && posisi.Text == "3")
    {
        kanan();
        aa.Text = "kanan";
        posisi.Text = "4";
    }
    else if (m_iMaze[i, j + 1] == 100 && posisi.Text == "3")
    {
        kiri();
        aa.Text = "kiri";
        posisi.Text = "2";
    }
    else if (m_iMaze[i, j - 1] == 100 && posisi.Text == "4")
    {
        maju();
        Thread.Sleep(1000);
        stop();
        aa.Text = "maju";
    }
    else if (m_iMaze[i + 1, j] == 100 && posisi.Text == "4")
    {
        kanan();
        aa.Text = "kanan";
        posisi.Text = "1";
    }
    else if (m_iMaze[i - 1, j] == 100 && posisi.Text == "4")
    {
        kiri();
        aa.Text = "kiri";
        posisi.Text = "3";
    }
}

}

}

```

```

    }
}

MazeSolver.cs
using System;
using System.Threading;
namespace Mehroz
{
    /// <summary>
    /// Summary description for MazeSolver.
    /// Class name: MazeSolver
    /// Developed by: Syed Mehroz Alam
    /// Email: smehrozalam@yahoo.com
    /// URL: Programming Home "http://www.geocities.com/smehrozalam/"
    ///
    /// Constructors:
    ///     ( int[,] ): takes 2D integer array
    ///     ( int Rows, int Cols )      initializes the dimensions, indexers may be used
    ///                                     to set individual elements'
values
    ///
    /// Properties:
    ///     Rows: returns the no. of rows in the current maze
    ///     Cols: returns the no. of columns in the current maze
    ///     Maze: returns the current maze as a 2D array
    ///     PathCharacter: to get/set the value of path tracing character
    ///     AllowDiagonal: whether diagonal paths are allowed
    ///
    /// Indexers:
    ///     [i,j] = used to set/get elements of maze
    ///
    /// Public Methods (Description is given with respective methods' definitions)
    ///     int[,] FindPath(int iFromY, int iFromX, int iToY, int iToX)
    ///
    /// Private Methods
    ///     void GetNodeContents(int[,] iMaze, int iNodeNo)
    ///     void ChangeNodeContents(int[,] iMaze, int iNodeNo, int iNewValue)
    ///     int[,] Search(int iBeginningNode, int iEndingNode)
    ///
    /// </summary>
    delegate void MazeChangedHandler(int iChanged, int jChanged);
    class MazeSolver
    {
        /// <summary>
        /// Class attributes/members
        /// </summary>
        int[,] m_iMaze;
        int m_iRows;
        int m_iCols;
        int iPath=100;
        bool diagonal=false;
        public event MazeChangedHandler OnMazeChangedEvent;

        /// <summary>
        /// Constructor 1: takes a 2D integer array

```

```

/// </summary>
public MazeSolver(int[,] iMaze)
{
    m_iMaze=iMaze;
    m_iRows=iMaze.GetLength(0);
    m_iCols=iMaze.GetLength(1);
}

/// <summary>
/// Constructor 2: initializes the dimensions of maze,
/// later, indexers may be used to set individual elements' values
/// </summary>
public MazeSolver(int iRows, int iCols)
{
    m_iMaze=new int[iRows, iCols];
    m_iRows=iRows;
    m_iCols=iCols;
}

/// <summary>
/// Properites:
/// </summary>
public int Rows
{
    get { return m_iRows; }
}

public int Cols
{
    get { return m_iCols; }
}
public int[,] GetMaze
{
    get { return m_iMaze; }
}
public int PathCharacter
{
    get { return iPath; }
    set
    {
        if (value==0)
            throw new Exception("Invalid path character
specified");
        else
            iPath=value;
    }
}

/// <summary>
/// Indexer
/// </summary>
public int this[int iRow, int iCol]
{
    get { return m_iMaze[iRow,iCol]; }
}

```



```

        set
        {
            m_iMaze[iRow,iCol]=value;
            if (this.OnMazeChangedEvent!=null) // trigger event
                this.OnMazeChangedEvent(iRow, iCol);
        }
    }

    /// <summary>
    /// The function is used to get the contents of a given node in a given maze,
    /// specified by its node no.
    /// </summary>
    private int GetNodeContents(int[,] iMaze, int iNodeNo)
    {
        int iCols=iMaze.GetLength(1);
        return iMaze[iNodeNo/iCols,iNodeNo-iNodeNo/iCols*iCols];
    }

    /// <summary>
    /// The function is used to change the contents of a given node in a given maze,
    /// specified by its node no.
    /// </summary>
    private void ChangeNodeContents(int[,] iMaze, int iNodeNo, int iNewValue)
    {
        int iCols=iMaze.GetLength(1);
        iMaze[iNodeNo/iCols,iNodeNo-iNodeNo/iCols*iCols]=iNewValue;
    }

    /// <summary>
    /// This public function finds the shortest path between two points
    /// in the maze and return the solution as an array with the path traced
    /// by "iPath" (can be changed using property "PathCharacter")
    /// if no path exists, the function returns null
    /// </summary>
    public int[,] FindPath(int iFromY, int iFromX, int iToY, int iToX)
    {
        int iBeginningNode = iFromY*this.Cols + iFromX;
        int iEndingNode = iToY*this.Cols + iToX;
        return ( Search(iBeginningNode, iEndingNode) );
    }

    /// <summary>
    /// Internal function for that finds the shortest path using a technique
    /// similar to breadth-first search.
    /// It assigns a node no. to each node(2D array element) and applies the
    algorithm
    /// </summary>
    private enum Status
    {
        Ready, Waiting, Processed
    }
    private int[,] Search(int iStart, int iStop)
    {
        const int empty=0;

        int iRows=m_iRows;

```

```

int iCols=m_iCols;
int iMax=iRows*iCols;
int[] Queue=new int[iMax];
int[] Origin=new int[iMax];
int iFront=0, iRear=0;

//check if starting and ending points are valid (open)
if ( GetNodeContents(m_iMaze, iStart)!=empty ||
GetNodeContents(m_iMaze, iStop)!=empty )
{
    return null;
}

//create dummy array for storing status
int[,] iMazeStatus=new int[iRows,iCols];
//initially all nodes are ready
for(int i=0;i<iRows;i++)
    for(int j=0;j<iCols;j++)
        iMazeStatus[i,j]=(int)Status.Ready;

//add starting node to Q
Queue[iRear]=iStart;
Origin[iRear]=-1;
iRear++;
int iCurrent, iLeft, iRight, iTop, iDown, iRightUp, iRightDown,
iLeftUp, iLeftDown;

while(iFront!=iRear)    // while Q not empty
{
    if (Queue[iFront]==iStop)    // maze is solved
        break;

    iCurrent=Queue[iFront];

    iLeft=iCurrent-1;
    if (iLeft>=0 && iLeft/iCols==iCurrent/iCols)    //if left
node exists
        if ( GetNodeContents(m_iMaze, iLeft)==empty )
            //if left node is open(a path exists)
            if (GetNodeContents(iMazeStatus, iLeft) ==
(int)Status.Ready)    //if left node is ready
                {
                    Queue[iRear]=iLeft; //add to Q
                    Origin[iRear]=iCurrent;
                    ChangeNodeContents(iMazeStatus,
iLeft, (int)Status.Waiting); //change status to waiting
                    iRear++;
                }

    iRight=iCurrent+1;
    if (iRight<iMax && iRight/iCols==iCurrent/iCols)    //if right
node exists
        if ( GetNodeContents(m_iMaze, iRight)==empty )
            //if right node is open(a path exists)
            if (GetNodeContents(iMazeStatus, iRight)
== (int)Status.Ready)    //if right node is ready

```

```

        {
            Queue[iRear]=iRight; //add to Q
            Origin[iRear]=iCurrent;
            ChangeNodeContents(iMazeStatus,
iRight, (int)Status.Waiting); //change status to waiting
            iRear++;
        }

        iTop=iCurrent-iCols;
        if (iTop>=0) //if top node exists
            if ( GetNodeContents(m_iMaze, iTop)==empty )
                //if top node is open(a path exists)
                if (GetNodeContents(iMazeStatus, iTop) ==
(int)Status.Ready) //if top node is ready
                    {
                        Queue[iRear]=iTop; //add to Q
                        Origin[iRear]=iCurrent;
                        ChangeNodeContents(iMazeStatus,
iTop, (int)Status.Waiting ); //change status to waiting
                        iRear++;
                    }

                iDown=iCurrent+iCols;
                if (iDown<iMax ) //if bottom node exists
                    if ( GetNodeContents(m_iMaze, iDown)==empty )
                        //if bottom node is open(a path exists)
                        if (GetNodeContents(iMazeStatus, iDown)
== (int)Status.Ready) //if bottom node is ready
                            {
                                Queue[iRear]=iDown; //add to Q
                                Origin[iRear]=iCurrent;
                                ChangeNodeContents(iMazeStatus,
iDown, (int)Status.Waiting); //change status to waiting
                                iRear++;
                            }

                        //change status of current node to processed
                        ChangeNodeContents(iMazeStatus, iCurrent,
(int)Status.Processed);

                        iFront++;
                    }

                //create an array(maze) for solution
                int[,] iMazeSolved=new int[iRows,iCols];
                for(int i=0;i<iRows;i++)
                    for(int j=0;j<iCols;j++)
                        iMazeSolved[i,j]=m_iMaze[i,j];

                //make a path in the Solved Maze
                iCurrent=iStop;
                ChangeNodeContents(iMazeSolved, iCurrent, iPath);
                for(int i=iFront; i>=0; i--)

```

```

        {
            if (Queue[i]==iCurrent)
            {
                iCurrent=Origin[i];
                if (iCurrent==-1) // maze is solved
                    return ( iMazeSolved );
                ChangeNodeContents(iMazeSolved, iCurrent, iPath);
            }
        }
        //no path exists
        return null;
    }
}
}

```

---

```

StringA.cs
using System;
using System.Collections.Generic;
using System.Text;

namespace MazeSolver
{
    public class StringA
    {
        private string data, delimiter;
        private string[] token;
        private int index;

        public StringA(string dataLine)
        { init(dataLine, " "); }
        private void init(String dataLine, string delim)
        {
            delimiter = delim;
            data = dataLine;
            token = data.Split(delimiter.ToCharArray());
            index = 2;
        }
        public StringA(string dataLine, string delim)
        { init(dataLine, delim); }
        public string nextElement()
        {
            if (index < token.Length)
                return token[index++];
            else
                return "";
        }
    }
}

```

---

```

StringT.cs
using System;
using System.Collections.Generic;

```

```

using System.Text;

namespace MazeSolver
{
    public class StringT
    {
        private string data, delimiter;
        private string[] token;
        private int index;

        public StringT(string dataLine)
        {
            init(dataLine, " ");
        }
        private void init(String dataLine, string delim)
        {
            delimiter = delim;
            data = dataLine;
            token = data.Split(delimiter.ToCharArray());
            index = 1;
        }
        public StringT(string dataLine, string delim)
        { init(dataLine, delim); }

        public string nextElement()
        {
            if (index < token.Length)
                return token[index++];
            else
                return "";
        }
        //
        // TODO: Add constructor logic here
        //
    }
}

```